
Routing in Wireless D2D Networks

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D2D Networks

- Nodes are computing and communication devices, e.g laptops, PDAs, mobile phones, even sensors
- Nodes organize and maintain the network by themselves
- A node is both a host and a router
- IP is used at the network layer
- First and foremost issue: **routing**

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Problems with Routing

1. Self-organizing networks

- Need for distributed algorithms

2. Topology changes dynamically

- Mobile nodes (joining in or leaving)
- Unannounced loss of network connectivity due to the time-varying channel nature

3. Link failure / repair

- Network partitions
 - Loop formation during temporary node failures
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Problems with Routing

4. Asymmetric links: links may be unidirectional

5. Limited bandwidth

- Protocols using flooding create high traffic and control overhead

6. Different performance criteria

- Number of hops (delay)
 - Available Bandwidth
 - Route stability despite mobility
 - Energy consumption
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Remarks/Assumptions

1. Find/maintain a route provided it exists
 - Another problem is to ensure that a route exists, e.g., through power control [Ramanathan'00,Wattwnhofer'00]
2. Assume that nodes are willing to cooperate

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Routing Protocols for D2D

- **Topology based routing**

- Proactive approach, e.g., DSDV, OLSR
- Reactive approach, e.g., DSR, AODV
- Hybrid approach, e.g., Cluster, ZRP

- **Position based routing**

- Location Services: e.g., DREAM, Quorum-based, GLS, Home zone etc.
- Forwarding Strategy: e.g., Greedy, GPSR, RDF, Hierarchical

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The Proactive Approach

- Attempts to build and maintain consistent, up-to-date routing information from each node to every other node in the network, BEFORE a route is needed.
 - Respond to changes by propagating updates throughout the network
 - Good for connection-less traffic where you may send traffic to any node at any time
- Based on **distance vector** or **link-state** mechanisms

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The Reactive Approach

- Routes are only created when desired by the source node
- Two-stage procedure
 - **Route discovery protocol:** route discovery ends either when a route is discovered or all possible communication paths have been examined
 - Once a route is established, it's maintained by some sort of **route maintenance protocol**

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Trade-off

	Proactive Approach	Reactive Approach
Latency	Low	High
Overhead	High	Low

- Reactive more suitable for a mobile environment with limited bandwidth
- Proactive preferred when time constraints are important

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Proactive Protocols

DV for fixed networks, DSDV for wireless networks

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Distance Vector Routing

- Route discovery algorithm used by RIP (**DVR does not address route maintenance**)
- Based on Bellman-Ford or Ford-Fulkerson algorithms but DVR does not require an a-priori knowledge of the network

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Distance Vector Routing (1)

- Let's consider that **cost coincides with distance, i.e., number of hops** (it could be expressed also in terms of bandwidth, latency,...)
- **Each node** has a **routing table** where distance to **all** reachable **destinations** is recorded
 - 1) Each table entry contains:
 - a) Destination node ID (i.e., IP address)
 - b) Next hop
 - c) Distance (number of hops) to the destination
 - 2) Each node keeps track and informs **its neighbors** of its distance **to every destination** (main idea of distance vector-based protocols)
- A router updates its distance to a destination **based on its neighbors distance to the destination**

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Distance Vector Routing (2)

1. Initially, each node sets the cost of the link to itself to 0 and to any other node to infinity
 2. A node broadcasts its routing information (list of destinations and distance)
 3. Upon receiving information from neighbors, a node computes the minimum cost-path toward destination and makes changes to its routing table if needed
 4. Either periodically or every time a node updates its table, it broadcasts routing information to its neighbors (then the procedure repeats from step 2)
- The algorithm **converges by iteration**

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Distance Vector Routing (2)

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More Details on Step 3

- At **node i and time step n+1**, the minimum cost path between nodes **i** and **j** is computed as

$$D^{n+1}(i, j) = \min \left\{ D^n(i, j), \min_{k \in N} \{ d(i, k) + D^n(k, j) \} \right\}$$

where:

$D^n(i, j)$ is the path cost from i to j at time step n

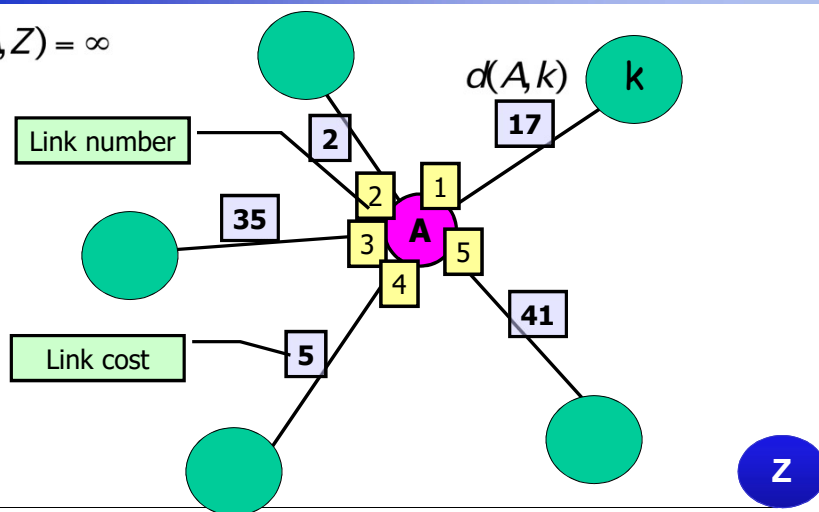
$d(i,k)$ is the cost of the link between i and its neighbor k

N is the set of i 's neighbours

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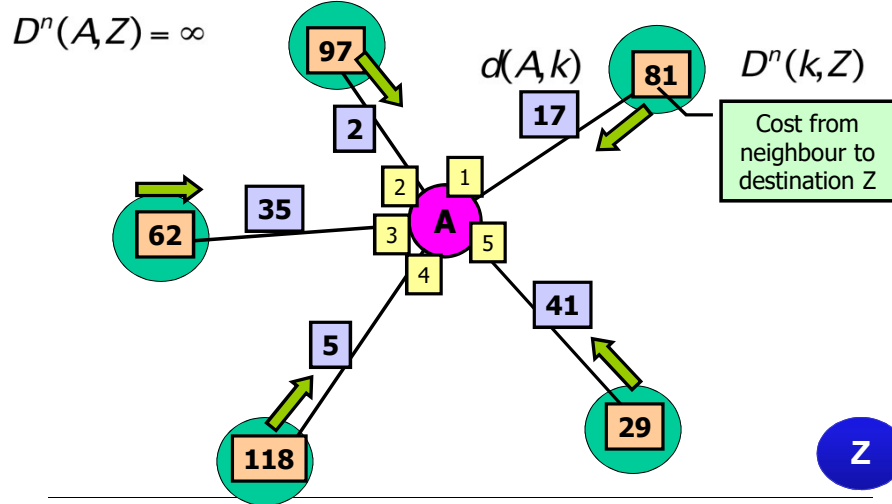
Distance Vector Routing for Address “Z”

$$D^n(A, Z) = \infty$$

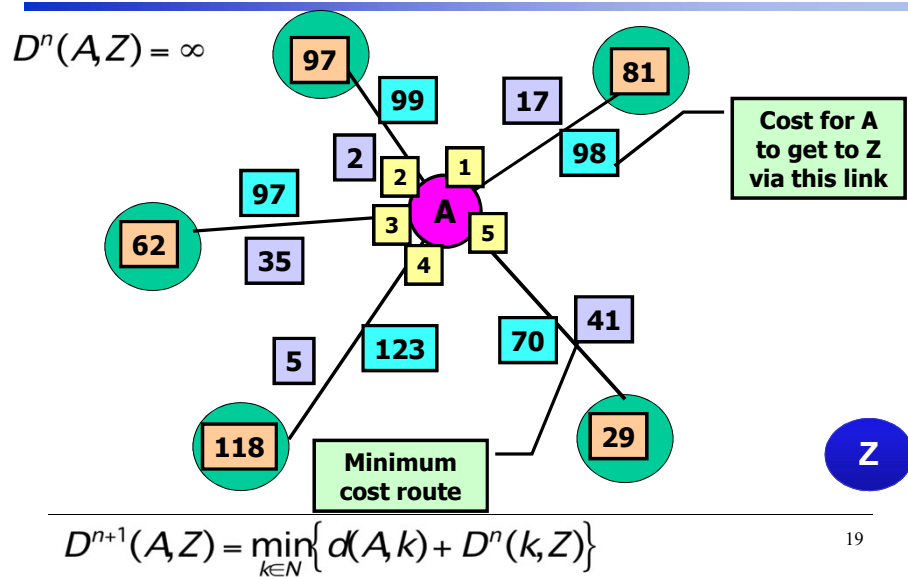


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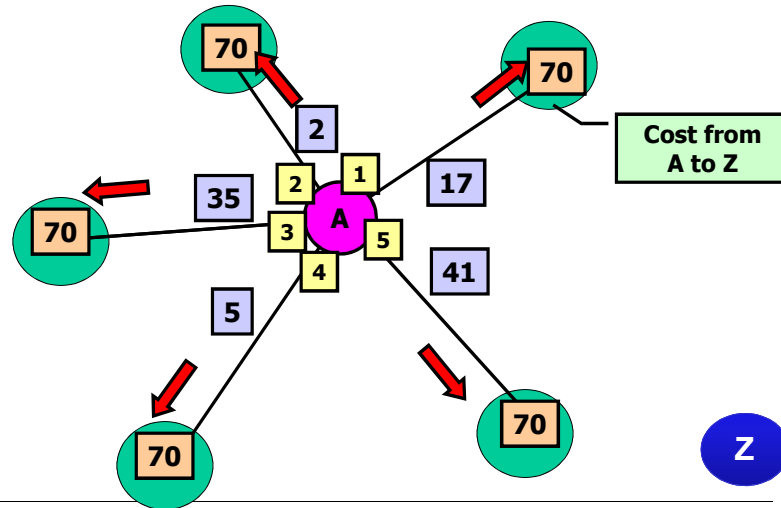
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Distance Vector Routing for Address "Z"



Distance Vector Routing for Address “Z”

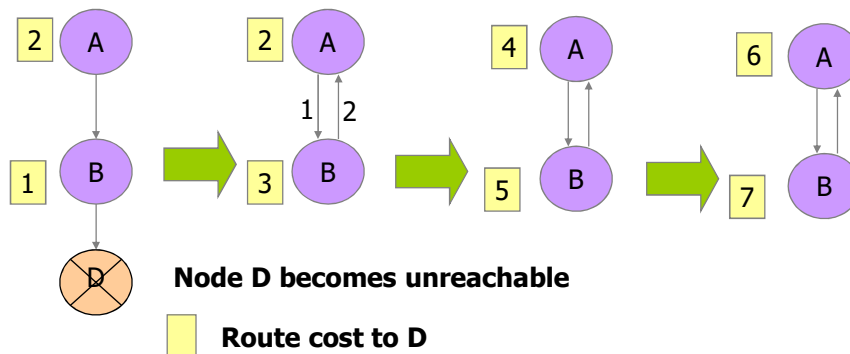


Problems with Distance Vector

1. **Does not scale well** with the number of nodes in the network (overhead $O(n^2)$)
2. **Slow convergence** to the lowest cost route
3. **Slow recovery time** if there are link failures, hence routing problems during disruption times
 - **Count-to-infinity:** Router loops may take place when degradation of a link cost occurs
 - Solved only when the cost of the alternative route including a loop reaches the cost of the degraded link

Count-to-Infinity: An Example

Cost of the link A-B and B-D equal to 1 => cost of the path between A and D equal to 2



It occurs only if A sends its update before B

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DSDV (1): Destination Sequenced Distance Vector Routing

- Proposed by Perkins [’94], based on Bellman-Ford routing mechanism
- Each node maintains a routing table that records all possible destinations
- Each table entry contains
 1. Destination node ID (i.e., IP address)
 2. Next hop
 3. Number of hops to the destination
 4. A sequence number (SN), used to distinguish “old” vs. “new” routes and avoid loops

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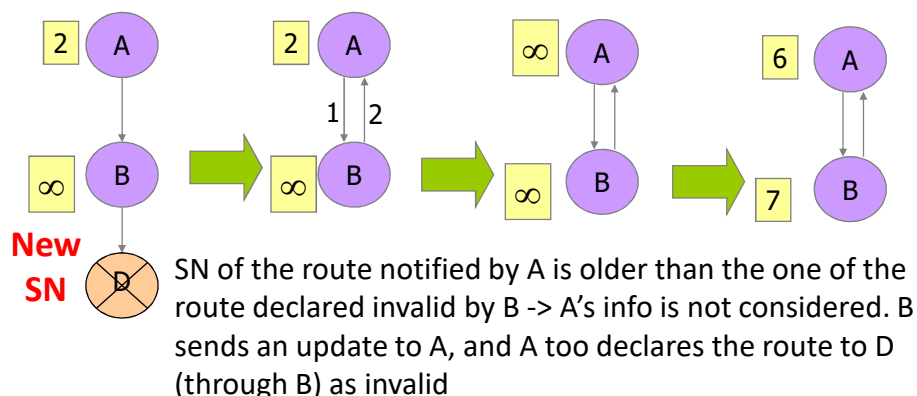
DSDV (2)

- Upon reception of a route update:
 - If the node doesn't have such information, it adds an entry to its table
 - Otherwise, it checks the SN and updates the table only in case of fresher information, i.e., the route with most recent SN is used
 - If two routes have the same SN, the route with the smaller metric (== shorter route) is used
- When a link fails, an ∞ metric is used and the route SN is increased

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Count-to-Infinity: An Example

Cost of the link A-B and B-D equal to 1 => cost of the path between A and D equal to 2



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Detecting Link Failure

- Detection:
 - If data is flowing over a link, failure of link layer to deliver a packet can be used to assume link failure
 - If a node does not hear for a long time (how long?) from its neighbor

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Proactive Protocol

OLSR

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OLSR

Optimized Link State Routing [Jacquet'00]

- OLSR is based on the link state routing approach
- Traditional approach in Link State Routing:
 - Every node generates control packets to advertise its links status (i.e., its one-hop neighbors and the links cost)
 - Such information is propagated over the whole network (flooding)

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OLSR

Optimized Link State Routing [Jacquet'00]

- However, in OLSR:
 - Sources build routes proactively by using only **MultiPoint Relay** nodes (MPRs)
 - Only MPRs need to **generate and forward** link state updates
- OLSR thus leads to efficient flooding of control messages in the network: superfluous broadcast packet retransmission as well as the size of the link state packets are reduced

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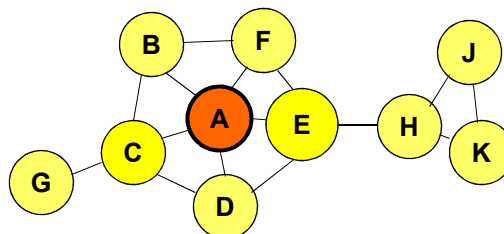
MPRs and Their Selection

- Every node in the network selects its own MPR(s)
- A node selects its MPRs among its 1-hop neighbors so that it can reach all nodes that are within 2-hop away, through symmetric links
- Nodes exchange 1-hop neighbor lists to know their 2-hop neighbors and link type, and choose the MPRs
- **No. of MPRs per node should be minimized**

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MPRs: Example (1)

- Hp: all links are bi-directional

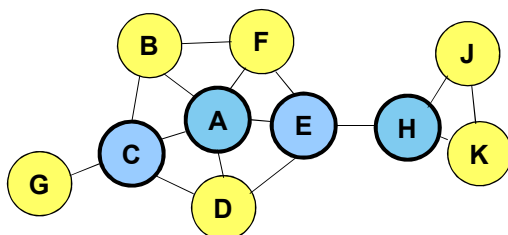


Nodes C and E are multipoint relays of node A

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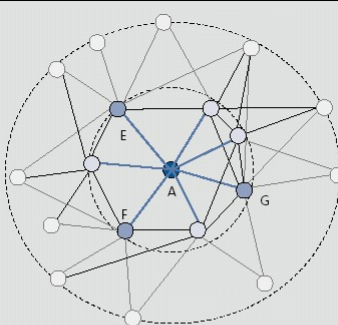
MPRs: Example (2)

- C selects A as MPR, while E selects A and H
- Node E is a multipoint relay also for node H
 - If the link H-J were unidirectional, then K would also be selected as MPR by H
 - Indeed, OLSR never uses unidirectional links



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MPRs: Example (3)

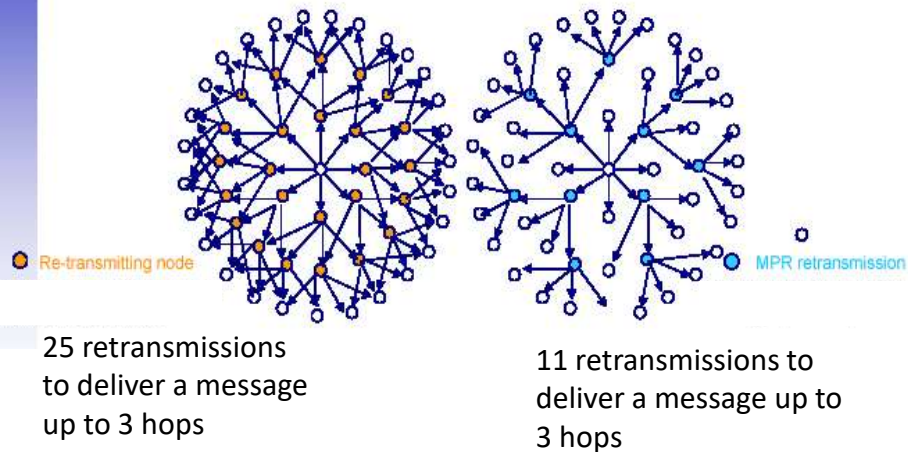


- Neighbors of node A
- Nodes E,F,G are A's MPR
- Two-hop neighbors of A that are covered by MPR
- Wireless links
- Links connecting MPR nodes and the two-hop nodes they covered
- Links connecting A and its neighbors

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■ Figure 2. OLSR: an illustration of multipoint relays.

Controlled Flooding of Link State Updates



Controlled Flooding of Link State Updates

- OLSR is particularly suited for dense networks
- In sparse networks, every neighbor becomes a multipoint relay, then OLSR reduces to pure link state protocol

How It Works: Hellos

- The generic node X broadcasts Hello messages every Hello interval to its 1-hop neighbors:
 - Hello message contains list of known 1-hop neighbors and
 - the link status (symmetric, asymmetric, or MPR) of its 1-hop neighbors

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How It Works: Neighbor Table

- Node X builds a **Neighbor Table** that includes all its 1-hop neighbors and, for each of them, all 2-hop neighbors that can be reached through it. The link types are also recorded.
 - X selects its MPR nodes among its 1-hop neighbors such that it can reach all nodes that are within 2-hops away through symmetric links
 - Once X has selected a neighbor, say Y, as MPR, X tags its link with Y as MPR and, through the next Hello, X will notify Y about it
 - **Y maintains the list of nodes that selected Y as an MPR**

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How It Works: Topology Control

- MPR nodes generate and broadcast Topology Control (TC) messages every TC interval to advertize link states, specifically
 - A TC message contains list of 1-hop neighbors who have selected this node as an MPR
 - Only MPR nodes can forward TC messages (but note that all network nodes connected through symmetric links will receive them) -> more efficient flooding
 - Nodes receiving TC messages use them to build their **Topology Table** (and for routing table calculation afterwards)

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Some Remarks

- Control messages do not require a reliable transmission since they are periodically sent
- Each control message includes a sequence number so that old messages with outdated information can be detected and discarded

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Some Observations (1)

- Routes are **all composed of MPRs** only (except source and destination): MPRs form a network backbone that is in charge of routing all traffic
- Asymmetric links are never used
- MPR nodes selection impact:
 - How much more traffic must MPR nodes handle? Higher load leads to higher energy consumption
- Node mobility impact
 - Consequences? Particularly for MPR nodes

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Some Observations (2)

- Hello interval impact on overhead vs. protocol reactivity:
 - Recall: Hellos are sent by all nodes to their 1-hop neighbors (but they are not rebroadcast)
- TC interval impact on overhead vs. protocol reactivity:
 - Recall: TC messages are sent only by MPR nodes to advertize link state but they reach all network nodes

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Reactive Protocols

DSR
AODV

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DSR

Dynamic Source Routing [Johnson'96]

- **Entirely “on demand”**: No periodic messages or advertisements at any layer
- **Dynamic**: it maintains a “soft state,” i.e., all state is discovered when needed and can be easily re-discovered if needed after a failure without impacting the protocol functioning
- **Source Routing**: the source specifies in the header of each data packet the entire route, not only the next hop (**no need for routing tables**)

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Assumptions

- The network is fairly small (up to 200 nodes, network diameter of 10-15 nodes /hops)
- Each node maintains a cache containing all source routes of which it is aware
 - Routes in the cache are continuously updated as they are learned
 - Several routes can be cached to the same destination
- Either bi- or uni-directional links are present

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DSR: Two Phases

The protocol consists of two phases:

- **Route discovery:**
 - Started by **S** when **S** needs to send data to **D** and doesn't have any route to **D** in cache
- **Route Maintenance:**
 - **While using a route to D**, **S** can detect if the route is no longer valid and, in case, send an error message
 - Upon route failure, **S** may use another route (if it knows it) or start a new route discovery

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DSR

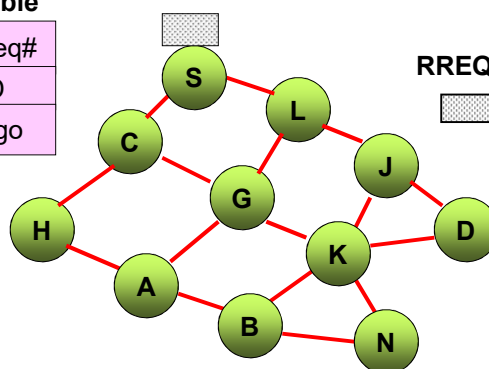
- DSR uses four control messages:
 - Route REQuest packets (RREQ)
 - Route REPLY packets (RREP)
 - Route ERRor packets (RERR)
 - ACKnowledgments (ACKs)
- RREP can be piggybacked to RREQ packets and ACKs to IP data packets

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Route Discovery

RREQ Table

Initiator seq#
Dest ID
Time to go



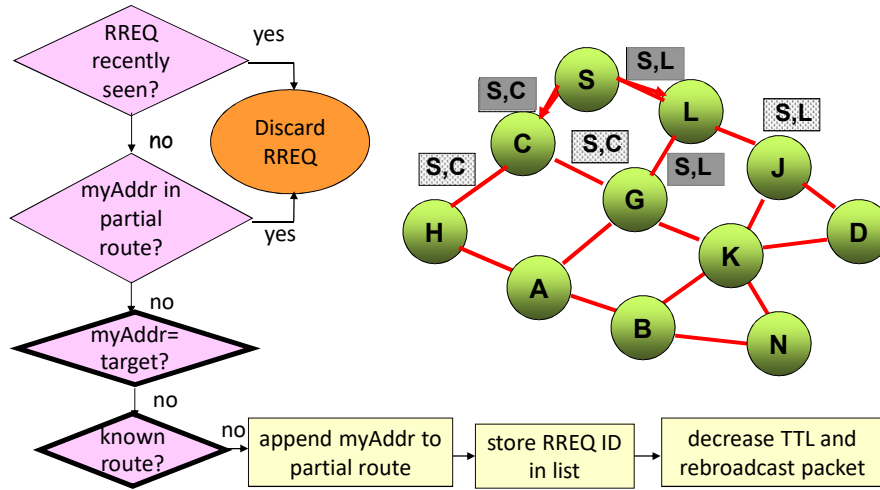
RREQ

Initiator ID
Initiator seq#
Dest ID
Partial route
TTL
Unique ID
QoS cost

If no reply by the “time to go”, S sends a new RREQ till a max no. of attempts have been made

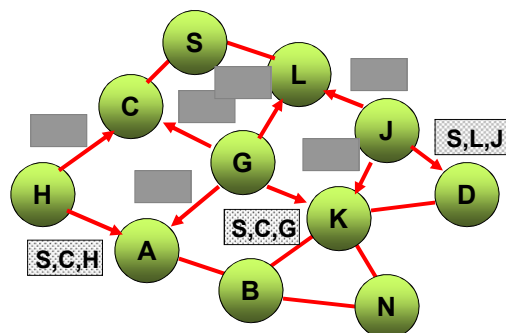
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Route Discovery



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Route Discovery



Route discovery succeeded !

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Route Reply (1)

- Once the message gets to the destination or reaches a node with an unexpired cached entry, a **RREP** is sent
 - If it is an intermediate node, it appends the cached route to the route record
 - If it is the destination, upon receiving the RREQ, it places the final route record into the RREP
- The route cost is returned by **D** (or intermediate node) in the RREP
 - Cost depends on the target QoS metric (energy consumption, latency, bandwidth, etc.)

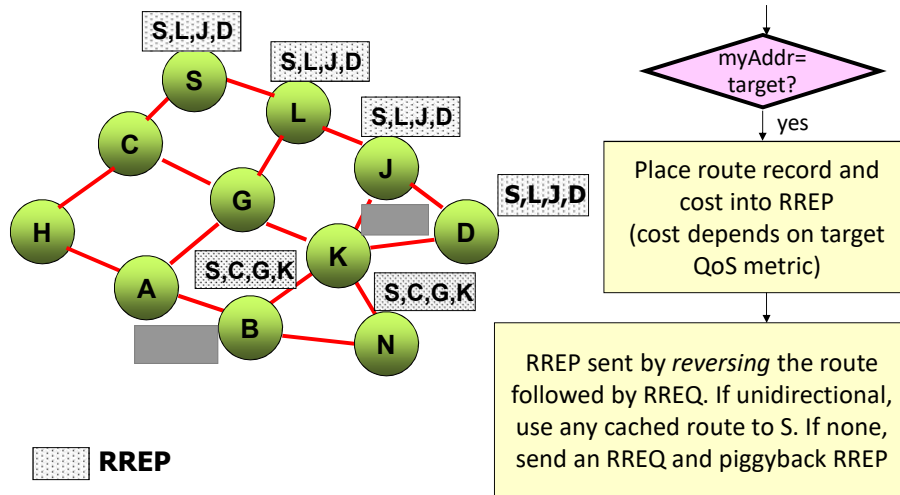
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Route Reply (2)

- The replying node must have a route back to the source
 - RREP can be sent on the route obtained by *reversing* the route appended to received RREQ
 - If it's a unidirectional link, the node can use any route it knows to the source
 - If the node does not have any route to the source, it performs a route discovery. The route reply is piggybacked on the new RREQ

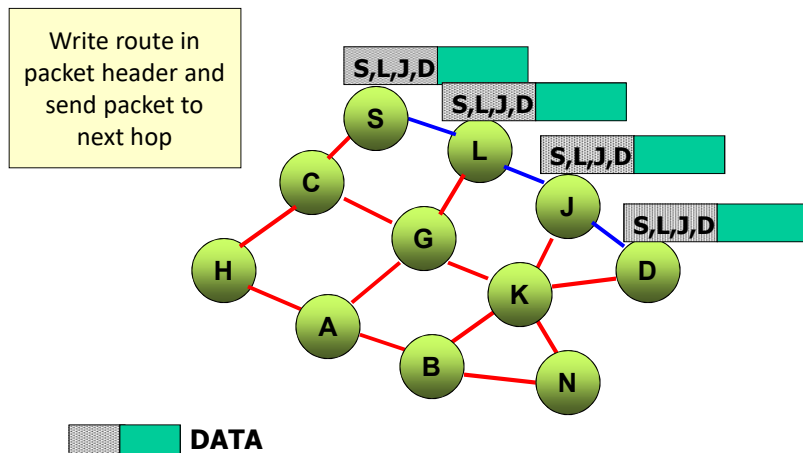
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Route Reply



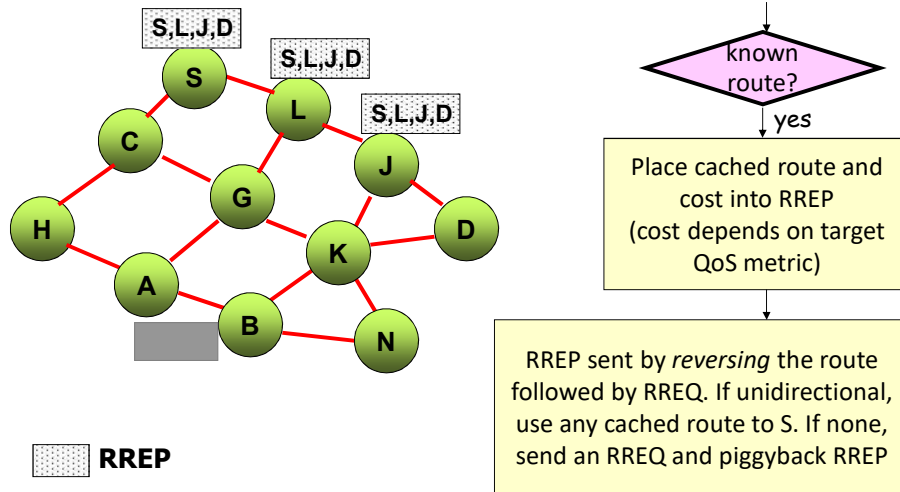
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Data Delivery



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Route Caching



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Route Caching

- **S** caches the route to **D** contained in the RREP
 - For each **D**, more than one route can be cached, thus **S** can perform traffic routing over several possible routes
- Advantages of route caching
 - Speeds up routing
 - Reduces propagation of route requests

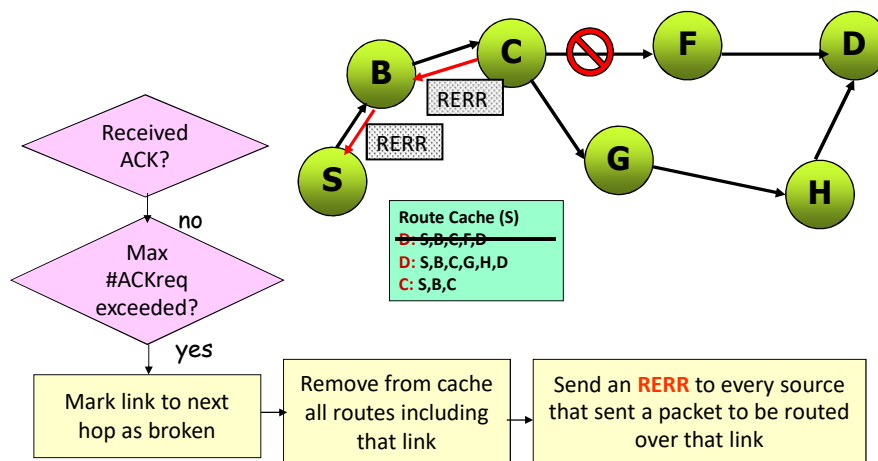
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Route Maintenance

- Along a source route, each node transmitting a packet is responsible for correct transmission confirmation
- An ACK is needed for confirmation
 - MAC or link-layer ACKs can be used
 - Overhearing next node forwarding the packet (**passive ACK**: A hears B sending to C)
 - Use of DSR-ACKs: the node transmitting the packet can require an ACK (which may follow a different route back)

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Route Maintenance



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Route Maintenance

- Nodes overhearing RERR remove from their cache all routes including the broken link
- **S** uses another route from its cache, if it has any; otherwise it starts a new route discovery
- The transport layer (e.g., TCP) should take care of data retransmissions

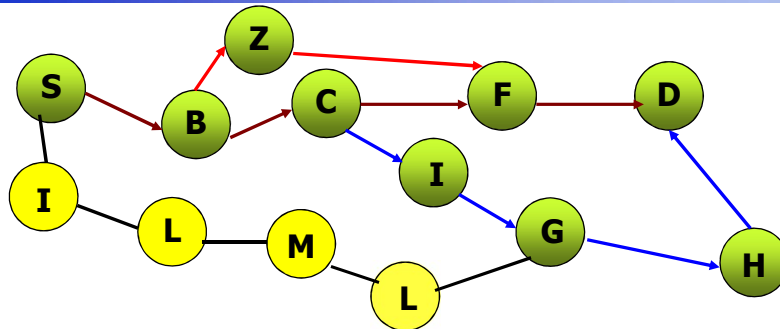
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Optimizations

- **Promiscuous mode:** listening to arbitrary routes in use (A hears B sending to C)
 - Replace with shorter routes / Store new routes
 - But promiscuous mode takes energy
- **Packet salvaging**
 - Upon link failure
 - If intermediate node has another route to **D**, it replaces the original source
 - However, no double salvage is allowed !!! (flag in the packet header indicates if the packet has been saved already once)

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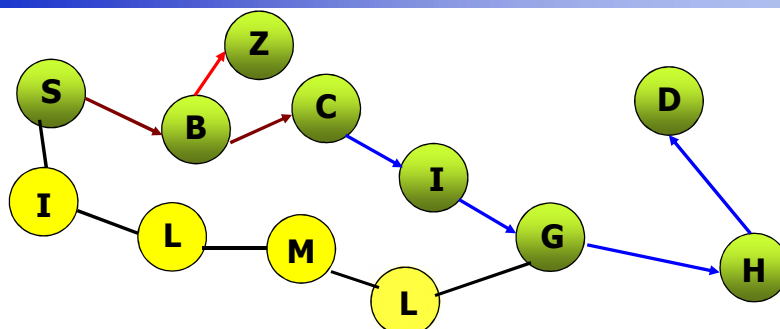
Packet Salvaging: An Example (1)



- Initial route: S (source) – B – C – F – D (destination)
- However, S and C have an alternative route to D in their cache (S-B-Z-F-D and C-I-G-H-D, respectively)
- At a certain time, F moves out of the network

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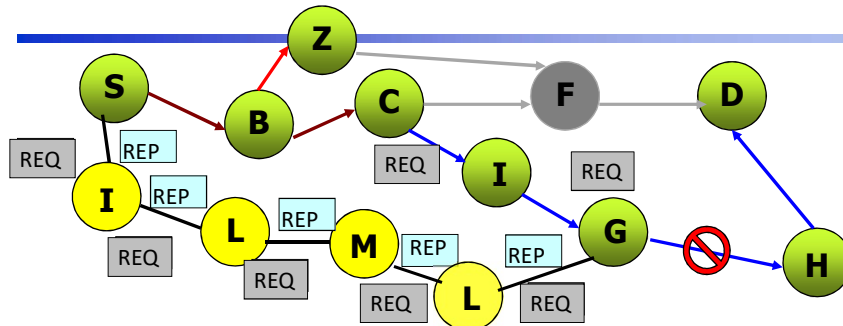
Packet Salvaging: An Example (2)



- Assume that unfortunately S (and B) do not receive RERR, from either C or Z, then S keeps sending its packets toward C
- C can salvage the packets by replacing the original route (S-B-C-F-D) in the packet with the new route (C-I-G-H-D)

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Packet Salvaging: An Example (3)



- Now, assume the G-H link fails, then IF G could save the packet again, a loop could have been formed. Indeed
 - (i) G does not know that the packet was originated by S (it only sees C as originator),
 - (ii) S could respond to a RREQ by G with route S-B-Z-F-D (If C does not send the RRERR or its RRERR does not reach S before G's RREQ)

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DSR: Advantages

- Enirely reactive
- "Soft state" and support of unidirectional links
- Source routing
 - No need for routing decisions by intermediate nodes
 - Nodes can learn new routes from relayed packets
 - Guarantee that routes are loop-free
- Caching
 - Reduced route discovery overhead
 - One route discovery may yield many routes to D, due to intermediate nodes replying from local caches

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DSR: Disadvantages

- ✗ RREQ flooding may be huge
 - ✗ Possible collisions between RREQs propagated by neighboring nodes
 - ✗ Contention between RREPs come back due to use of local caches (RREP *Storm* problem)
 - ✗ Packet delays/jitters due to on-demand routing
 - ✗ Headers may become too long with respect to data payloads -> suitable for small networks
 - ✗ Cached routes may become invalid; stale caches can adversely affect performance
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AODV

Ad-Hoc On Demand Distance Vector [Perkins'99]

- Builds routes *on demand*
 - Attempts to improve DSR by using (small) routing tables at the nodes so that packets do not have to include routes
 - Avoids loop formation by using sequence numbers
 - Similar procedures of route discovery and route maintenance as in DSR
-

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Assumptions

Each node maintains:

- A broadcast ID to be used for RREQs
 - Broadcast ID is incremented for each RREQ
 - Combination of the node IP address & broadcast ID uniquely identifies an RREQ
- **A (small) routing table** with an entry for each “useful” destination node
- Consider only symmetric links

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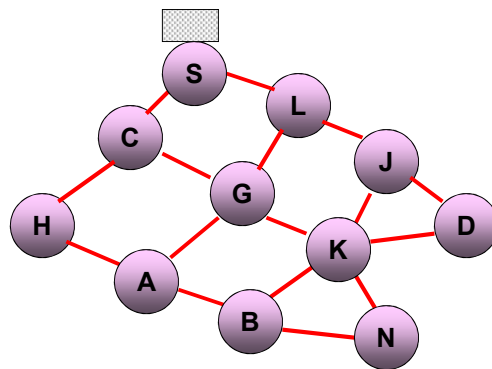
Routing Table

A routing table entry includes:

1. Destination IP address
2. Next hop
3. Hop count
4. **Active route timeout (lifetime)**
5. **Routing flag indicating whether the path is active or not**
6. **Sequence number assigned to the path by the destination (Destination Sequence Number, DSN)**

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Route Discovery



RREQ

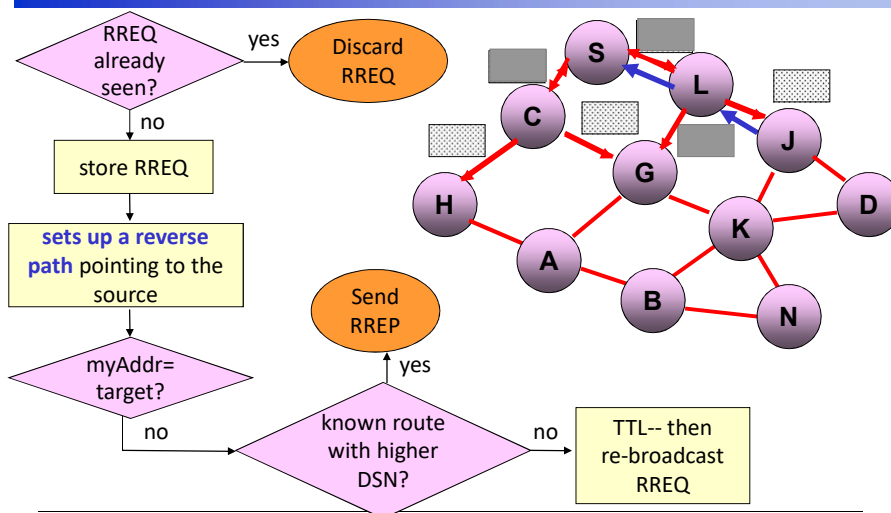
Initiator ID
Dest. Sequ. #
Dest ID
Broadcast ID
TTL
QoS cost

No partial route field, since no route is recorded on RREQ

- **Two routes will be found:** from S to D and from D to S (symmetric links are needed)
- A new RREQ by node **S** for a given destination, is assigned a higher DSN (for the inverse route with **S** as a destination)

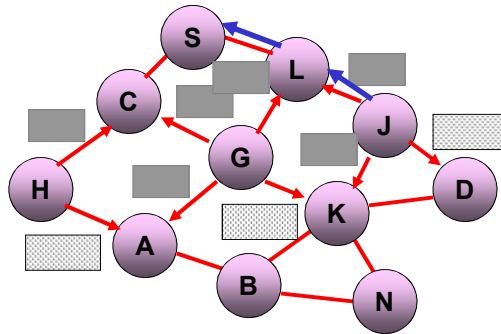
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Route Discovery



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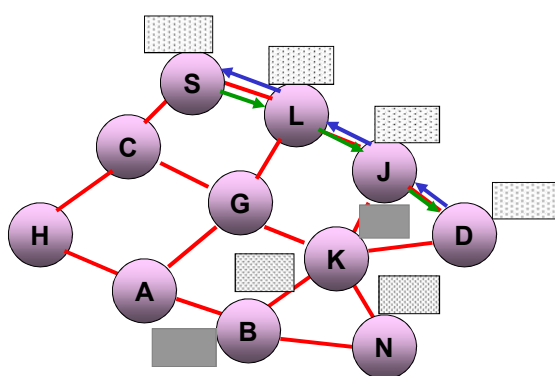
Route Discovery



Route discovery succeeded !

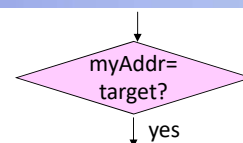
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Route Reply



 RREP

Nodes on the route **set a forward path** to D as they receive the RREP



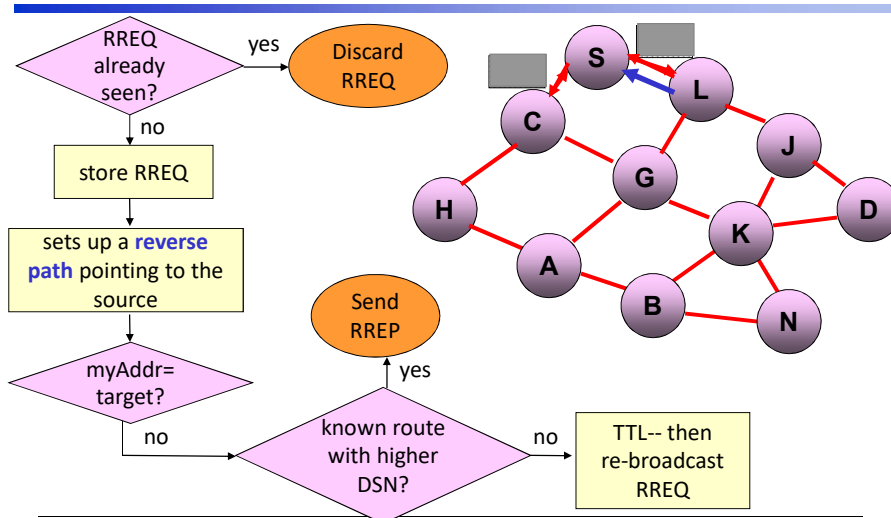
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Remarks

- **D** replies to the first arrived RREQ thus AODV favors the least congested route (that is not always the shortest one)
- As OLSR, it only supports symmetric links!
 - RREP forwarded along the same route followed by the RREQ

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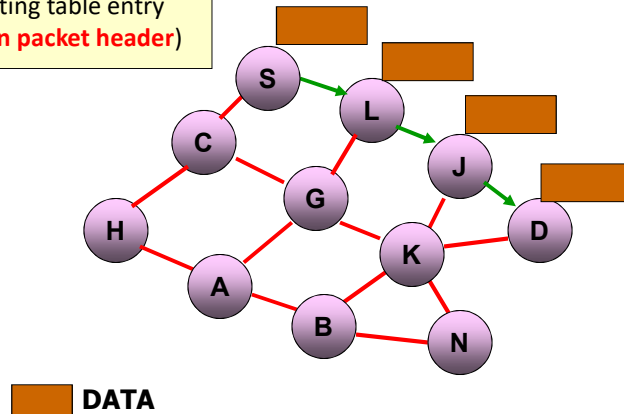
Route Discovery



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Data Delivery

Send data packet to next hop
using routing table entry
(no route in packet header)



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Timeouts

- A routing table entry maintaining a **reverse** path is purged after a timeout interval long enough to let the RREP come back to the source
- A routing table entry is purged if the route has not been used for an **active_route_timeout** interval

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Route Maintenance

- **HELLO** messages are periodically exchanged between neighboring nodes to maintain local connectivity
 - Absence of Hello messages is used as an indication of link failure
 - Hello messages can also contain the ID of the neighbors from which a node has heard
- A node can also use MAC acknowledgements or packet retransmissions done by a neighbor to check on the next hop reachability

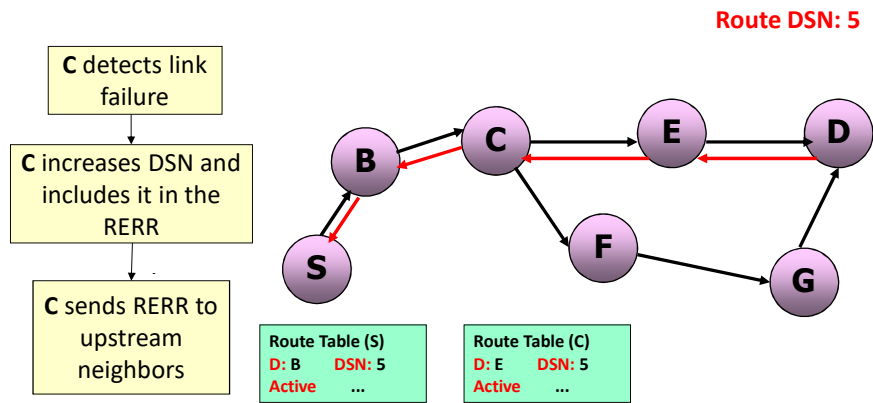
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Link Failure

- If a node, **X**, along the route moves, the upstream neighbor propagates an **RERR** message to each upstream neighbor till **S** is reached
- The upstream neighbor of **X** increases the route DSN and includes it in the RERR
- **S** may decide to start a new route discovery for that destination, using the new value of DSN
- When **D** receives the route request with destination sequence number **N**, node **D** will set its sequence number to **N**, unless it is already larger than **N**

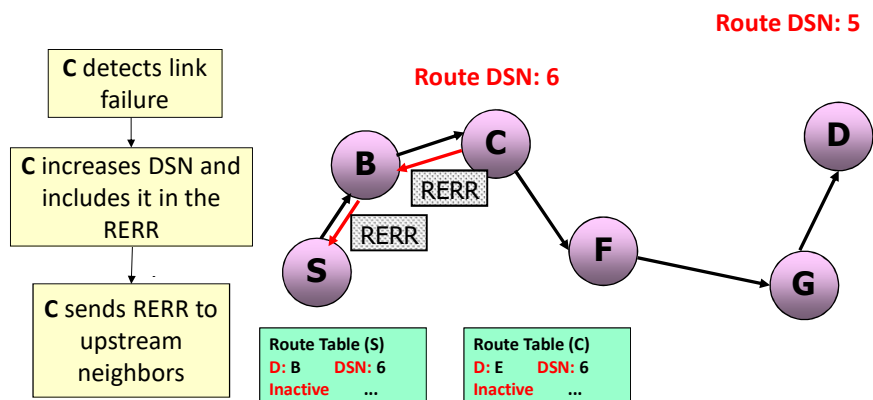
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Link Failure



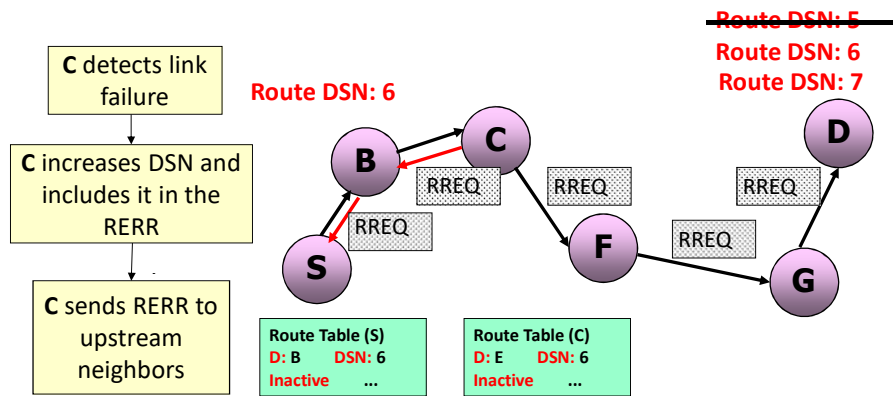
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Link Failure



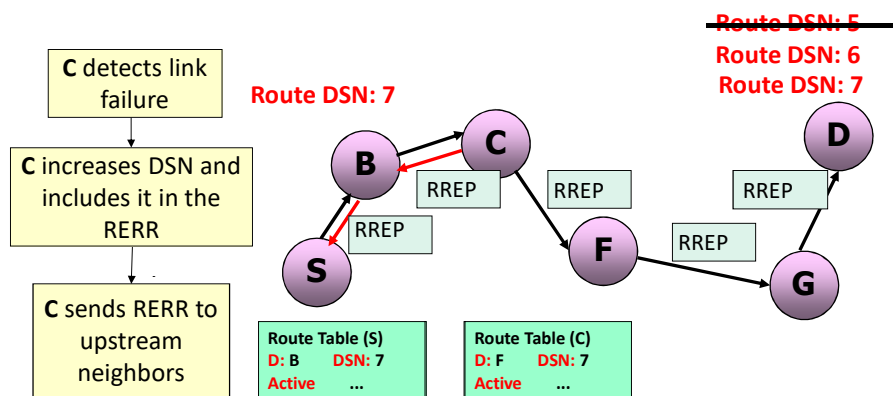
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Link Failure



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Link Failure



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Advantages & Disadvantages

Advantages

- No need to include route in the packet header
- Nodes maintain routing tables containing entries only for routes in use
- DSNs allow nodes to avoid invalid/broken routes
- DSNs prevent formation of loops

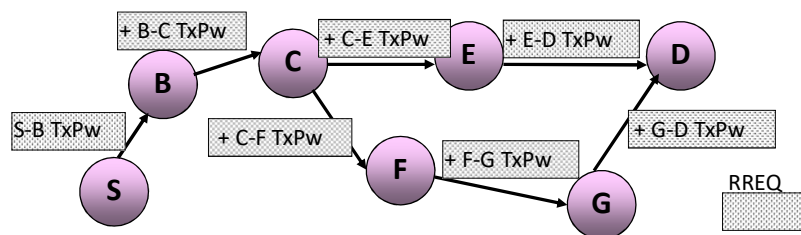
Disadvantages

- ✗ Unused routes expire even if topology is unchanged
- ✗ Multiple routes for each pair S-D are not supported
- ✗ Need for symmetrical links

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QoS Routing

- Associate each link with a **cost**
 - E.g., transmission power, transmitter's residual energy, traffic load, available bandwidth
- RREQs used to collect the cost (or minimum cost) of all traversed links along a route



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QoS Routing

- Destination responds with a Route Reply to a RREQ if
 - it is the first RREQ with a given (“current”) sequence number, or
 - the route cost is smaller than all other routes cost received with the current sequence number
- Possible modifications to routing protocols, such as DSR, to make them QoS-aware

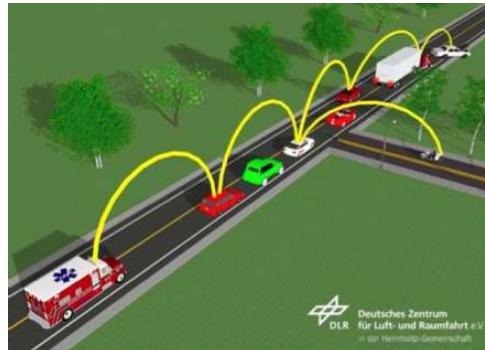
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QoS Routing

- Optimal routing decision requires constant updates on link state information (e.g., delay, bandwidth, loss rate, link stability) resulting in large overhead
- Dynamic nature of ad hoc networks makes maintaining the precise link state information very hard
- Even after resource reservation, QoS still cannot be guaranteed due to the frequent topology changes

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Routing in VANETs



Which Protocol Is Suitable?

- Proactive and reactive protocols may not be suitable:
 - Proactive protocols: routing tables might often contain stale information, due to the highly-dynamic network topology
 - Reactive protocols typically imply high latency due to the route discovery phase
- Positioning systems can be exploited to efficiently route traffic in VANETs → **geographic routing**

Geographic Routing (1)

- Position-based schemes: nodes determine their geographical position through GPS; **using BSM (Basic Safety Message)/CAM (Cooperative Awareness Messages) a node can acquire also the position of its neighboring nodes**
- It is assumed that the **destination coordinates are known** (easy if it's an RSU-Road Side Unit) and they are included in the data packet
 - If the destination is a vehicle, then its position can vary over time and message delivery may fail

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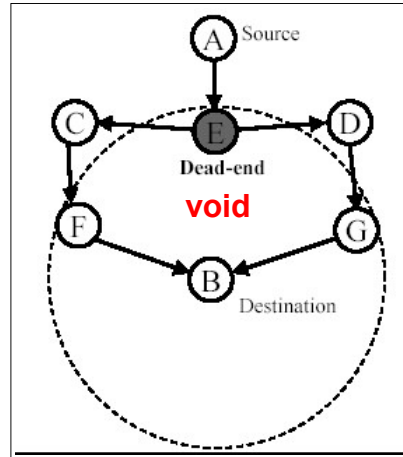
Geographic Routing (2)

- Next hops are determined based on their position or movement direction with respect to the intended destination
 - Self-election is possible, or the current forwarder can select the next one
- In the **basic greedy geographic** technique, the packet is forwarded at each step to the neighbor whose position is closest to destination
- Greedy forwarding, however, is susceptible to problem of dead-ends

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Dead-end with Geographic Routing

- Both E's neighbors (i.e., C and D) are further away from the destination than the sender (E)
- Adopt the right-hand rule to solve the problem: E-C-F-B (same as to get out of a maze)
- A similar approach is used in sensor networks; however in VANETs, several factors can help:
 - the spatial-constrained topology (roads)
 - the delay-tolerant nature of the traffic, along with the fact that nodes move and can get closer to the destination themselves



Location-Aided Routing (LAR)

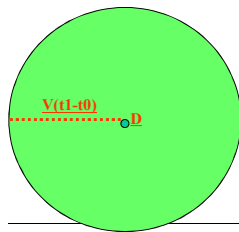
(Young-Bae Ko and Nitin H. Vaidya, 2000)

A Reactive algorithm – uses location info to reduce route discovery overhead

- ❑ It uses location information (e.g., GPS)
- ❑ Every node specifies 2 zones for route discovery
 1. Expected zone (for the destination)
 2. Request zone (route request)

LAR: Expected zone

- ☐ Node S wants to communicate with node D at t_1
- ☐ Assume that S knows position of D at time t_0
- ☐ S defines the zone into which D is expected (this zone is just an estimation of S's location)
 - ☐ When this zone is correct, route is established quickly
 - ☐ When this zone is incorrect, performance similar to flooding



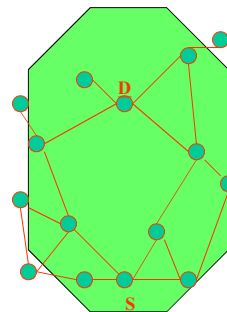
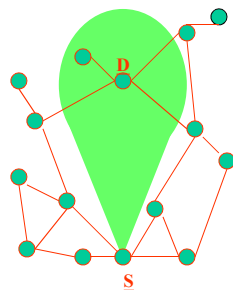
the expected zone is proportional to

- (i) average speed of movement v , and
- (ii) time elapsed since the last known location of the destination was recorded

LAR: Request Zone

- S searches for D by defining a new zone, the request zone
- A node forwards a route request only if it is inside the request zone
- The *request zone* includes the *expected zone*

“minimal” request zone does not include any path to D!

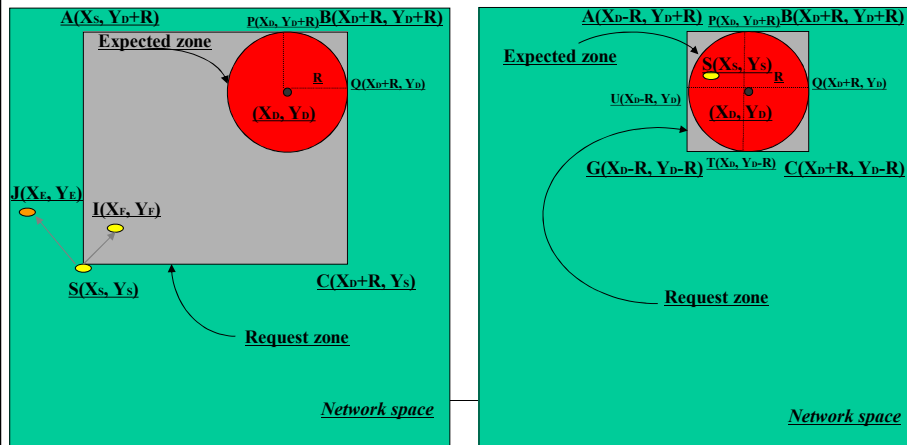


“expanded” request zone will induce more overhead but saves repeated cycles of search / delays.

Upon D discovery, reply message carries updated info for D (location, speed, etc) for future search

LAR: Scheme 1

Request zone: the smallest rectangle that includes current location of S and the expected zone (the circular region) - Coordinates of zone (4 corners) sent by S with the route request message transmitted when initiating route discovery



LAR: Scheme 2

The forwarded route request includes 2 pieces of info:

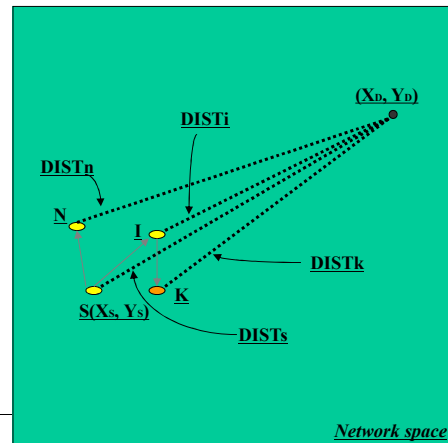
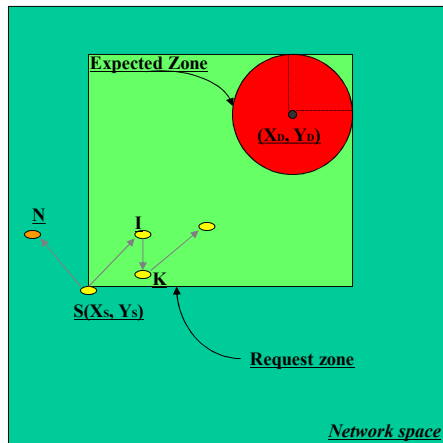
- The coordinates of D
- The distance $DIST_k$ between forwarding node k and D (the most recent info is used)

A node i forwards the route request it receives only when:

- It is not the destination node itself
- It has not forwarded the same route request in the past
- For some parameters α and β , $\alpha(DIST_s) + \beta > DIST_i$. That is, if node i is closer or not much further away from S.
(α and β shape the trade off between the probability of finding a route on the first attempt and the cost of finding the route)

LAR: Schemes 1 & 2

LAR1: node N discards / LAR2 ($\alpha=1, \beta=0$) node K discards



Energy-Aware Routing

Possible objectives:

1. Minimization of energy for packet transmission

Problem: Frequent use of the same routes/paths

2. Maximization of the system's lifetime

Some Energy-Aware Routing Algorithms

Request-delay algorithm

- Each node holds a request packet for a period which is inversely proportional to its current energy level
- After this waiting period, the node forwards the request
- Each node accepts only an earlier request packet and discards other duplicate requests
- The destination node selects the path that corresponds to the first request packet that it receives; the recorded routes in this packet are expected to be along nodes with relatively high energy levels.

Max-min algorithm

- Requires an energy value field in a request packet
- Every node that forwards such request inscribes its energy level
- The destination node selects the route with the lower-energy node that has the higher energy level

DSR-Based

Example - Using Energy Level Info

