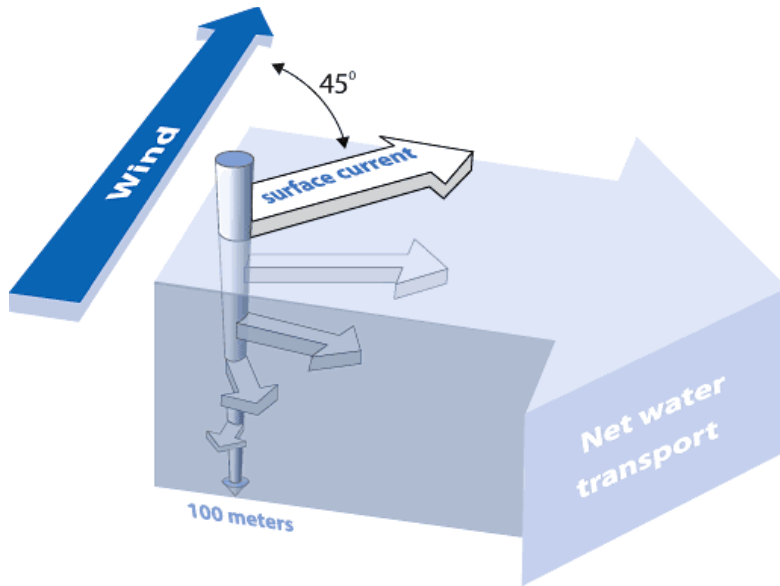




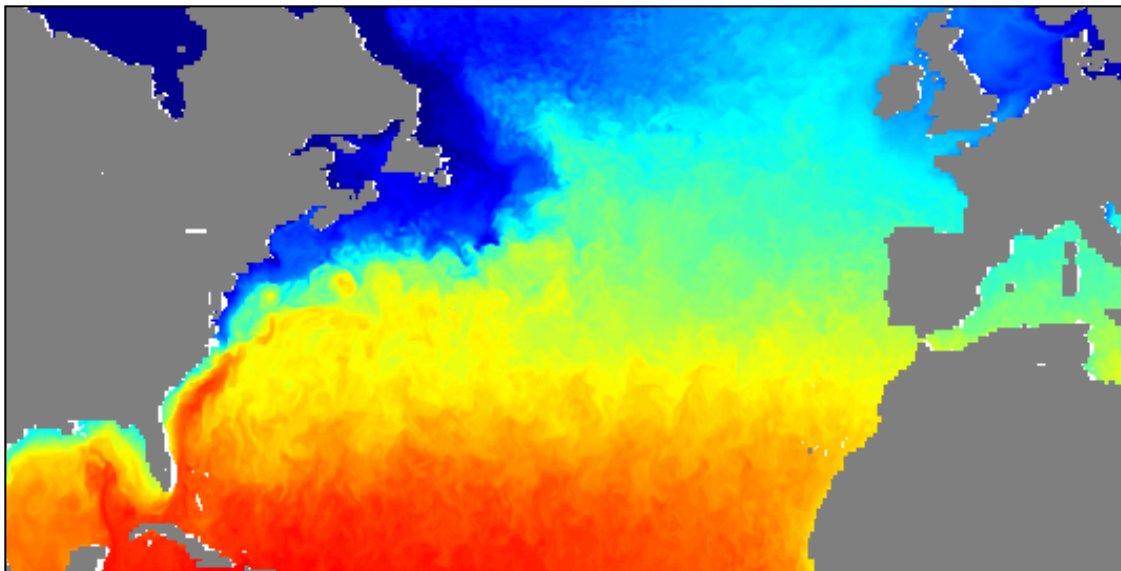
Ρεύματα παρουσία τριβής – ανεμογενής κυκλοφορία



6. Wind driven circulation

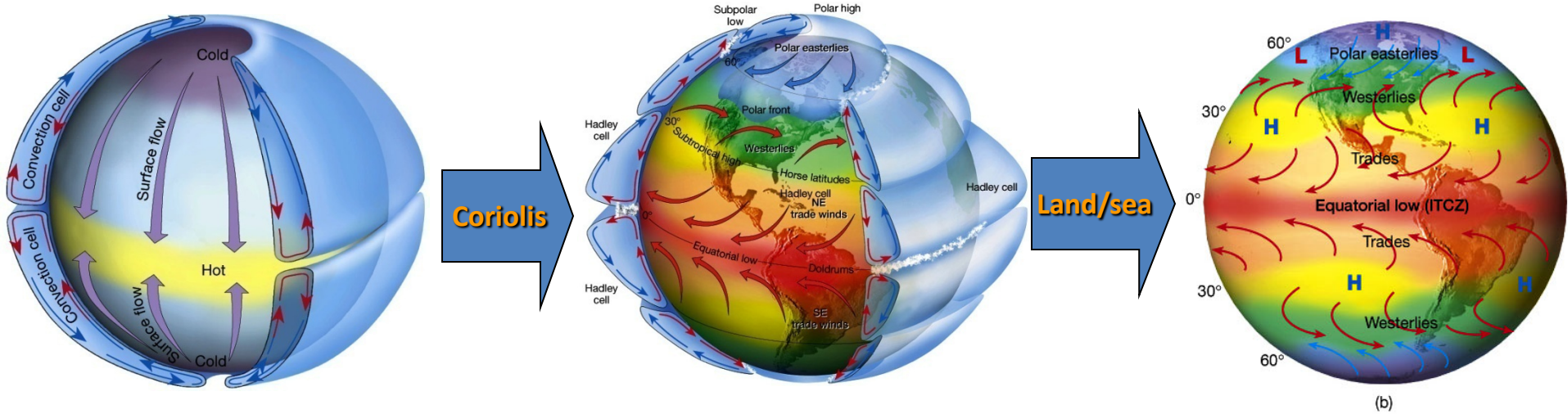
Sarantis Sofianos

Dept. of Physics, University of Athens

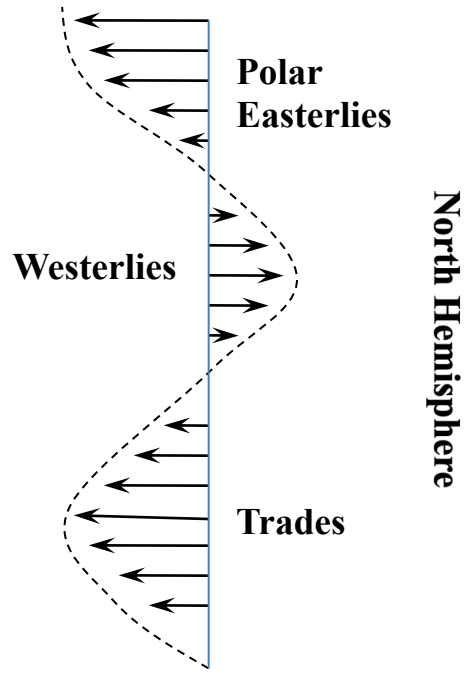
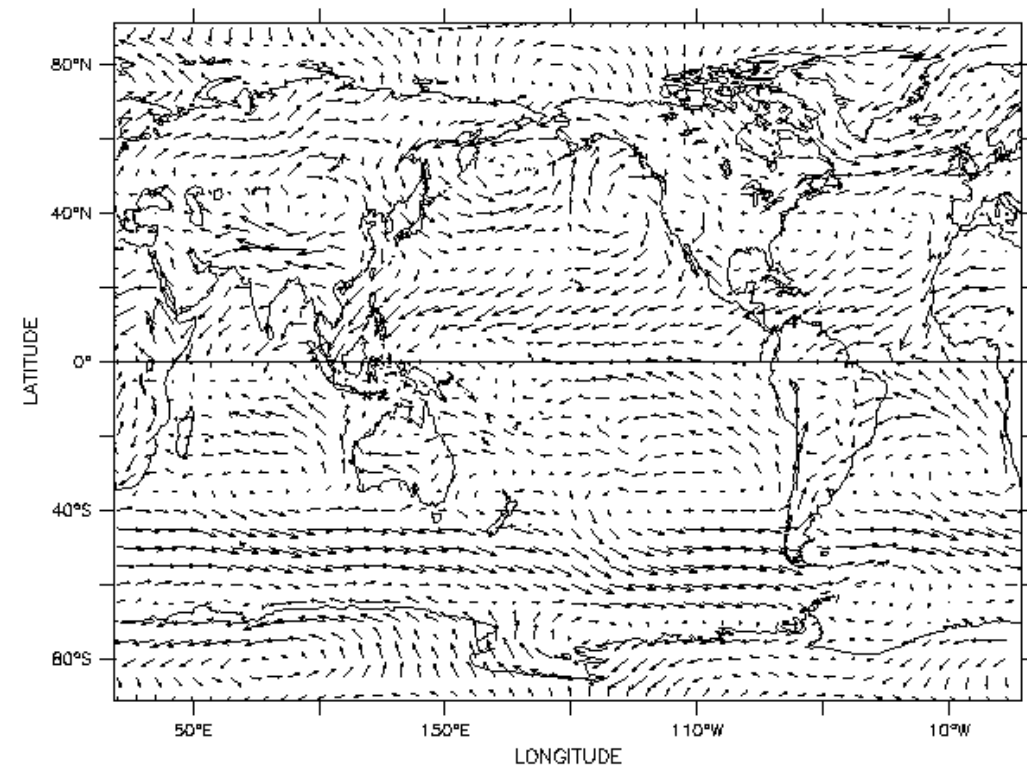


- Ekman Theory
- Sverdrup theory for the wind-driven circulation
- Stommel and Munk theory of the western boundary intensification

Global atmospheric circulation



(b)



Wind stress on the sea

$$\vec{\tau} = c_D \rho_a |u_{10}| \vec{u}_{10}$$

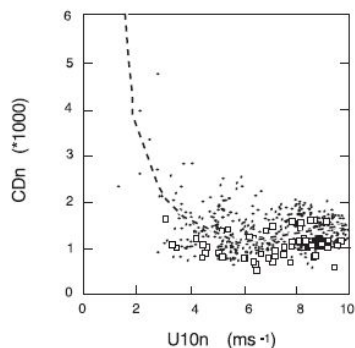
where:

ρ_a air density (1.3 kg/m^3)

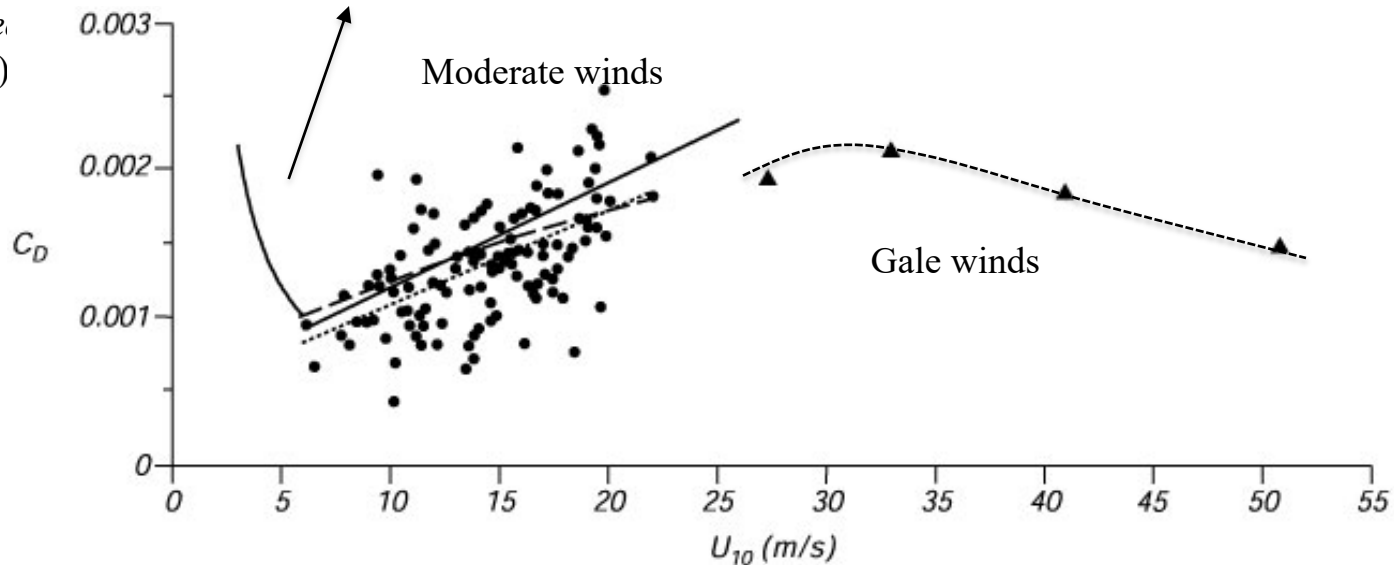
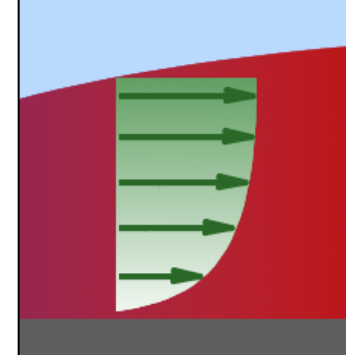
u_{10} wind speed at 10 m (m/sec)

c_D drag coefficient (unitless)

Measurements showed that c_D is related to the wind speed (not a constant). Nevertheless, we usually use a constant value for simplicity.



Weak winds



Examples of c_D used:

$$c_D = 1.4 \times 10^{-3}$$

$$c_D = 1.1 \times 10^{-3} \text{ ασθενείς άνεμοι}$$

$$c_D = (0.61 + 0.063u) \times 10^{-3} \text{ ισχυροί άνεμοι}$$

$$c_D = (0.29 + 3.1u_{10}^{-1} + 7.7u_{10}^{-2}) 10^{-3}$$

for $3 \text{ m/sec} \leq u_{10} \leq 6 \text{ m/sec}$

$$c_D = (0.60 + 0.070u_{10}) 10^{-3}$$

for $6 \text{ m/sec} \leq u_{10} \leq 26 \text{ m/sec}$

and many more ...

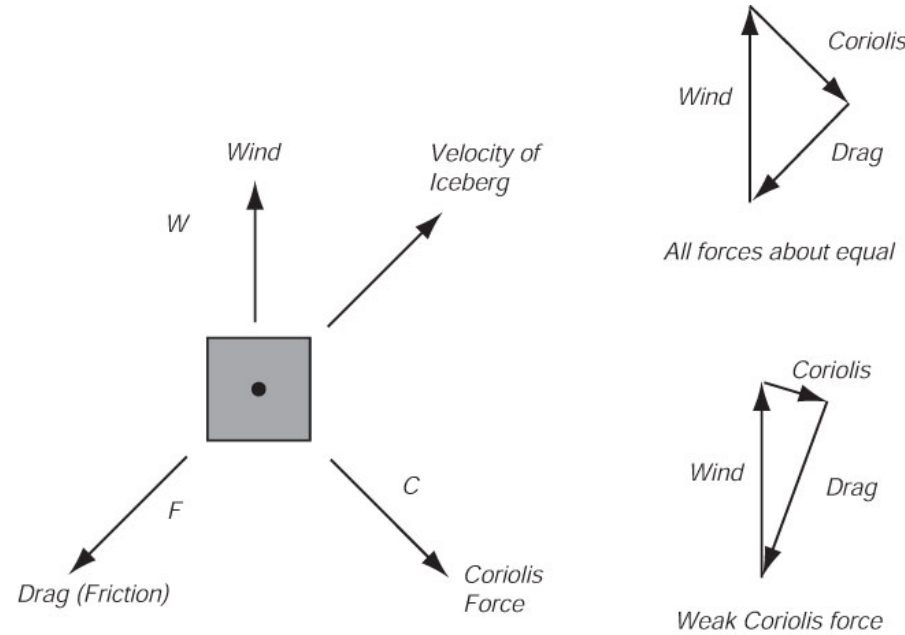
Evolution of wind-driven circulation theory:

<i>Fridtjof Nansen</i>	(1898)	Qualitative theory, currents transport water at an angle to the wind.
<i>Vagn Walfrid Ekman</i>	(1902)	Quantitative theory for wind-driven transport at the sea surface.
<i>Harald Sverdrup</i>	(1947)	Theory for wind-driven circulation in the eastern Pacific.
<i>Henry Stommel</i>	(1948)	Theory for westward intensification of wind-driven circulation (western boundary currents).
<i>Walter Munk</i>	(1950)	Quantitative theory for main features of the wind-driven circulation
<i>Kirk Bryan</i>	(1963)	Numerical models of the oceanic circulation.

The surface wind effect (Nansen theory):



Based on observations of iceberg movements
 $W + F + C = 0$



Working Equations

x (u):

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial x} + fv + A_H \frac{\partial^2 u}{\partial x^2} + A_H \frac{\partial^2 u}{\partial y^2} + A_V \frac{\partial^2 u}{\partial z^2}$$

y (v):

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial y} - fu + A_H \frac{\partial^2 v}{\partial x^2} + A_H \frac{\partial^2 v}{\partial y^2} + A_V \frac{\partial^2 v}{\partial z^2}$$

z (w):

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial z} - g + A_H \frac{\partial^2 w}{\partial x^2} + A_H \frac{\partial^2 w}{\partial y^2} + A_V \frac{\partial^2 w}{\partial z^2}$$

***Continuity equation
(Boussinesq approximation):***

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Ekman Theory

$$R_o = \frac{U}{fL} \ll 1$$

$$E_k = \frac{\text{Viscosity Terms}}{\text{Coriolis Term}} = A_H \frac{U}{L^2} \frac{1}{fU} = \frac{A_H}{fL^2} \left(\frac{A_V}{fH^2} \right) \sim 1$$

Assuming that H is the thickness of the layer affected by the wind (through friction) and \ll of the total depth of the ocean

$$A_H \nabla_H^2 \vec{u} \ll A_V \frac{\partial^2 \vec{u}}{\partial z^2}$$

The Navier-Stokes equation (horizontal) become:

$$\left. \begin{aligned} -fv &= -\frac{1}{\rho} \frac{\partial P}{\partial x} + A_V \frac{\partial^2 u}{\partial z^2} \\ fu &= -\frac{1}{\rho} \frac{\partial P}{\partial y} + A_V \frac{\partial^2 v}{\partial z^2} \end{aligned} \right\} \text{(A)}$$

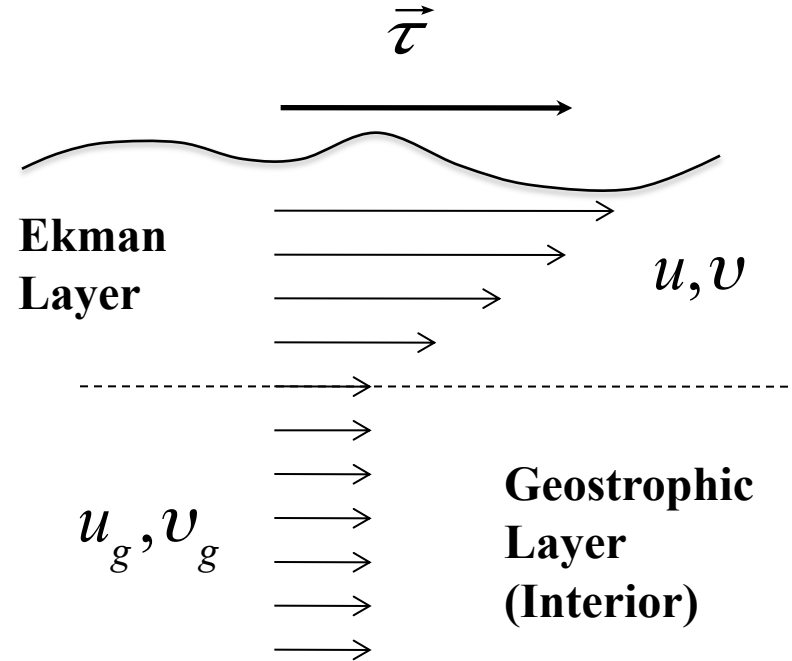
The geostrophic approximation still holds:

$$\left. \begin{aligned} -fv_g &= -\frac{1}{\rho} \frac{\partial P}{\partial x} \\ fu_g &= -\frac{1}{\rho} \frac{\partial P}{\partial y} \end{aligned} \right\} \text{(B)}$$

$$\text{(A) - (B)}$$

$$\begin{aligned} -f(v - v_g) &= A_V \frac{\partial^2 u}{\partial z^2} \\ f(u - u_g) &= A_V \frac{\partial^2 v}{\partial z^2} \end{aligned}$$

Ekman Equations



$$\left. \begin{aligned} -f(v - v_g) &= A_v \frac{\partial^2 u}{\partial z^2} \quad (1) \\ f(u - u_g) &= A_v \frac{\partial^2 v}{\partial z^2} \quad (2) \end{aligned} \right\}$$

Boundary conditions:

For simplicity, only zonal wind

$$\left\{ \begin{aligned} \text{at } z = 0 &\mapsto \rho A_v \frac{\partial u}{\partial z} = \tau^x; \rho A_v \frac{\partial v}{\partial z} = 0 \\ \text{at } z \rightarrow -\infty &\mapsto u = u_g; v = v_g \end{aligned} \right.$$

Multiplying (2) by $i = \sqrt{-1}$ and adding (1):

$$\frac{d^2 V}{dz^2} - \frac{if}{A_v} V = 0 \quad (3) \quad \text{where } V \equiv u - u_g + i(v - v_g)$$

remember u_g, v_g not $\propto z$

The solution is: $V = Ae^{(1+i)z/\delta} + Be^{-(1+i)z/\delta}$

$$\text{where } \delta = \sqrt{\frac{2A_v}{f}}$$

$B=0$, since the solution can not become infinite with z becoming $-\infty$

Using the two surface boundary conditions:

$$A = \frac{\tau^x \delta (1-i)}{2\rho A_v}$$

Substituting in (3):

$$\begin{aligned} u - u_g + i(v - v_g) &= \frac{\tau\delta(1-i)}{2\rho A_v} e^{\frac{(1+i)z}{\delta}} = (1-i) \frac{\tau/\rho}{\sqrt{fA_v}} \frac{\sqrt{2}}{2} e^{\frac{z}{\delta}} \left(\cos \frac{z}{\delta} + i \sin \frac{z}{\delta} \right) = \\ &= \frac{\tau/\rho}{\sqrt{fA_v}} e^{\frac{z}{\delta}} \left(\frac{\sqrt{2}}{2} \cos \frac{z}{\delta} + \frac{\sqrt{2}}{2} \sin \frac{z}{\delta} \right) - i \frac{\tau/\rho}{\sqrt{fA_v}} e^{\frac{z}{\delta}} \left(\frac{\sqrt{2}}{2} \cos \frac{z}{\delta} - \frac{\sqrt{2}}{2} \sin \frac{z}{\delta} \right) \Rightarrow \end{aligned}$$

$$\boxed{\begin{aligned} u &= u_g + \frac{\tau^x/\rho}{\sqrt{fA_v}} e^{z/\delta} \cos\left(-\frac{z}{\delta} + \frac{\pi}{4}\right) \\ v &= v_g - \frac{\tau^x/\rho}{\sqrt{fA_v}} e^{z/\delta} \sin\left(-\frac{z}{\delta} + \frac{\pi}{4}\right) \end{aligned}}$$

$$\begin{aligned} \cos \frac{\pi}{4} \cos \frac{z}{\delta} + \sin \frac{\pi}{4} \sin \frac{z}{\delta} &= \cos\left(-\frac{z}{\delta} + \frac{\pi}{4}\right) & \sin \frac{\pi}{4} \cos \frac{z}{\delta} - \cos \frac{\pi}{4} \sin \frac{z}{\delta} &= \cos\left(-\frac{z}{\delta} + \frac{\pi}{4}\right) \end{aligned}$$

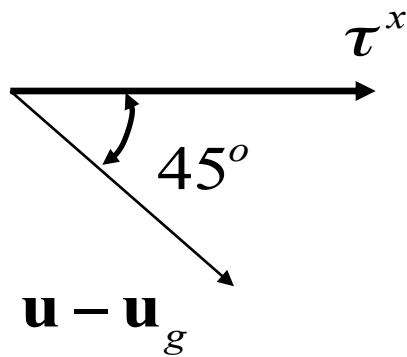
$$u = u_g + \frac{\tau^x / \rho}{\sqrt{fA_v}} e^{z/\delta} \cos\left(-\frac{z}{\delta} + \frac{\pi}{4}\right) \quad v = v_g - \frac{\tau^x / \rho}{\sqrt{fA_v}} e^{z/\delta} \sin\left(-\frac{z}{\delta} + \frac{\pi}{4}\right)$$

II. Surface Ekman velocity:

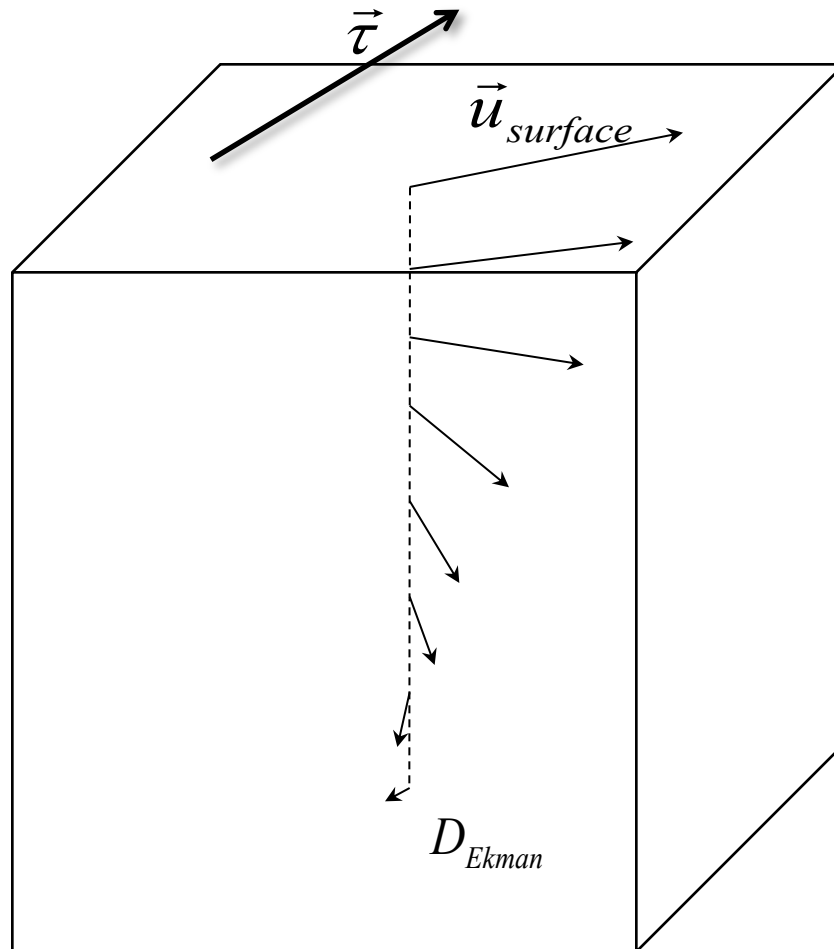
at $z = 0$

$$u_{surface} = u_g + \frac{\tau^x / \rho}{\sqrt{fA_v}} \cos\left(\frac{\pi}{4}\right)$$

$$v_{surface} = v_g - \frac{\tau^x / \rho}{\sqrt{fA_v}} \sin\left(\frac{\pi}{4}\right)$$



II. Vertical distribution of Ekman solution:



Ekman Spiral

The depth of the layer (**Ekman layer**) is defined as the depth where velocity is decreased by e (e-folding scale)

$$\delta = \sqrt{\frac{2A_v}{f}}$$

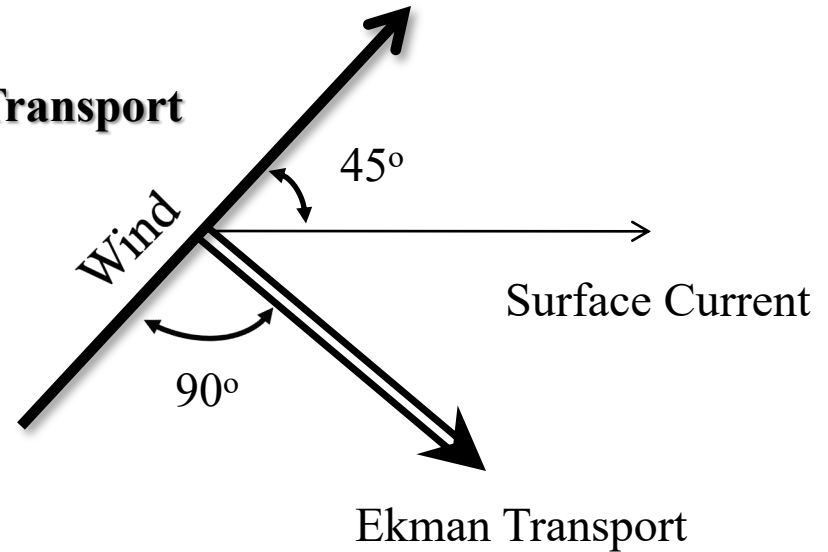
III. The vertically integrated Ekman transport:

Integrating the ocean velocity due to the direct effect of the wind ($\mathbf{u} - \mathbf{u}_g$) from the interior to the ocean surface:

$$U = \int_{-\infty}^0 (u - u_g) dz = \frac{1}{\rho f} \tau^y$$

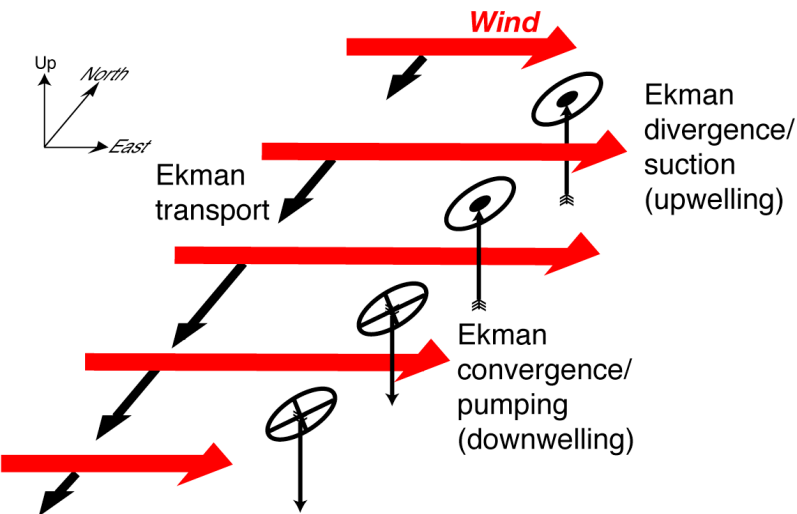
$$V = \int_{-\infty}^0 (v - v_g) dz = -\frac{1}{\rho f} \tau^x$$

Ekman Transport

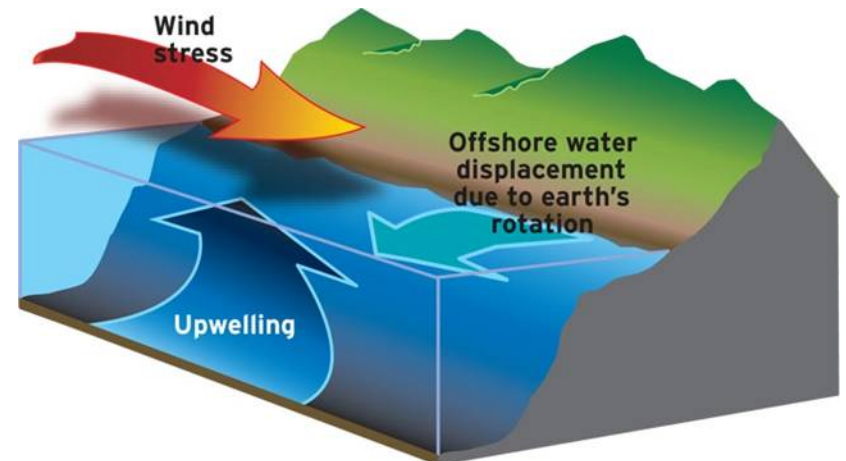


Consequences:

Open sea upwelling/downwelling



Coastal upwelling



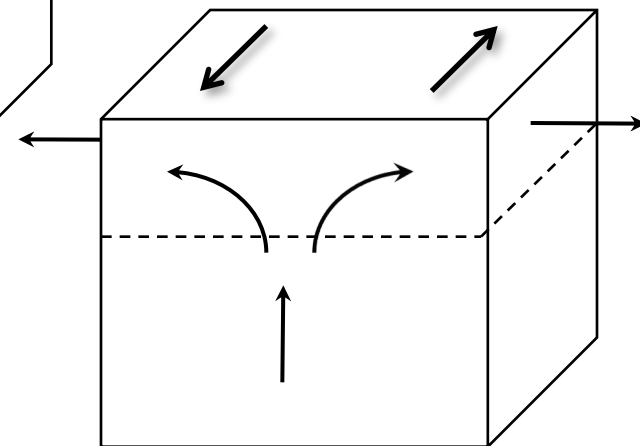
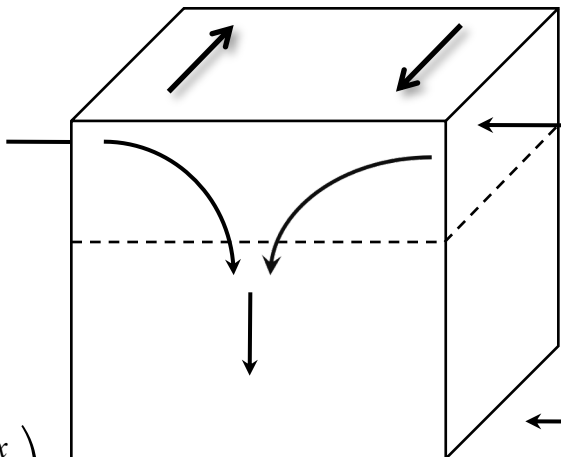
IV. Ekman pumping

From continuity: $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$

$$-\int_{\delta}^0 dw = \int_{\delta}^0 \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) dz$$

$$\Rightarrow -w(o) + w(\delta) = \frac{1}{\rho f} \underbrace{\left(\frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y} \right)}$$

Wind Stress Curl



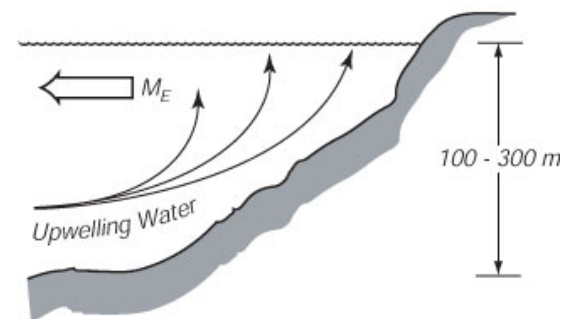
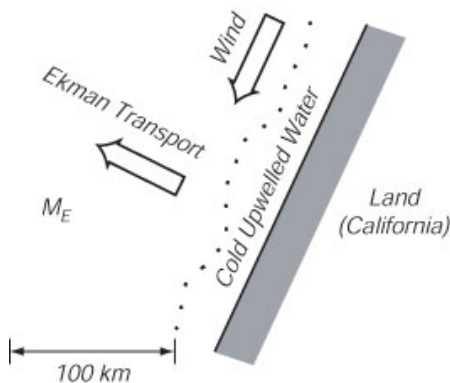
At the bottom of the Ekman layer:

$$w(\delta) = \frac{1}{\rho f} \left(\frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y} \right)$$

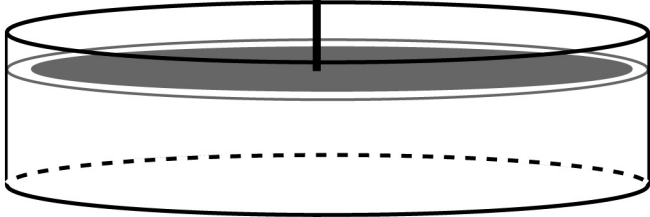
Coastal Ekman pumping

$$w(\delta) = \frac{U}{L} = \frac{\tau^y}{L\rho f}$$

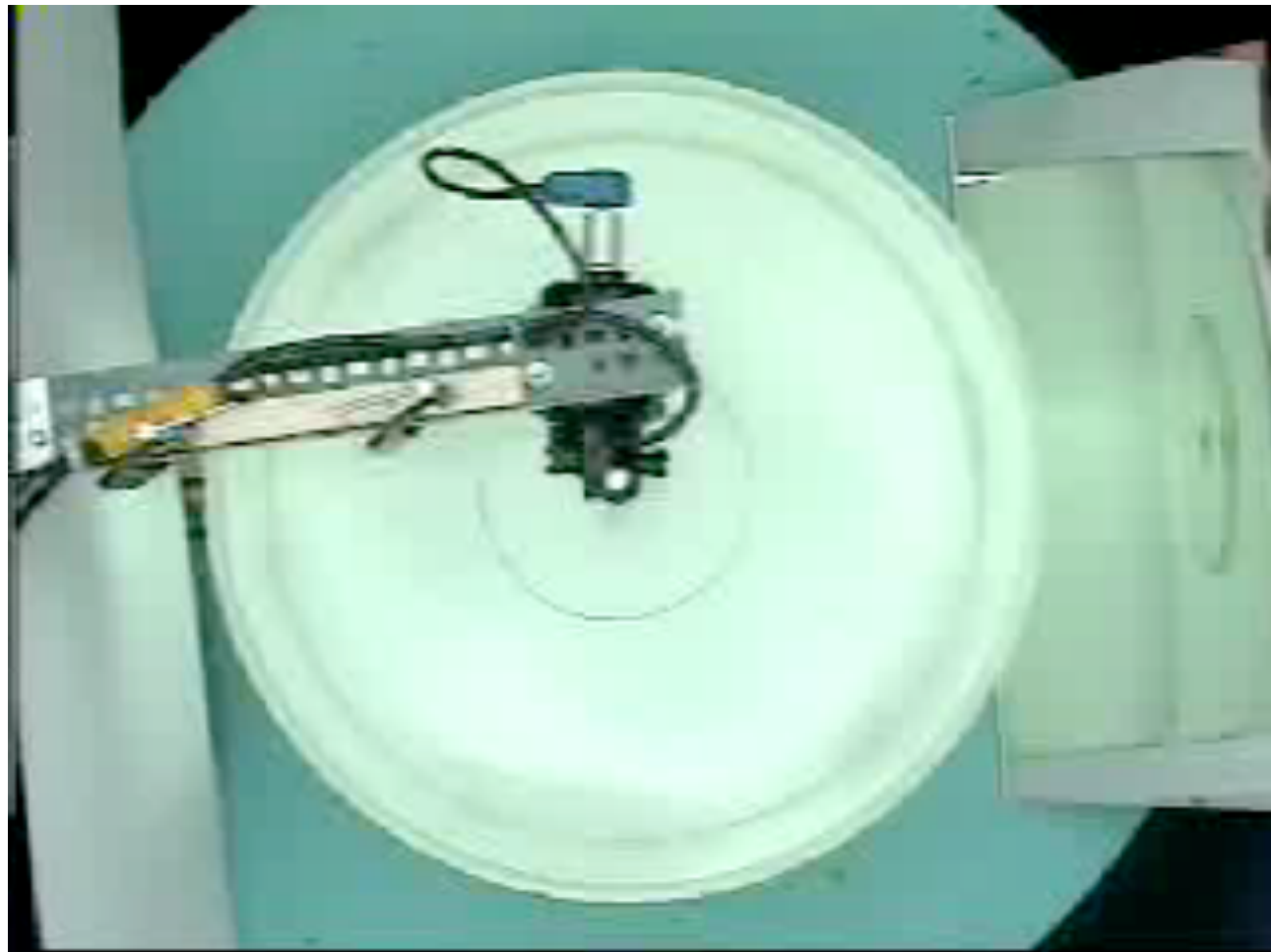
We can not define the derivative along the coastal zone



Lid rotation rate $\Omega + \omega$



Tank rotation rate Ω



Sverdrup theory for the wind-driven circulation

Starting from the same equations of motion (with friction):

$$\left. \begin{aligned} -fv &= -\frac{1}{\rho} \frac{\partial P}{\partial x} + A_v \frac{\partial^2 u}{\partial z^2} & (1) \\ fu &= -\frac{1}{\rho} \frac{\partial P}{\partial y} + A_v \frac{\partial^2 v}{\partial z^2} & (2) \end{aligned} \right\} \frac{\partial}{\partial x}(2) - \frac{\partial}{\partial y}(1)$$

$$u \cancel{\frac{\partial f}{\partial x}} + f \frac{\partial u}{\partial x} + v \left(\frac{\partial f}{\partial y} \right) + f \frac{\partial v}{\partial y} = -\cancel{\frac{1}{\rho} \frac{\partial^2 P}{\partial x \partial y}} + \cancel{\frac{1}{\rho} \frac{\partial^2 P}{\partial x \partial y}} + \frac{1}{\rho} \frac{\partial^3 v}{\partial x \partial z^2} - \frac{1}{\rho} \frac{\partial^3 u}{\partial y \partial z^2}$$

β

$$f \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \beta v = \frac{1}{\rho} \frac{\partial}{\partial z^2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

Integrating from the bottom ($-H$) to the sea surface:

$$\rho f \int_{-H}^0 \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) dz + \beta \int_{-H}^0 \rho v dz = \int_{-H}^0 \left(\frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y} \right) dz$$

since at $z = 0 \mapsto \rho A_v \frac{\partial u}{\partial z} = \tau^x$;
 $\rho A_v \frac{\partial v}{\partial z} = \tau^y$

Using continuity and the fact that $w(0) = w(-H) = 0$

Meridional mass transport M_y

Wind stress curl

$$\beta M_y = \frac{\partial \tau^y}{\partial x} - \frac{\partial \tau^x}{\partial y} = \text{wind - stress curl}$$

Depth integrated Vorticity equation for the wind-driven circulation

$$\frac{\partial \tau^y}{\partial x} \rightarrow 0 \quad (\tau^y = 0)$$

The meridional Sverdrup transport

$$M_y = -\frac{1}{\beta} \frac{\partial \tau^x}{\partial y}$$

Zonal velocity vanishes at one boundary. Selection according to vorticity conservation

$$\Delta(f + \zeta) + \zeta_\tau = 0$$

Eastern boundary:

$\Delta f \downarrow$; ζ must be +; balanced by $\zeta_\tau -$

Western boundary:

$\Delta f \uparrow$; ζ must be -; does not balanced by $\zeta_\tau -$

We need another vorticity term

β - effect

Polar
Easterlies

Westerlies

Trades

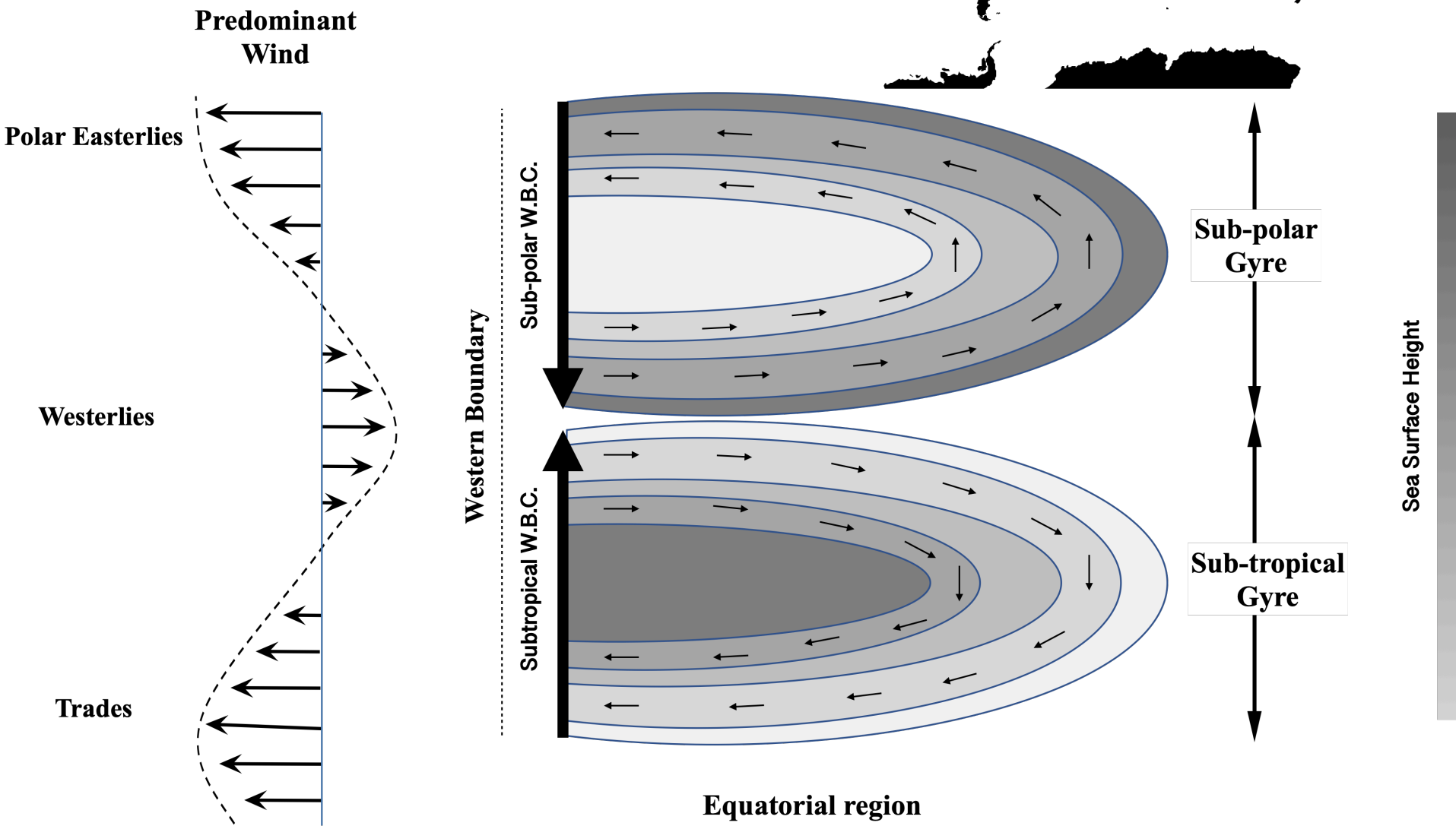
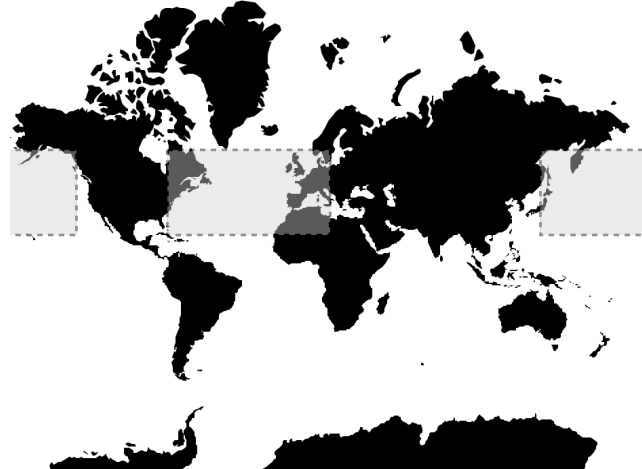
x_{East}

The zonal Sverdrup transport

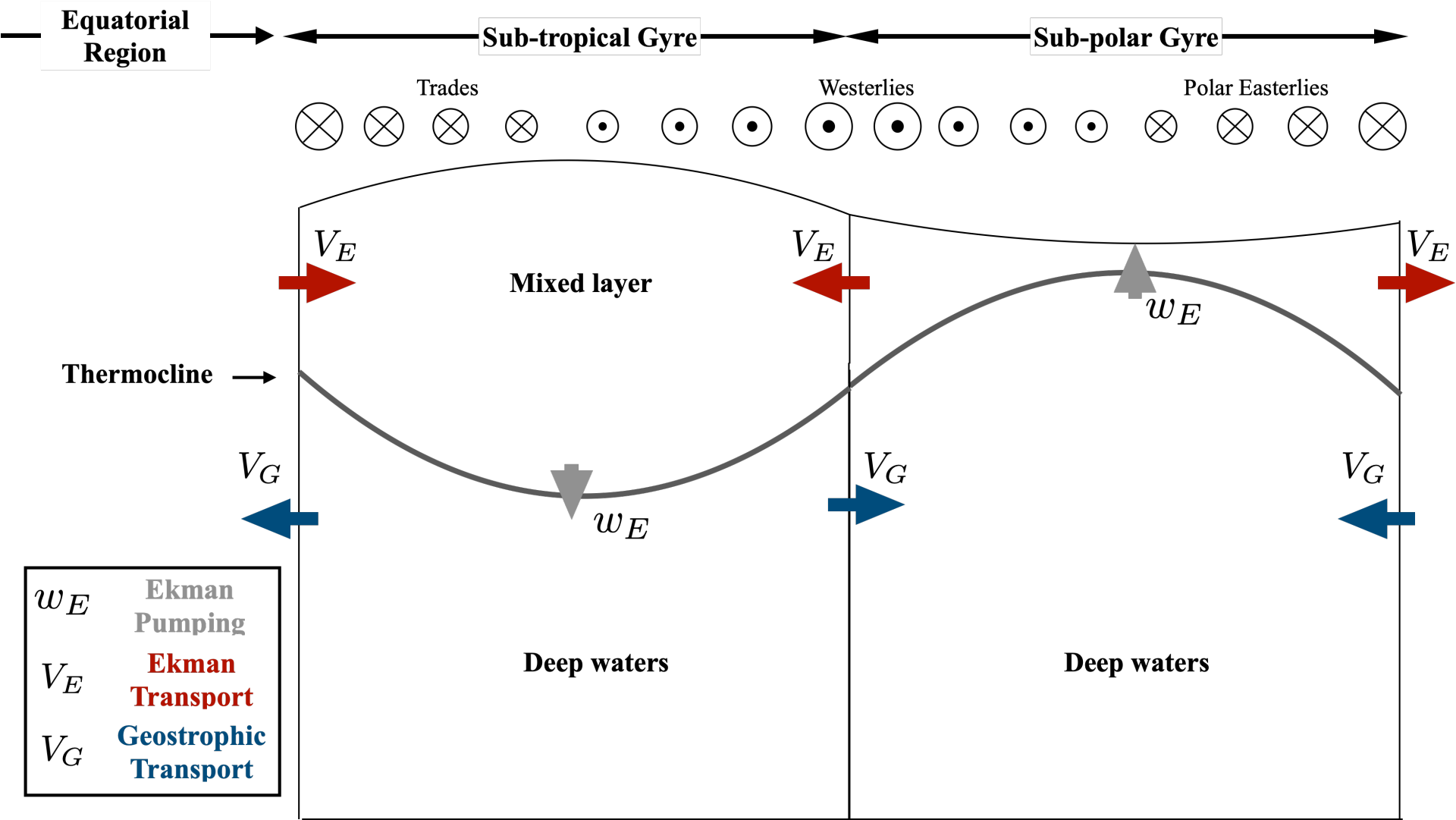
Using the depth integrated continuity equation

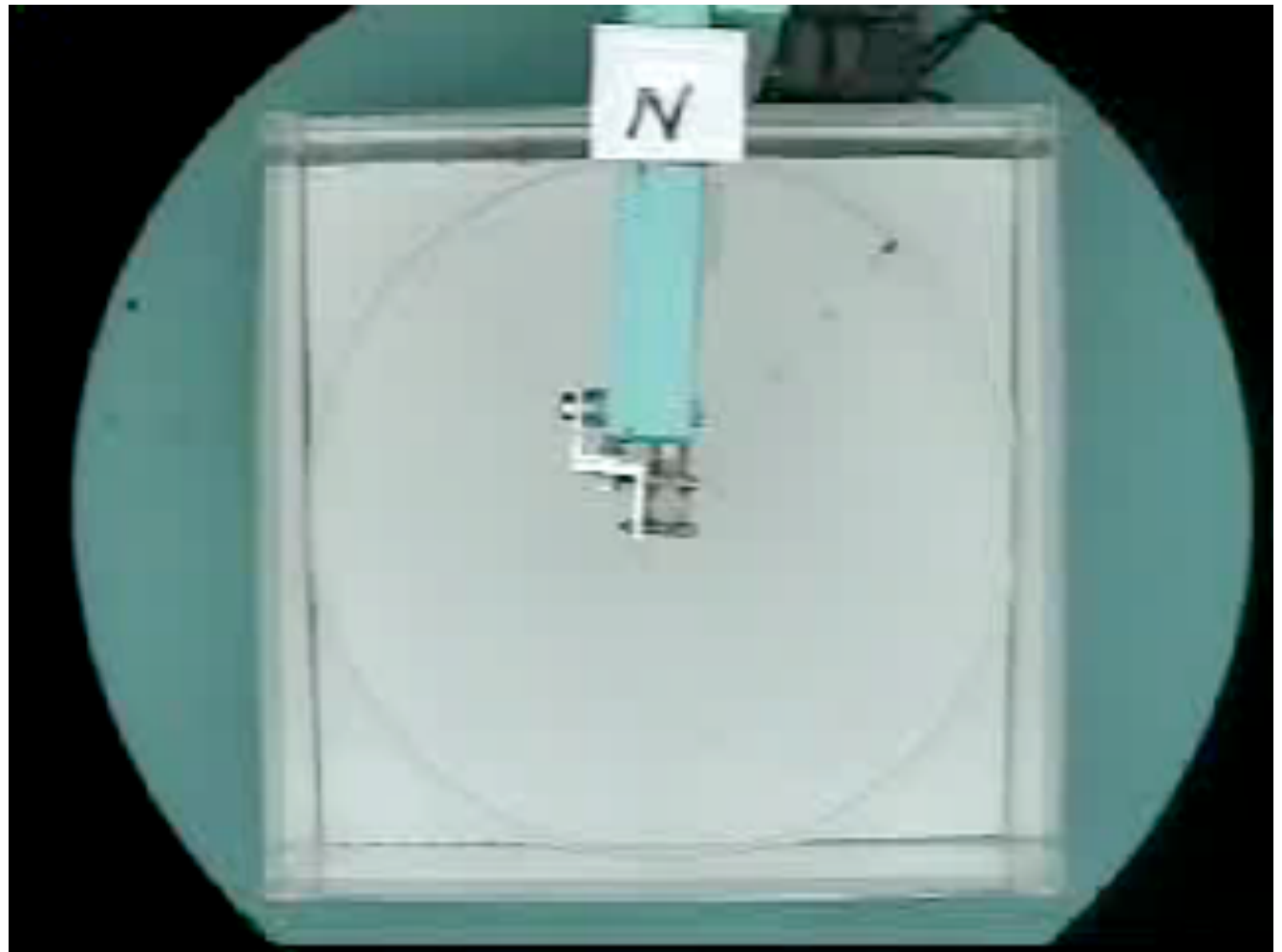
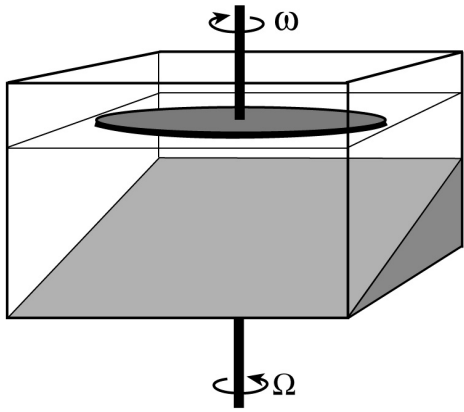
$$M_x(x) = \frac{\partial}{\partial y} \int_x^{x_{East}} M_y dx = -\frac{1}{\beta} \frac{\partial^2 \tau^x}{\partial y^2} (x_{East} - x)$$

A top view of the wind-driven gyres



A side view of the wind-driven gyres





Why is there a **Western Boundary Current**?

Ekman's (and Sverdrup's) scaling is failing at the western boundary:

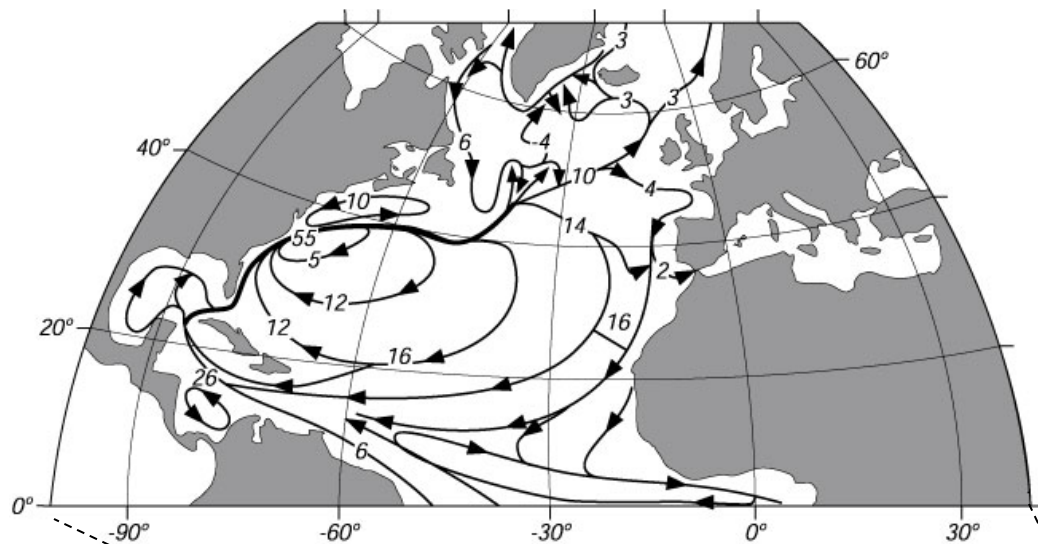
$\frac{\partial \tau^x}{\partial y}$ is very small at the boundaries (weak and irregular winds) \rightarrow L is now much smaller than the open ocean $O(100 \text{ km})$ \rightarrow $Ek_H = \frac{A_H}{fL^2} \sim 1$ horizontal friction/dissipation dominates

Stommel proposed a more general vorticity equation (including the western boundary region) that can be applied to the interior (Sverdrup) and the western limit of ocean. There is a dissipation term $-R\zeta$

Interior $\beta U + \frac{\partial \tau^x}{\partial y} = 0$ $\beta U - R\zeta + \frac{\partial \tau^x}{\partial y} = 0$ **WBL** $\beta U - R\zeta = 0$

Munk followed Stommel's approach but the dissipation term is more complicated and appropriate for the ocean dynamics, of the form: $A_H \nabla^2 \zeta$

Interior $\beta U + \frac{\partial \tau^x}{\partial y} = 0$ $\beta U - A_H \nabla^2 \zeta + \frac{\partial \tau^x}{\partial y} = 0$ **WBL** $\beta U - A_H \nabla^2 \zeta = 0$



Stommel Model:

$$R\zeta \approx \beta U$$

$$\Rightarrow R \frac{U}{L} \approx \beta U$$

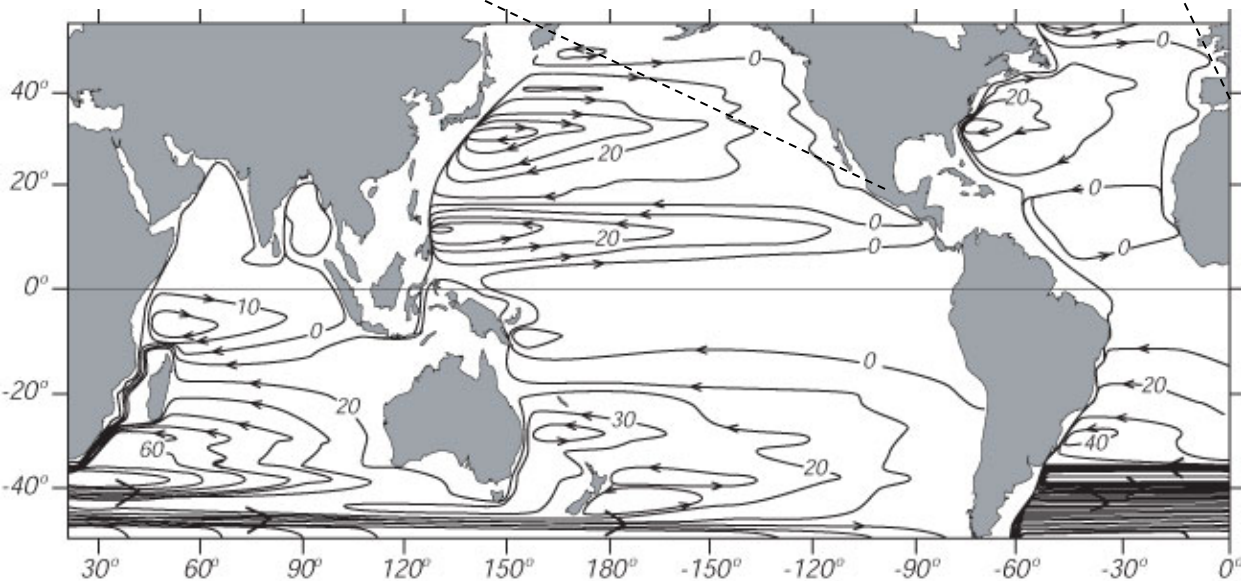
$$\Rightarrow L = O\left(\frac{R}{\beta}\right)$$

Munk Model:

$$A_H \nabla^2 \zeta \approx \beta U$$

$$\Rightarrow A_H \frac{U}{L^3} \approx \beta U$$

$$\Rightarrow L = O\left(\sqrt[3]{\frac{A_H}{\beta}}\right)$$



We can estimate L
or R/A_H .

