

# Character Tables of Point Groups

## 1 The single crystallographic point groups

The 32 crystallographic point groups will be listed in roughly decreasing order of complexity. For each group the following details are given:

(a) *The group elements.* The notation for rotations is as in Chapter 1, Section 2(a),  $C_{nj}$  denoting a proper rotation through  $2\pi/n$  in the right-hand screw sense about the axis  $Oj$  and  $I$  denoting the spatial inversion operator. All the axes involved are indicated in Figures D.1

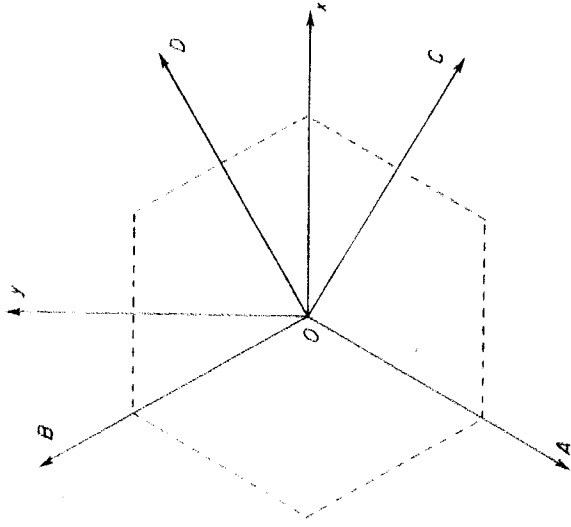
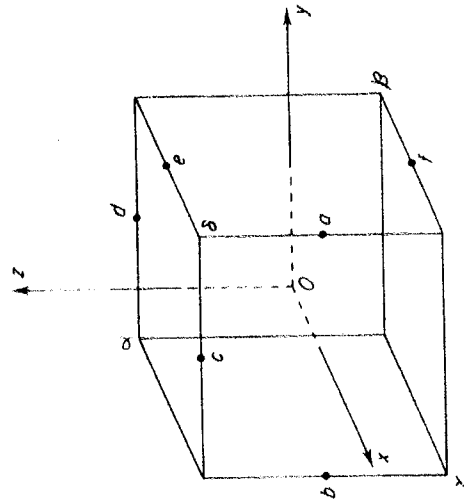


Figure D.2 The axes OA, OB, OC and OD. (All these axes lie in the plane Oxy.)

and D.2. The matrices  $R(T)$  for every relevant proper rotation are specified in Table D.1. The rotations are listed in classes.

(b) *The character table.* Several alternative systems of labelling are given, the first column merely giving an arbitrary listing. In the labelling of the second column one-dimensional representations are

$$R(E) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

$$R(C_{36}) = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix},$$

$$R(C_{36}^2) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix},$$

$$R(C_{36}^3) = \begin{bmatrix} 0 & 0 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{bmatrix},$$

$$R(C_{36}^4) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & -1 \\ -1 & 0 & 0 \end{bmatrix},$$

$$R(C_{36}^5) = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ -1 & 0 & 0 \end{bmatrix},$$

$$R(C_{36}^6) = \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \\ 0 & -1 & 0 \end{bmatrix},$$

$$R(C_{36}^7) = \begin{bmatrix} 0 & 0 & -1 \\ -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix},$$

Table D.1 The matrices  $R(T)$  for the proper rotations T appearing in various crystallographic point groups.

$$\begin{aligned}
\mathbf{R}(C_{36}^{-1}) &= \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, & \mathbf{R}(C_{2x}) &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \\
\mathbf{R}(C_{2y}) &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}, & \mathbf{R}(C_{2z}) &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \\
\mathbf{R}(C_{4x}) &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}, & \mathbf{R}(C_{4y}) &= \begin{bmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \\
\mathbf{R}(C_{4z}) &= \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, & \mathbf{R}(C_{4x}^{-1}) &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}, \\
\mathbf{R}(C_{4y}^{-1}) &= \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix}, & \mathbf{R}(C_{4z}^{-1}) &= \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \\
\mathbf{R}(C_{2a}) &= \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}, & \mathbf{R}(C_{2b}) &= \begin{bmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \\
\mathbf{R}(C_{2c}) &= \begin{bmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, & \mathbf{R}(C_{2d}) &= \begin{bmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \\
\mathbf{R}(C_{2e}) &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, & \mathbf{R}(C_{2f}) &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix}, \\
\mathbf{R}(C_{3a}) &= \begin{bmatrix} -\frac{1}{2} & \frac{1}{2}\sqrt{3} & 0 \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}, & \mathbf{R}(C_{3x}^{-1}) &= \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2}\sqrt{3} & 0 \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}, \\
\mathbf{R}(C_{6z}) &= \begin{bmatrix} \frac{1}{2} & \frac{1}{2}\sqrt{3} & 0 \\ -\frac{1}{2}\sqrt{3} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}, & \mathbf{R}(C_{6z}^{-1}) &= \begin{bmatrix} \frac{1}{2} & -\frac{1}{2}\sqrt{3} & 0 \\ \frac{1}{2}\sqrt{3} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}, \\
\mathbf{R}(C_{2A}) &= \begin{bmatrix} -\frac{1}{2} & \frac{1}{2}\sqrt{3} & 0 \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} & 0 \\ 0 & 0 & -1 \end{bmatrix}, & \mathbf{R}(C_{2B}) &= \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2}\sqrt{3} & 0 \\ -\frac{1}{2}\sqrt{3} & \frac{1}{2} & 0 \\ 0 & 0 & -1 \end{bmatrix}, \\
\mathbf{R}(C_{2C}) &= \begin{bmatrix} \frac{1}{2} & -\frac{1}{2}\sqrt{3} & 0 \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} & 0 \\ 0 & 0 & -1 \end{bmatrix}, & \mathbf{R}(C_{2D}) &= \begin{bmatrix} \frac{1}{2} & \frac{1}{2}\sqrt{3} & 0 \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} & 0 \\ 0 & 0 & -1 \end{bmatrix}.
\end{aligned}$$

Table D.1 (continued)

denoted by A or B, two-dimensional irreducible representations by E and three-dimensional irreducible representations by T, in all cases with subscripts and/or superscripts attached. (The subscripts g and u (standing for *gerade* and *ungerade*) indicated representations that are even and odd under I respectively.) However, pairs of one-dimensional complex conjugate representations are bracketed together and labelled as a two-dimensional representation, as they correspond to degenerate eigenvalues (see Chapter 6, Section 5(a) and Chapter 7, Section 3(f)).

For a point group that is isomorphic to a group  $\mathcal{G}_0(\mathbf{k})$  (see Chapter 9, Section 2(a)) for  $O_h$ ,  $O_h^*$  and  $O_h^*$ , the third column gives the labelling convention of Bouckaert *et al.* (1936). In such cases the corresponding  $\mathbf{k}$ -vector is as defined in Tables 9.1, 9.2 or 9.3. As described in Chapter 9, Section 2(b), it is possible for two or more  $\mathbf{k}$ -vectors in different stars to have point groups  $\mathcal{G}_0(\mathbf{k})$  that are isomorphic. The group elements for each such  $\mathcal{G}_0(\mathbf{k})$  belonging to  $O_h$ ,  $O_h^*$  and  $O_h^*$  are specified when this occurs.

(c) *Matrices for the irreducible representations of dimension greater than one.* (Of course these are only unique up to a similarity transformation.) For one-dimensional representations the characters themselves are the matrix elements.

The notation employed for the point groups is that of Schönflies (1923). More information on these groups may be found in the book of Koster *et al.* (1964), which is wholly devoted to this subject, and in the articles of Altmann (1962, 1963).

(1)  $O_h$ :

(a) Classes [for  $\mathcal{G}_0(\mathbf{k})$  of  $\Gamma$ , H and R]:

$$\begin{aligned}
\mathcal{G}_1 &= E; \mathcal{G}_2 = C_{3a}, C_{3\beta}, C_{3\gamma}, C_{3\delta}, C_{3a}^{-1}, C_{3\beta}^{-1}, C_{3\gamma}^{-1}, C_{3\delta}^{-1}, \\
\mathcal{G}_3 &= C_{2x}, C_{2y}, C_{2z}; \mathcal{G}_4 = C_{4x}, C_{4y}, C_{4z}, C_{4x}^{-1}, C_{4y}^{-1}, C_{4z}^{-1}, \\
\mathcal{G}_5 &= C_{2a}, C_{2b}, C_{2c}, C_{2d}, C_{2e}, C_{2f}; \mathcal{G}_6 = I; \\
\mathcal{G}_7 &= IC_{3a}, IC_{3\beta}, IC_{3\gamma}, IC_{3\delta}, IC_{3a}^{-1}, IC_{3\beta}^{-1}, IC_{3\gamma}^{-1}, IC_{3\delta}^{-1}, \\
\mathcal{G}_8 &= IC_{2x}, IC_{2y}, IC_{2z}; \mathcal{G}_9 = IC_{4x}, IC_{4y}, IC_{4z}, IC_{4x}^{-1}, IC_{4y}^{-1}, IC_{4z}^{-1}, \\
\mathcal{G}_{10} &= IC_{2a}, IC_{2b}, IC_{2c}, IC_{2d}, IC_{2e}, IC_{2f}.
\end{aligned}$$

(b) The character table is given in Table D.2.

(c) Matrices for irreducible representations of dimension greater



$$\begin{aligned}\Gamma^m(\mathbf{E}) &= \Gamma^m(C_{2x}) = \Gamma^m(C_{2y}) = \Gamma^m(C_{2z}) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \\ \Gamma^m(C_{3\alpha}) &= \Gamma^m(C_{3\beta}) = \Gamma^m(C_{3\gamma}) = \Gamma^m(C_{3\delta}) = \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, \\ \Gamma^m(C_{3\alpha}^{-1}) &= \Gamma^m(C_{3\beta}^{-1}) = \Gamma^m(C_{3\gamma}^{-1}) = \Gamma^m(C_{3\delta}^{-1}) = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, \\ \Gamma^m(C_{4x}) &= \Gamma^m(C_{4y}) = \Gamma^m(C_{4z}) = \Gamma^m(C_{2x}) = \Gamma^m(C_{2y}) = \Gamma^m(C_{2z}) = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, \\ \Gamma^m(C_{4x}^{-1}) &= \Gamma^m(C_{4y}^{-1}) = \Gamma^m(C_{4z}^{-1}) = \Gamma^m(C_{2x}) = \Gamma^m(C_{2y}) = \Gamma^m(C_{2z}) = \begin{bmatrix} \frac{1}{2} & \frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, \\ \Gamma^m(C_{6x}) &= \Gamma^m(C_{6y}) = \Gamma^m(C_{6z}) = \Gamma^m(C_{2x}) = \Gamma^m(C_{2y}) = \Gamma^m(C_{2z}) = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}.\end{aligned}$$

Table D.4 The matrices  $\Gamma^m$  for  $O_h$ ,  $T_d$ ,  $O$ ,  $D_{3d}$  and  $C_{3v}$ .

	$\mathcal{E}_1$	$\mathcal{E}_2$	$\mathcal{E}_3$	$\mathcal{E}_4$	$\mathcal{E}_5$	$\mathcal{E}_6$	$\mathcal{E}_7$	$\mathcal{E}_8$	$\mathcal{E}_9$	$\mathcal{E}_{10}$	$\mathcal{E}_{11}$	$\mathcal{E}_{12}$
$\Gamma^1$	$A_{1g}$	1	1	1	1	1	1	1	1	1	1	1
$\Gamma^2$	$A_{2g}$	1	1	1	-1	-1	1	1	1	1	-1	-1
$\Gamma^3$	$B_{1g}$	1	-1	1	1	-1	1	-1	1	-1	1	-1
$\Gamma^4$	$B_{2g}$	1	-1	1	-1	1	1	-1	1	-1	-1	1
$\Gamma^5$	$E_{2g}$	2	-1	-1	2	0	0	2	-1	-1	2	0
$\Gamma^6$	$E_{1g}$	2	1	-1	-2	0	0	2	1	-1	-2	0
$\Gamma^7$	$A_{1u}$	1	1	1	1	1	1	-1	-1	-1	-1	-1
$\Gamma^8$	$A_{2u}$	1	1	1	1	-1	-1	-1	-1	-1	-1	1
$\Gamma^9$	$B_{1u}$	1	-1	1	-1	1	1	-1	1	-1	1	-1
$\Gamma^{10}$	$B_{2u}$	1	-1	1	-1	1	1	-1	1	-1	1	-1
$\Gamma^{11}$	$E_{2u}$	2	-1	-1	2	0	0	-2	1	1	-2	0
$\Gamma^{12}$	$E_{1u}$	2	1	-1	-2	0	0	-2	-1	-1	2	0

Table D.5 Character table for  $D_{6h}$ .

$$\begin{aligned}\mathbf{D}(\mathbf{E}) &= \mathbf{D}(C_{2x}) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, & \mathbf{D}(C_{6x}) &= \mathbf{D}(C_{3x}^{-1}) = \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, \\ \mathbf{D}(C_{6x}^{-1}) &= \mathbf{D}(C_{6x}) = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, & \mathbf{D}(C_{2x}) &= \mathbf{D}(C_{2x}) = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}, \\ \mathbf{D}(C_{2A}) &= \mathbf{D}(C_{2C}) = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, & \mathbf{D}(C_{2D}) &= \mathbf{D}(C_{2D}) = \begin{bmatrix} \frac{1}{2} & \frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}.\end{aligned}$$

Table D.6 The matrices  $\mathbf{D}$  for  $D_{6h}$ ,  $D_{3h}$ ,  $C_{6v}$  and  $D_6$ .

$$\begin{aligned}\mathbf{D}'(\mathbf{E}) &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, & \mathbf{D}'(C_{6x}) &= \begin{bmatrix} \frac{1}{2} & \frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & \frac{1}{2} \end{bmatrix}, \\ \mathbf{D}'(C_{6x}^{-1}) &= \begin{bmatrix} \frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & \frac{1}{2} \end{bmatrix}, & \mathbf{D}'(C_{3x}) &= \begin{bmatrix} -\frac{1}{2} & \frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, \\ \mathbf{D}'(C_{3x}^{-1}) &= \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, & \mathbf{D}'(C_{2x}) &= \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \\ \mathbf{D}'(C_{2x}) &= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, & \mathbf{D}'(C_{2A}) &= \begin{bmatrix} -\frac{1}{2} & \frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, \\ \mathbf{D}'(C_{2B}) &= \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & \frac{1}{2} \end{bmatrix}, & \mathbf{D}'(C_{2y}) &= \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}, \\ \mathbf{D}'(C_{2C}) &= \begin{bmatrix} \frac{1}{2} & -\frac{1}{2}\sqrt{3} \\ -\frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}, & \mathbf{D}'(C_{2D}) &= \begin{bmatrix} \frac{1}{2} & \frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & -\frac{1}{2} \end{bmatrix}.\end{aligned}$$

Table D.7 The matrices  $\mathbf{D}'$  for  $D_{6h}$ ,  $C_{6v}$ ,  $D_6$  and  $D_3$ .

(3)  $T_d$ :

(a) Classes [for  $\mathcal{G}_0(\mathbf{k})$  of  $P$ ]:

$$\begin{aligned}\mathcal{E}_1 &= E, \mathcal{E}_2 = C_{3\alpha}, C_{3\beta}, C_{3\gamma}, C_{3\delta}, C_{3\alpha}^{-1}, C_{3\beta}^{-1}, C_{3\gamma}^{-1}, C_{3\delta}^{-1}, \\ \mathcal{E}_3 &= C_{2x}, C_{2y}, C_{2z}; \mathcal{E}_4 = IC_{4x}, IC_{4y}, IC_{4z}, IC_{4x}^{-1}, IC_{4y}^{-1}, IC_{4z}^{-1}, \\ \mathcal{E}_5 &= IC_{2x}, IC_{2y}, IC_{2z}, IC_{2x}, IC_{2y}, IC_{2z}.\end{aligned}$$

(b) The character table is given in Table D.8.

(c) Matrices for irreducible representations of dimension greater than one, for proper rotations  $C_{n_j}$  of  $T_d$ :

$$\begin{aligned}\Gamma^3(C_{n_j}) &= \Gamma^m(C_{n_j}); \Gamma^4(C_{n_j}) = \mathbf{R}(C_{n_j}); \Gamma^5(C_{n_j}) = \Gamma^m(C_{n_j}); \\ \text{and for the improper rotations } IC_{n_j} \text{ of } T_d: \\ \Gamma^3(IC_{n_j}) &= -\Gamma^m(C_{n_j}); \Gamma^4(IC_{n_j}) = -\mathbf{R}(C_{n_j}); \Gamma^5(IC_{n_j}) = -\Gamma^m(C_{n_j});\end{aligned}$$

where the matrices  $\Gamma^m(C_{n_j})$ ,  $\Gamma^m(C_{n_j})$  and  $\mathbf{R}(C_{n_j})$  are given in Tables D.3, D.4 and D.1 respectively.

	$\mathcal{E}_1$	$\mathcal{E}_2$	$\mathcal{E}_3$	$\mathcal{E}_4$	$\mathcal{E}_5$
$\Gamma^1$	$A_1$	1	1	1	1
$\Gamma^2$	$A_2$	1	1	1	-1
$\Gamma^3$	$E$	2	-1	2	0
$\Gamma^4$	$T_2$	3	0	-1	1
$\Gamma^5$	$T_1$	3	0	-1	-1

Table D.8 Character table for  $T_d$  and  $O$ .

	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$	$\mathcal{C}_4$	$\mathcal{C}_5$	$\mathcal{C}_6$	$\mathcal{C}_7$	$\mathcal{C}_8$	$\mathcal{C}_9$	$\mathcal{C}_{10}$
$\Gamma^1$	$X_1, M_1$	1	1	1	1	1	1	1	1	1
$\Gamma^2$	$X_2, M_2$	1	1	1	-1	-1	1	1	1	-1
$\Gamma^3$	$X_3, M_3$	1	-1	1	-1	1	-1	1	-1	1
$\Gamma^4$	$X_4, M_4$	1	-1	1	1	-1	-1	1	1	-1
$\Gamma^5$	$X_5, M_5$	2	0	-2	0	0	2	0	-2	0
$\Gamma^6$	$X_1, M_1$	1	1	1	1	1	-1	-1	-1	-1
$\Gamma^7$	$X_2, M_2$	1	1	1	-1	-1	-1	-1	1	1
$\Gamma^8$	$X_3, M_3$	1	-1	1	-1	1	-1	1	-1	1
$\Gamma^9$	$X_4, M_4$	1	-1	1	1	-1	-1	1	-1	1
$\Gamma^{10}$	$X_5, M_5$	2	0	-2	0	0	-2	0	2	0

Table D.10 Character table for  $D_{4h}$ .

(6)  $D_{4h}$ :

(a) Classes [for  $\mathcal{C}_0(\mathbf{k})$  of X]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2z}, C_{2y}; \mathcal{C}_3 = C_{2x}; \mathcal{C}_4 = C_{4z}, C_{4z}^{-1};$$

$$\mathcal{C}_5 = C_{2\alpha}, C_{2\beta}; \mathcal{C}_6 = I; \mathcal{C}_7 = IC_{2z}, IC_{2y}; \mathcal{C}_8 = IC_{2x}; \mathcal{C}_9 = IC_{4z}, IC_{4z}^{-1};$$

$$\mathcal{C}_{10} = IC_{2\alpha}, IC_{2\beta}.$$

Classes [for  $\mathcal{C}_0(\mathbf{k})$  of M]:

$$\mathcal{C}_1 = E, \mathcal{C}_2 = C_{2y}, C_{2z}; \mathcal{C}_3 = C_{2x}; \mathcal{C}_4 = C_{4x}, C_{4x}^{-1}; \mathcal{C}_5 = C_{2z}, C_{2z}^{-1}; \mathcal{C}_6 = I;$$

$$\mathcal{C}_7 = IC_{2y}, IC_{2z}; \mathcal{C}_8 = IC_{2x}; \mathcal{C}_9 = IC_{4x}, IC_{4x}^{-1}; \mathcal{C}_{10} = IC_{2z}, IC_{2z}^{-1}.$$

(b) The character table is given in Table D.10.

(c) Matrices for irreducible representations of dimension greater than one, for any proper rotation  $C_{nj}$  of  $D_{4h}$ :

$$\Gamma^5(C_{nj}) = \Gamma^{10}(C_{nj}) = D(C_{nj}); \Gamma^5(IC_{nj}) = -\Gamma^{10}(IC_{nj}) = D(C_{nj});$$

where for  $\mathcal{C}_0(\mathbf{k})$  of M the matrices  $D(C_{nj})$  are given in Table D.11, while for  $\mathcal{C}_0(\mathbf{k})$  of X they are given in Table D.12.

$$D(E) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad D(C_{2z}) = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \quad D(C_{2\alpha}) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix},$$

$$D(C_{2z}) = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}, \quad D(C_{4z}) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad D(C_{4z}^{-1}) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix},$$

$$D(C_{2z}) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad D(C_{2z}^{-1}) = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}.$$

Table D.11 The matrices  $D$  for  $D_{4h}$  for  $\mathcal{C}_0(\mathbf{k})$  of M.

(4) O:

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{3\alpha}, C_{3\beta}, C_{3\gamma}, C_{3\delta}, C_{3\alpha}^{-1}, C_{3\beta}^{-1}, C_{3\gamma}^{-1}, C_{3\delta}^{-1};$$

$$\mathcal{C}_3 = C_{2x}, C_{2y}, C_{2z}; \mathcal{C}_4 = C_{4x}, C_{4y}, C_{4z}, C_{4x}^{-1}, C_{4y}^{-1}, C_{4z}^{-1};$$

$$\mathcal{C}_5 = C_{2\alpha}, C_{2\beta}, C_{2\gamma}, C_{2\delta}, C_{2\alpha}^{-1}, C_{2\beta}^{-1}, C_{2\gamma}^{-1}, C_{2\delta}^{-1}.$$

(b) The character table is given in Table D.8.

(c) Matrices for irreducible representations of dimension greater than one, for all rotations  $C_{nj}$  of O:

$$\Gamma^8(C_{nj}) = \Gamma^7(C_{nj}); \Gamma^4(C_{nj}) = \Gamma^5(C_{nj}); \Gamma^6(C_{nj}) = \Gamma^3(C_{nj});$$

where the matrices  $\Gamma^7(C_{nj})$ ,  $\Gamma^5(C_{nj})$  and  $\Gamma^3(C_{nj})$  are given in Tables D.3, D.4 and D.1 respectively.

(5)  $T_h$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{3\alpha}, C_{3\beta}, C_{3\gamma}, C_{3\delta}; \mathcal{C}_3 = C_{3\alpha}^{-1}, C_{3\beta}^{-1}, C_{3\gamma}^{-1}, C_{3\delta}^{-1};$$

$$\mathcal{C}_4 = C_{2x}, C_{2y}, C_{2z}; \mathcal{C}_5 = I; \mathcal{C}_6 = IC_{3\alpha}, IC_{3\beta}, IC_{3\gamma}, IC_{3\delta};$$

$$\mathcal{C}_7 = IC_{3\alpha}^{-1}, IC_{3\beta}^{-1}, IC_{3\gamma}^{-1}, IC_{3\delta}^{-1}; \mathcal{C}_8 = IC_{2x}, IC_{2y}, IC_{2z}.$$

(b) The character table is given in Table D.9.

(c) Matrices for irreducible representations of dimension greater than one, for any proper rotation  $C_{nj}$  of  $T_h$ :

$$\Gamma^4(C_{nj}) = \Gamma^8(C_{nj}) = \Gamma^7(C_{nj}); \Gamma^4(IC_{nj}) = -\Gamma^8(IC_{nj}) = \Gamma^7(C_{nj});$$

where the matrices  $\Gamma^7(C_{nj})$  are given in Table D.3.

	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$	$\mathcal{C}_4$	$\mathcal{C}_5$	$\mathcal{C}_6$	$\mathcal{C}_7$	$\mathcal{C}_8$
$\Gamma^1$	$A_x$	1	1	1	1	1	1	1
$\Gamma^2$	$E_x$	1	$\phi$	$\phi^2$	1	$\phi$	$\phi^2$	1
$\Gamma^3$	$T_x$	1	$\phi^2$	$\phi$	1	$\phi^2$	$\phi$	1
$\Gamma^4$	$A_u$	3	0	0	-1	3	0	-1
$\Gamma^5$	$E_u$	1	1	1	-1	-1	-1	-1
$\Gamma^6$	$T_u$	1	$\phi$	$\phi^2$	1	-1	-1	-1
$\Gamma^7$	$E_u$	1	$\phi^2$	$\phi$	1	-1	-1	-1
$\Gamma^8$	$T_u$	3	0	0	-1	-3	0	-1

Table D.9 Character table for  $T_h$  ( $\phi = \exp(\frac{2\pi i}{3})$ ).

$$\begin{aligned} \mathbf{D}(\mathbf{E}) &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, & \mathbf{D}(C_{2x}) &= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, & \mathbf{D}(C_{2y}) &= \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}, \\ \mathbf{D}(C_{2z}) &= \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, & \mathbf{D}(C_{4z}) &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, & \mathbf{D}(C_{4z}^{-1}) &= \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, \\ \mathbf{D}(C_{2a}) &= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, & \mathbf{D}(C_{2b}) &= \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}. \end{aligned}$$

Table D.12 The matrices  $\mathbf{D}$  for  $D_{3h}$  for  $\mathcal{S}_0(\mathbf{k})$  of X.

(7)  $D_{3h}$ :

(a) Classes

$$\mathcal{E}_1 = \mathbf{E}; \mathcal{E}_2 = C_{2x}, C_{3z}^{-1}, \mathcal{E}_3 = C_{2x}, C_{2A}, C_{2B}; \mathcal{E}_4 = IC_{2x}; \mathcal{E}_5 = IC_{6z}, IC_{6z}^{-1};$$

$$\mathcal{E}_6 = IC_{2y}, IC_{2C}, IC_{2D}.$$

(b) The character table is given in Table D.13.

(c) Matrices for irreducible representations of dimension greater than one, for any proper rotation  $C_{nj}$  of  $D_{3h}$ :

$$\Gamma^3(C_{nj}) = \Gamma^6(C_{nj}) = \mathbf{D}'(C_{nj});$$

and for any improper rotation  $IC_{nj}$  of  $D_{3h}$ :

$$\Gamma^3(IC_{nj}) = -\Gamma^6(IC_{nj}) = \mathbf{D}'(C_{nj});$$

where the matrices  $\mathbf{D}'(C_{nj})$  are given in Table D.6.

(8)  $D_{3d}$ :

(a) Classes [for  $\mathcal{S}_0(\mathbf{k})$  of L]:

$$\mathcal{E}_1 = \mathbf{E}; \mathcal{E}_2 = C_{3h}, C_{3h}^{-1}, \mathcal{E}_3 = C_{2b}, C_{2d}, C_{2f}; \mathcal{E}_4 = \mathbf{I}; \mathcal{E}_5 = IC_{3h}, IC_{3h}^{-1};$$

$$\mathcal{E}_6 = IC_{2b}, IC_{2d}, IC_{2f}.$$

(b) The character table is given in Table D.13.

	$D_{3h}$	$D_{3d}$	$C_{6v}$	$D_6$	$\mathcal{E}_1$	$\mathcal{E}_2$	$\mathcal{E}_3$	$\mathcal{E}_4$	$\mathcal{E}_5$	$\mathcal{E}_6$
$\Gamma^1$	$A_1'$	$A_1$	$A_1$	$A_1$	1	1	1	1	1	1
$\Gamma^2$	$A_2'$	$A_2$	$A_2$	$A_2$	1	1	-1	1	1	-1
$\Gamma^3$	$E'$	$E_2$	$E_2$	$E_2$	2	-1	0	2	-1	0
$\Gamma^4$	$A_1''$	$A_1$	$B_1$	$B_1$	1	1	1	-1	-1	-1
$\Gamma^5$	$A_2''$	$B_2$	$B_2$	$B_2$	1	1	-1	-1	-1	1
$\Gamma^6$	$E''$	$E_1$	$E_1$	$E_1$	2	-1	0	-2	1	0

Table D.13 Character table for  $D_{3h}$ ,  $D_{3d}$ ,  $C_{6v}$ , and  $D_6$ .

(c) Matrices for irreducible representations of dimension greater than one, for any proper rotation  $C_{nj}$  of  $D_{3d}$ :

$$\Gamma^3(C_{nj}) = \Gamma^6(C_{nj}) = \Gamma''(C_{nj}); \Gamma^3(IC_{nj}) = -\Gamma^6(IC_{nj}) = \Gamma''(C_{nj});$$

where the matrices  $\Gamma''(C_{nj})$  are given in Table D.4.

(9)  $C_{6v}$ :

(a) Classes:

$$\mathcal{E}_1 = \mathbf{E}; \mathcal{E}_2 = C_{3z}, C_{3z}^{-1}; \mathcal{E}_3 = IC_{2x}, IC_{2A}, IC_{2B}; \mathcal{E}_4 = C_{2x};$$

$$\mathcal{E}_5 = C_{6z}, C_{6z}^{-1}; \mathcal{E}_6 = IC_{2y}, IC_{2C}, IC_{2D}.$$

(b) The character table is given in Table D.13.

(c) Matrices for irreducible representations of dimension greater than one, for any proper rotation  $C_{nj}$  of  $C_{6v}$ :

$$\Gamma^6(C_{nj}) = \mathbf{D}''(C_{nj}); \Gamma^3(C_{nj}) = \mathbf{D}'(C_{nj});$$

and for any improper rotation  $IC_{nj}$  of  $C_{6v}$ :

$$\Gamma^6(IC_{nj}) = \mathbf{D}''(C_{nj}); \Gamma^3(IC_{nj}) = \mathbf{D}'(C_{nj});$$

where the matrices  $\mathbf{D}'(C_{nj})$  and  $\mathbf{D}''(C_{nj})$  are given in Tables D.6 and D.7 respectively.

(10)  $C_{6h}$ :

(a) Classes:

$$\mathcal{E}_1 = \mathbf{E}; \mathcal{E}_2 = C_{6z}; \mathcal{E}_3 = C_{3z}; \mathcal{E}_4 = C_{2z}; \mathcal{E}_5 = C_{3z}^{-1}; \mathcal{E}_6 = C_{6z}^{-1}; \mathcal{E}_7 = \mathbf{I};$$

$$\mathcal{E}_8 = IC_{6z}; \mathcal{E}_9 = IC_{3z}; \mathcal{E}_{10} = IC_{2z}; \mathcal{E}_{11} = IC_{3z}^{-1}; \mathcal{E}_{12} = IC_{6z}^{-1}.$$

(b) The character table is given in Table D.14.

(11)  $D_6$ :

(a) Classes:

$$\mathcal{E}_1 = \mathbf{E}; \mathcal{E}_2 = C_{3z}, C_{3z}^{-1}; \mathcal{E}_3 = C_{2z}, C_{2A}, C_{2B}; \mathcal{E}_4 = C_{2z}; \mathcal{E}_5 = C_{6z}, C_{6z}^{-1};$$

$$\mathcal{E}_6 = C_{2y}, C_{2C}, C_{2D}.$$

(b) The character table is given in Table D.13.

(c) Matrices for irreducible representations of dimension greater than one, for any rotation  $C_{nj}$  of  $D_6$ :

$$\Gamma^6(C_{nj}) = \mathbf{D}''(C_{nj}); \Gamma^3(C_{nj}) = \mathbf{D}'(C_{nj});$$

where the matrices  $\mathbf{D}'(C_{nj})$  and  $\mathbf{D}''(C_{nj})$  are given in Tables D.6 and D.7 respectively.

	$\mathcal{E}_1$	$\mathcal{E}_2$	$\mathcal{E}_3$	$\mathcal{E}_4$	$\mathcal{E}_5$	$\mathcal{E}_6$	$\mathcal{E}_7$	$\mathcal{E}_8$	$\mathcal{E}_9$	$\mathcal{E}_{10}$	$\mathcal{E}_{11}$	$\mathcal{E}_{12}$
$\Gamma^1$	1	1	1	1	1	1	1	1	1	1	1	1
$\Gamma^2$	1	-1	1	-1	1	-1	1	-1	1	-1	1	-1
$\Gamma^3$	1	$\omega$	$\omega^2$	-1	$\omega$	$\omega^2$	1	$\omega$	$\omega^2$	-1	$\omega$	$\omega^2$
$\Gamma^4$	1	$\omega^2$	$\omega$	-1	$\omega^2$	$\omega$	1	$\omega^2$	$\omega$	-1	$\omega^2$	$\omega$
$\Gamma^5$	1	$\omega^2$	$\omega$	1	$\omega^2$	$\omega$	1	$\omega^2$	$\omega$	1	$\omega^2$	$\omega$
$\Gamma^6$	1	$\omega$	$\omega^2$	1	$\omega$	$\omega^2$	1	$\omega$	$\omega^2$	1	$\omega$	$\omega^2$
$\Gamma^7$	1	1	1	1	1	1	-1	-1	-1	-1	-1	-1
$\Gamma^8$	1	-1	1	-1	1	-1	1	-1	1	-1	1	-1
$\Gamma^9$	1	$\omega$	$\omega^2$	-1	$\omega$	$\omega^2$	-1	$\omega$	$\omega^2$	1	$\omega$	$\omega^2$
$\Gamma^{10}$	1	$\omega^2$	$\omega$	-1	$\omega^2$	$\omega$	-1	$\omega^2$	$\omega$	1	$\omega^2$	$\omega$
$\Gamma^{11}$	1	$\omega^2$	$\omega$	1	$\omega^2$	$\omega$	-1	$\omega^2$	$\omega$	-1	$\omega^2$	$\omega$
$\Gamma^{12}$	1	$\omega$	$\omega^2$	1	$\omega$	$\omega^2$	-1	$\omega$	$\omega^2$	-1	$\omega$	$\omega^2$

Table D.14 Character table for  $C_{6h}$  ( $\omega = \exp(\frac{1}{3}\pi i$ )).

(12) T:

(a) Classes:

$$\mathcal{E}_1 = E; \mathcal{E}_2 = C_{3x}, C_{3y}, C_{3z}; \mathcal{E}_3 = C_{3x}^{-1}, C_{3y}^{-1}, C_{3z}^{-1};$$

$$\mathcal{E}_4 = C_{2x}, C_{2y}, C_{2z};$$

(b) The character table is given in Table D.15.

(c) Matrices for irreducible representation of dimension greater than one, for any rotation  $C_{nj}$  of T:

$$\Gamma^4(C_{nj}) = \Gamma'(C_{nj});$$

where the matrices  $\Gamma'(C_{nj})$  are given in Table D.3.

(13)  $D_{2h}$  or  $V_h$ :

(a) Classes [for  $\mathcal{G}_0(\mathbf{k})$  of N]:

$$\mathcal{E}_1 = E; \mathcal{E}_2 = C_{2x}; \mathcal{E}_3 = C_{2z}; \mathcal{E}_4 = C_{2y}; \mathcal{E}_5 = I; \mathcal{E}_6 = IC_{2x};$$

$$\mathcal{E}_7 = IC_{2z}; \mathcal{E}_8 = IC_{2y};$$

(b) The character table is given in Table D.16.

	$\mathcal{E}_1$	$\mathcal{E}_2$	$\mathcal{E}_3$	$\mathcal{E}_4$
$\Gamma^1$	A	1	1	1
$\Gamma^2$	E	1	$\phi^2$	1
$\Gamma^3$		1	$\phi$	1
$\Gamma^4$	T	3	0	-1

Table D.15 Character table for T ( $\phi = \exp(\frac{1}{3}\pi i$ )).

	$\mathcal{E}_1$	$\mathcal{E}_2$	$\mathcal{E}_3$	$\mathcal{E}_4$	$\mathcal{E}_5$	$\mathcal{E}_6$	$\mathcal{E}_7$	$\mathcal{E}_8$
$\Gamma^1$	$A_{1g}$	1	1	1	1	1	1	1
$\Gamma^2$	$B_{1g}$	1	-1	1	-1	1	1	-1
$\Gamma^3$	$B_{2g}$	1	-1	-1	1	-1	-1	1
$\Gamma^4$	$B_{3g}$	1	1	-1	-1	1	-1	-1
$\Gamma^5$	$A_{1u}$	1	1	1	1	-1	-1	-1
$\Gamma^6$	$B_{1u}$	1	-1	1	-1	-1	-1	1
$\Gamma^7$	$B_{2u}$	1	-1	-1	1	-1	1	-1
$\Gamma^8$	$B_{3u}$	1	1	-1	-1	-1	1	1

Table D.16 Character table for  $D_{2h}$ .

(14)  $C_{4v}$ :

(a) Classes [for  $\mathcal{G}_0(\mathbf{k})$  of  $\Delta$ ]:

$$\mathcal{E}_1 = E; \mathcal{E}_2 = C_{2x}; \mathcal{E}_3 = C_{4z}, C_{4z}^{-1}; \mathcal{E}_4 = IC_{2x}, IC_{2y}; \mathcal{E}_5 = IC_{2xz}, IC_{2yz};$$

Classes [for  $\mathcal{G}_0(\mathbf{k})$  of T]:

$$\mathcal{E}_1 = E; \mathcal{E}_2 = C_{2x}; \mathcal{E}_3 = C_{4z}, C_{4z}^{-1}; \mathcal{E}_4 = IC_{2y}, IC_{2z}; \mathcal{E}_5 = IC_{2xz}, IC_{2yz};$$

(b) The character table is given in Table D.17.

(c) Matrices for irreducible representation of dimension greater than one, for any proper rotation  $C_{nj}$  of  $C_{4v}$ :

$$\Gamma^5(C_{nj}) = \mathbf{D}(C_{nj});$$

and for any improper rotation  $IC_{nj}$  of  $C_{4v}$ :

$$\Gamma^5(IC_{nj}) = -\mathbf{D}(C_{nj});$$

where for  $\mathcal{G}_0(\mathbf{k})$  of  $\Delta$  the matrices  $\mathbf{D}(C_{nj})$  are given in Table D.12, while for  $\mathcal{G}_0(\mathbf{k})$  of T they are given in Table D.11.

	$\mathcal{E}_1$	$\mathcal{E}_2$	$\mathcal{E}_3$	$\mathcal{E}_4$	$\mathcal{E}_5$
$\Gamma^1$	$A_1$	$\Delta_1, T_1$	$W_1$	1	1
$\Gamma^2$	$B_1$	$\Delta_2, T_2$	$W_2$	1	-1
$\Gamma^3$	$A_2$	$\Delta_1, T_1$	$W_2$	1	1
$\Gamma^4$	$B_2$	$\Delta_2, T_2$	$W_1$	1	-1
$\Gamma^5$	E	$\Delta_5, T_5$	$W_3$	2	-2

Table D.17 Character table for  $C_{4v}$ ,  $D_4$  and  $D_{2d}$ .

(15)  $D_4$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2z}; \mathcal{C}_3 = C_{4y}; \mathcal{C}_4 = C_{4x}^{-1}; \mathcal{C}_5 = C_{2xz}; \mathcal{C}_6 = C_{2z}; \mathcal{C}_7 = C_{2x}; \mathcal{C}_8 = C_{2y}.$$

(b) The character table is given in Table D.17.

(c) Matrices for irreducible representation of dimension greater than one, for any rotation  $C_{nj}$  of  $D_4$ :

$$\Gamma^5(C_{nj}) = S(C_{nj});$$

where the matrices  $S(C_{nj})$  are given in Table D.18.

(16)  $D_{2d}$  or  $V_d$ :

(a) Classes [for  $\mathcal{G}_0(\mathbf{k})$  of  $W$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2y}; \mathcal{C}_3 = IC_{4y}; \mathcal{C}_4 = IC_{4x}^{-1}; \mathcal{C}_5 = IC_{2xz}; \mathcal{C}_6 = IC_{2z}; \mathcal{C}_7 = C_{2z}; \mathcal{C}_8 = C_{2d}.$$

(b) The character table is given in Table D.17.

(c) Matrices for irreducible representation of dimension greater than one, for any proper rotation  $C_{nj}$  of  $D_{2d}$ :

$$\Gamma^5(C_{nj}) = S(C_{nj});$$

and for any improper rotation  $IC_{nj}$  of  $D_{2d}$ :

$$\Gamma^5(IC_{nj}) = -S(C_{nj});$$

where the matrices  $S(C_{nj})$  are given in Table D.18.

(17)  $C_{4h}$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{4z}; \mathcal{C}_3 = C_{2z}; \mathcal{C}_4 = C_{4x}^{-1}; \mathcal{C}_5 = I; \mathcal{C}_6 = IC_{4z}; \mathcal{C}_7 = IC_{2z}; \mathcal{C}_8 = IC_{4x}^{-1}.$$

(b) The character table is given in Table D.19.

$$\begin{aligned} S(E) &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, & S(C_{2z}) &= \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, & S(C_{2x}) &= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \\ S(C_{4d}) &= \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}, & S(C_{4y}) &= \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, & S(C_{4x}) &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \\ S(C_{2x}) &= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, & S(C_{2z}) &= \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}. \end{aligned}$$

Table D.18 The matrices  $S$  for  $D_4$  and  $D_{2d}$ .

	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$	$\mathcal{C}_4$	$\mathcal{C}_5$	$\mathcal{C}_6$	$\mathcal{C}_7$	$\mathcal{C}_8$
$\Gamma^1$	1	1	1	1	1	1	1	1
$\Gamma^2$	1	-1	1	-1	1	-1	1	-1
$\Gamma^3$	1	$i$	-1	- $i$	1	$i$	-1	- $i$
$\Gamma^4$	1	- $i$	-1	$i$	1	- $i$	-1	$i$
$\Gamma^5$	1	1	1	1	-1	-1	-1	-1
$\Gamma^6$	1	-1	1	-1	-1	1	-1	1
$\Gamma^7$	1	$i$	-1	- $i$	-1	$i$	1	- $i$
$\Gamma^8$	1	- $i$	-1	$i$	-1	- $i$	1	- $i$

Table D.19 Character table for  $C_{4h}$ .

(18)  $C_{3h}$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = IC_{6z}; \mathcal{C}_3 = C_{3z}; \mathcal{C}_4 = IC_{2z}; \mathcal{C}_5 = C_{3z}; \mathcal{C}_6 = IC_{6z}^{-1}.$$

(b) The character table is given in Table D.20.

	$C_{3h}$	$C_{3i}$	$C_6$	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$	$\mathcal{C}_4$	$\mathcal{C}_5$	$\mathcal{C}_6$
$\Gamma^1$	$A'$	$A_x$	A	1	1	1	1	1	1
$\Gamma^2$	$A''$	$A_u$	B	1	-1	1	-1	1	-1
$\Gamma^3$	$E'$	$E_u$	$E'$	1	$\omega$	$\omega^2$	-1	$-\omega$	$-\omega^2$
$\Gamma^4$				1	$-\omega^2$	$-\omega$	-1	$\omega^2$	$\omega$
$\Gamma^5$	$E'$	$E_g$	$E''$	1	$\omega^2$	$-\omega$	1	$\omega^2$	$-\omega$
$\Gamma^6$				1	$-\omega$	$\omega^2$	1	$-\omega$	$\omega^2$

Table D.20 Character table for  $C_{3h}$ ,  $C_{3i}$ , and  $C_6$  ( $\omega = \exp(\frac{2\pi i}{3})$ ).

(19)  $C_{3v}$ :

(a) Classes [for  $\mathcal{G}_0(\mathbf{k})$  of  $\Lambda$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{3z}; \mathcal{C}_3 = IC_{2b}; \mathcal{C}_4 = IC_{2d}; \mathcal{C}_5 = IC_{2f}.$$

Classes [for  $\mathcal{G}_0(\mathbf{k})$  of  $F$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{3xz}; \mathcal{C}_3 = IC_{2b}; \mathcal{C}_4 = IC_{2c}; \mathcal{C}_5 = IC_{2e}.$$

(b) The character table is given in Table D.21.

	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$
$\Gamma^1$	$A_1$	$F_1, \Lambda_1$	1
$\Gamma^2$	$A_2$	$F_2, \Lambda_2$	1
$\Gamma^3$	E	$F_3, \Lambda_3$	2

Table D.21 Character table for  $C_{3v}$  and  $D_3$ .



(c) Matrices for irreducible representation of dimension greater than one, for any proper rotation  $C_{nj}$  of  $C_{3v}$ :

$$\Gamma^3(C_{nj}) = \Gamma^v(C_{nj});$$

and for any improper rotation  $IC_{nj}$  of  $C_{3v}$ :

$$\Gamma^3(IC_{nj}) = \Gamma^w(C_{nj});$$

where the matrices  $\Gamma^v(C_{nj})$  are given in Table D.4.

(20)  $D_3$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{3z}, C_{3x}^{-1}; \mathcal{C}_3 = C_{2xz}, C_{2Ay}, C_{2Bz}.$$

(b) The character table is given in Table D.21.

(c) Matrices for irreducible representation of dimension greater than one, for any rotation  $C_{nj}$  of  $D_3$ :

$$\Gamma^3(C_{nj}) = \mathbf{D}^l(C_{nj});$$

where the matrices  $\mathbf{D}^l(C_{nj})$  are given in Table D.6.

(21)  $C_{3i}$  or  $S_6$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = IC_{3z}^{-1}; \mathcal{C}_3 = C_{3z}; \mathcal{C}_4 = I; \mathcal{C}_5 = C_{3z}^{-1}; \mathcal{C}_6 = IC_{3z}.$$

(b) The character table is given in Table D.20.

(22)  $C_6$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{6z}; \mathcal{C}_3 = C_{3z}; \mathcal{C}_4 = C_{2z}; \mathcal{C}_5 = C_{3z}^{-1}; \mathcal{C}_6 = C_{6z}^{-1}.$$

(b) The character table is given in Table D.20.

(23)  $C_{2v}$ :

(a) Classes [for  $\mathcal{G}_0(\mathbf{k})$  for  $\Sigma$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2z}; \mathcal{C}_3 = IC_{2x}; \mathcal{C}_4 = IC_{2y}.$$

Classes [for  $\mathcal{G}_0(\mathbf{k})$  for  $D$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2z}; \mathcal{C}_3 = IC_{2z}; \mathcal{C}_4 = IC_{2y}.$$

Classes [for  $\mathcal{G}_0(\mathbf{k})$  for  $S$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2z}; \mathcal{C}_3 = IC_{2z}; \mathcal{C}_4 = IC_{2y}.$$

$\Gamma^i$	$C_{2z}$	$C_{2y}$	$D_2$	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$	$\mathcal{C}_4$
$\Gamma^1$	$A_1$	$A_1$	$\Sigma_1$	$S_1$	$Z_1$	$G_1$	$D_1$
$\Gamma^2$	$A_2$	$A_2$	$\Sigma_2$	$S_2$	$Z_2$	$G_2$	$D_2$
$\Gamma^3$	$B_1$	$B_1$	$\Sigma_3$	$S_3$	$Z_3$	$G_3$	$D_3$
$\Gamma^4$	$B_2$	$B_2$	$\Sigma_4$	$S_4$	$Z_4$	$G_4$	$D_4$

Table D.22 Character table for  $C_{2v}$ ,  $C_{2h}$  and  $D_2$ .

Classes [for  $\mathcal{G}_0(\mathbf{k})$  for  $Z$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2y}; \mathcal{C}_3 = IC_{2z}; \mathcal{C}_4 = IC_{2x}.$$

Classes [for  $\mathcal{G}_0(\mathbf{k})$  for  $G$ ]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2y}; \mathcal{C}_3 = IC_{2z}; \mathcal{C}_4 = IC_{2x}.$$

(b) The character table is given in Table D.22.

(24)  $C_{2h}$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2z}; \mathcal{C}_3 = I; \mathcal{C}_4 = IC_{2z}.$$

(b) The character table is given in Table D.22.

(25)  $D_2$  or  $V$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2z}; \mathcal{C}_3 = C_{2y}; \mathcal{C}_4 = C_{2x}.$$

(b) The character table is given in Table D.22.

(26)  $C_4$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{4z}; \mathcal{C}_3 = C_{2z}; \mathcal{C}_4 = C_{4z}^{-1}.$$

(b) The character table is given in Table D.23.

(27)  $S_4$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = IC_{4y}; \mathcal{C}_3 = C_{2z}; \mathcal{C}_4 = IC_{4y}^{-1}.$$

(b) The character table is given in Table D.23.

	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$	$\mathcal{C}_4$
$\Gamma^1$	1	1	1	1
$\Gamma^2$	1	-1	1	-1
$\Gamma^3$	1	$i$	-1	- $i$
$\Gamma^4$	1	- $i$	-1	$i$

Table D.23 Character table for  $C_4$  and  $S_4$ .

(28)  $C_3$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{3z}; \mathcal{C}_3 = C_{3z}^{-1}.$$

(b) The character table is given in Table D.24.

	$\mathcal{C}_1$	$\mathcal{C}_2$	$\mathcal{C}_3$
$\Gamma^1$	1	1	1
$\Gamma^2$	1	$\phi$	$\phi^2$
$\Gamma^3$	1	$\phi^2$	$\phi$

Table D.24 Character table for  $C_3$  ( $\phi = \exp(\frac{2}{3}\pi i$ )).

(29)  $C_8$  or  $C_{1h}$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = IC_{2z}.$$

(b) The character table is given in Table D.25.

	$C_s$	$C_2$	$C_i$	$\mathcal{C}_1$	$\mathcal{C}_2$
$\Gamma^1$	A'	A	$A_g$	$Q_t$	1
$\Gamma^2$	$A''$	B	$A_u$	$Q_2$	-1

Table D.25 Character table for  $C_s$ ,  $C_2$  and  $C_i$ .

(30)  $C_2$ :

(a) Classes [for  $\mathcal{C}_0(\mathbf{k})$  of Q]:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = C_{2d}.$$

(b) The character table is given in Table D.25.

(31)  $C_1$  or  $S_2$ :

(a) Classes:

$$\mathcal{C}_1 = E; \mathcal{C}_2 = I.$$

(b) The character table is given in Table D.25

(32)  $C_1$ :

(a) This group consists of E alone.

(b)  $\chi(E) = 1$ .