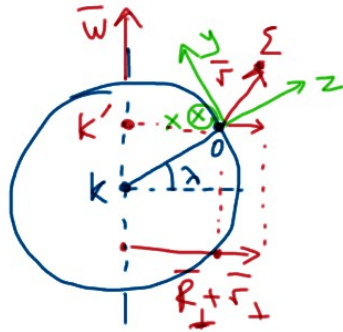
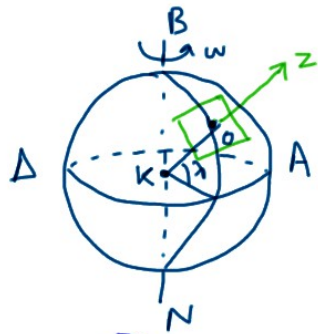


# Κίνηση σώματος κοντά στην επιφάνεια της Γης



$$m\bar{\alpha}_G = \bar{B} + \bar{F}_{\text{αίσθησης}} - m\bar{\alpha}_0 - m\bar{\omega} \times (\bar{\omega} \times \bar{r}) - 2m\bar{\omega} \times \bar{v}_G - m\dot{\bar{\omega}} \times \bar{r}$$

βάρος  $\bar{B} = -\frac{GMm}{|\bar{K}\Sigma|^3} \bar{K}\Sigma = -\frac{GMm}{|\bar{K}O + \bar{r}|^3} (\bar{K}O + \bar{r}) \approx -\frac{GMm}{R^2} \hat{z}$

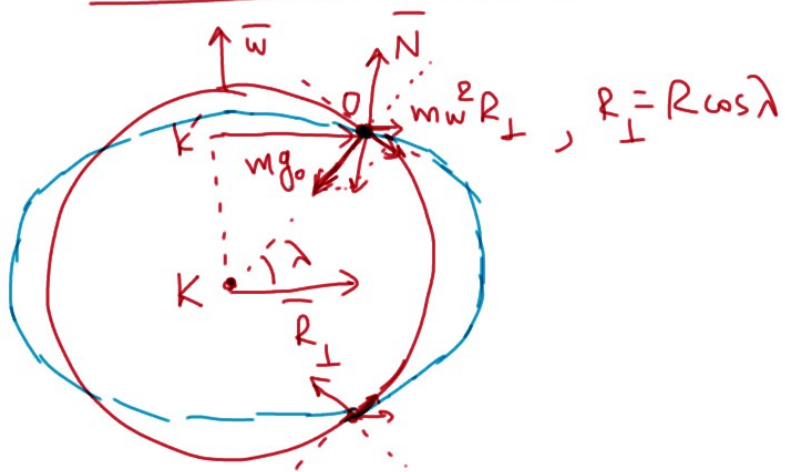
$$\bar{B} = m\bar{g}_0 \quad \text{for } \bar{g}_0 \approx -\frac{GM}{R^2} \hat{z}$$

$$-m\bar{\alpha}_0 = -m(-\omega^2 \bar{k}'O) = m\omega^2 \bar{r}_\perp \quad (\text{εξ } O \text{ κινείται κυκλικά με } \omega, \bar{r}_\perp = \bar{k}'O = R \cos \lambda)$$

$$-m\bar{\omega} \times (\bar{\omega} \times \bar{r}) = m\omega^2 \bar{r}_\perp \quad \text{αφ'εξής με σχέση με την } -m\bar{\alpha}_0 = m\omega^2 \bar{r}_\perp$$

$$\bar{B} - m\bar{\alpha}_0 + m\bar{\omega} \times (\bar{\omega} \times \bar{r}) \approx m(\bar{g}_0 + \omega^2 \bar{r}_\perp) = m\bar{g}_{\text{eff}} \quad \text{Άρα } \boxed{m\bar{\alpha}_G = m\bar{g}_{\text{eff}} - 2m\bar{\omega} \times \bar{v}_G + \bar{F}_{\text{αίσθησης}}}$$

Σχήμα της Γης:



Στο σώμα με κέντρο το K που περιστρέφεται,

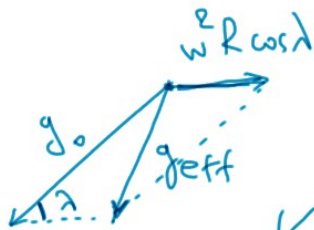
$$m\bar{\alpha}_G = m\bar{g}_0 - m\dot{\bar{\alpha}}_0 + m\omega^2 \bar{R}_\perp - 2m\bar{\omega} \times \bar{v}_G$$

$$- m\dot{\bar{\omega}} \times \bar{r} + \bar{N}$$

$$-\bar{N} = m(\bar{g}_0 + \omega^2 \bar{R}_\perp) = m \underline{\underline{\bar{g}_{eff}}}$$

$$\frac{m\omega^2 R_\perp}{mg_0} = \frac{\left(\frac{2\pi}{1 \text{ day}}\right)^2 \cdot 6400 \text{ km} \cos\lambda}{9,81 \text{ m/s}^2} = \underline{\underline{3 \cdot 10^{-3} \cos\lambda}}$$

η επιφάνεια σε κάθε τόπο είναι κάθετη στο  $\bar{g}_{eff}$ .

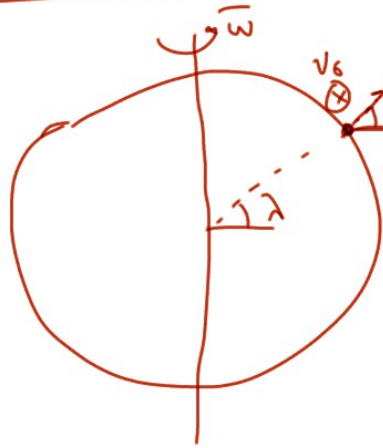


$$g_{eff} = \sqrt{g_0^2 + (\omega^2 R \cos\lambda)^2 - 2g_0 \omega^2 R \cos\lambda}$$

(όπου αν  $g_{eff} = \sqrt{(g_0 + \omega^2 R_\perp)^2}$ )

$$m\bar{\alpha}_G = m \underset{\substack{\uparrow \\ \text{eff}}}{\bar{g}} - 2m\bar{\omega} \times \bar{v}_G + \bar{F}_{αλλες}$$

# Eötvös effect:



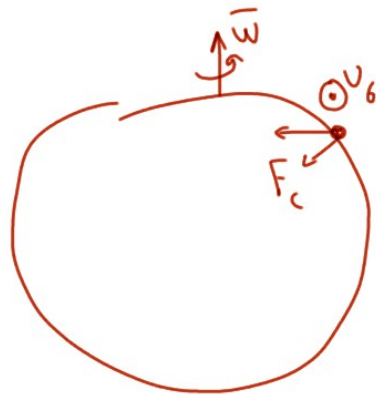
η σφαίρα κινείται προς άνω

$$\vec{F}_c = -2m\vec{\omega} \times \vec{v}_6$$

$$m\vec{a}_6 = m\vec{g} + \vec{F}_c + \vec{N}$$

$$-\vec{N} = m\vec{g} + \vec{F}_c$$

από "μικρότερο" βάρος

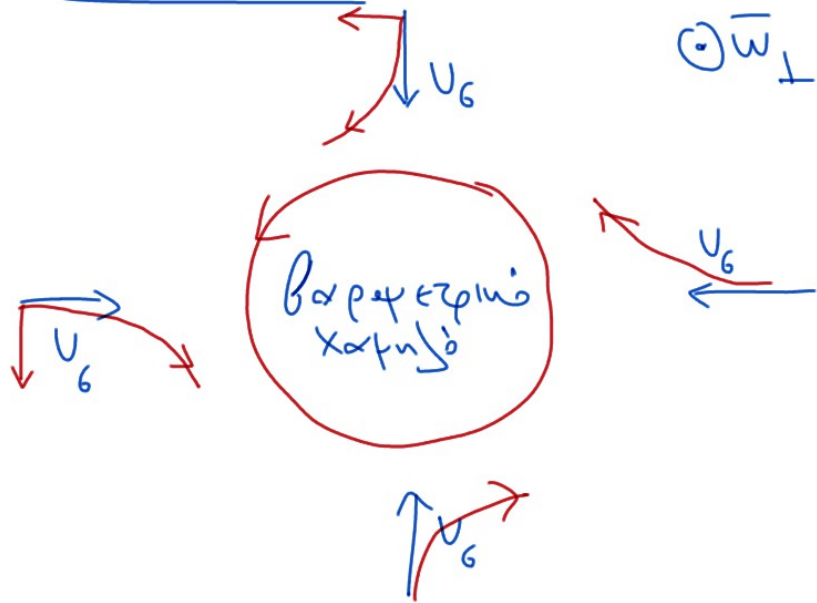


Αν η σφαίρα κινείται προς κάτω

"μεγαλύτερο" βάρος.

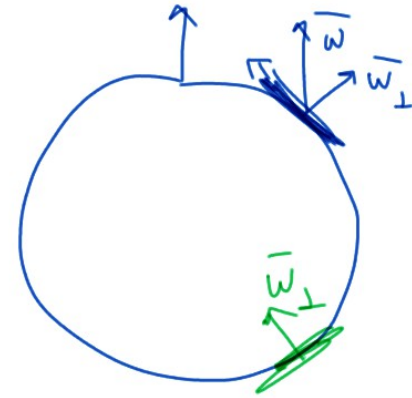
$$\frac{F_{c\perp}}{mg} = \frac{2m\omega v_6 \cos\lambda}{mg} = 4 \cdot 10^{-4} \left( \frac{v_6}{100 \frac{\text{km}}{\text{h}}} \right) \cos\lambda$$

Κυκλιωτής :



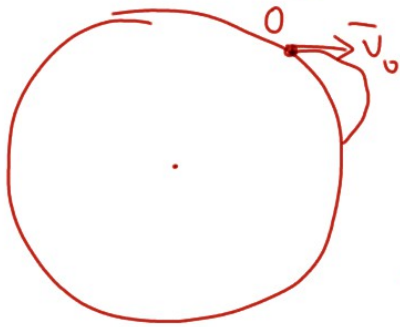
Στο βέπτιο υφιστάριο

$$\ominus \bar{\omega}_\perp$$



$$- 2 m \bar{\omega}_\perp \times U_6$$

Πλάγια βολή σε ένα τόνο  $O$  της ηφελιοσφαιρικής Γης:



$$m \bar{\alpha}_6 = m \bar{g}_{\text{eff}} - 2m \bar{\omega} \times \bar{v}_6 + \cancel{F_{\text{αλλες}}}$$

ή αντιστοίχα  $\bar{\alpha} = \bar{g} - 2 \bar{\omega} \times \bar{v} \quad (*)$

Διαχωρίζουμε :  $\bar{r} = \bar{r}^{(0)} + \bar{r}^{(1)}$  ,  $\bar{v} = \bar{v}^{(0)} + \bar{v}^{(1)}$   
δράση του  $\omega$   $\dot{\bar{r}}^{(0)}$   $\dot{\bar{r}}^{(1)}$

$$\bar{\alpha} = \underbrace{\bar{\alpha}^{(0)}}_{\dot{\bar{v}}^{(0)}} + \underbrace{\bar{\alpha}^{(1)}}_{\dot{\bar{v}}^{(1)}}$$

Σε μηδενική τάση :  $(*) \rightarrow \bar{\alpha}^{(0)} = \bar{g} \Leftrightarrow \bar{v}^{(0)} = \bar{v}_0 + \bar{g} t \Leftrightarrow \bar{r}^{(0)} = \bar{r}_0 + \bar{v}_0 t + \frac{\bar{g} t^2}{2}$

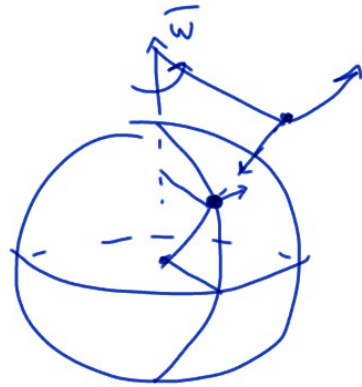
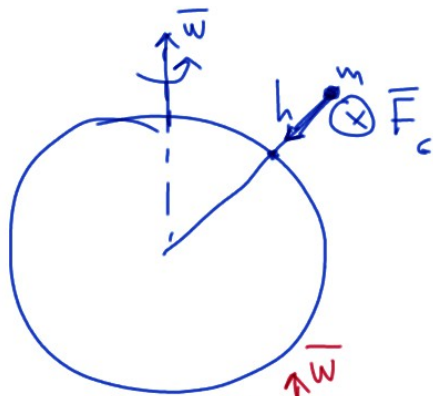
Σε 1<sup>η</sup> τάση :  $(*) \rightarrow \bar{\alpha}^{(0)} + \bar{\alpha}^{(1)} = \bar{g} - 2 \bar{\omega} \times (\bar{v}^{(0)} + \bar{v}^{(1)}) \Leftrightarrow$

$$\Leftrightarrow \dot{\bar{v}}^{(1)} = -2 \bar{\omega} \times (\bar{v}_0 + \bar{g} t) \Leftrightarrow \bar{v}^{(1)} = -2 \bar{\omega} \times (\bar{v}_0 t + \frac{\bar{g} t^2}{2}) + \cancel{\bar{v}^{(1)}|_{t=0}} \quad \text{ώστε } \dot{\bar{v}}^{(1)}|_{t=0} = 0$$

$$\Leftrightarrow \bar{r}^{(1)} = -2 \bar{\omega} \times \left( \bar{v}_0 \frac{t^2}{2} + \frac{\bar{g} t^3}{6} \right) + \cancel{\bar{r}^{(1)}|_{t=0}} \quad \text{ώστε } \bar{r}^{(1)}|_{t=0} = 0$$

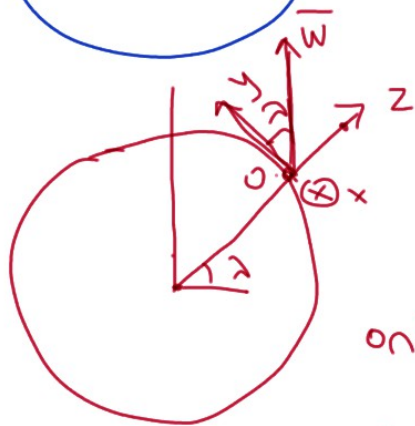
Δηλ.  $\bar{r} = \bar{r}_0 + \bar{v}_0 t + \frac{\bar{g} t^2}{2} - \bar{\omega} \times \bar{v}_0 t^2 - \underbrace{\bar{\omega} \times \bar{g} \frac{t^3}{3}}_{\text{Από άραξη}}$

Παράδειγμα: Σώμα αρχικά ακίνητο σε ύψος  $h$ .



$$\bar{\alpha} = \bar{g} - \omega \times \bar{v}$$

Αντίστοιχο προς αναζήτι



$$\bar{\omega} = \omega \cos \lambda \hat{y} + \omega \sin \lambda \hat{z}$$

$$\bar{r}_0 = h \hat{z}, \quad \bar{v}_0 = 0, \quad \bar{g} = -g \hat{z}$$

οπότε

$$\bar{r} = \bar{r}_0 + \bar{v}_0 t + \frac{\bar{g} t^2}{2} - \bar{\omega} \times \bar{v}_0 t^2 - \bar{\omega} \times \bar{g} \frac{t^3}{3}$$

$$\Leftrightarrow \begin{cases} x = \omega \cos \lambda \frac{g t^3}{3} \\ y = 0 \\ z = h - \frac{g t^2}{2} \end{cases}$$

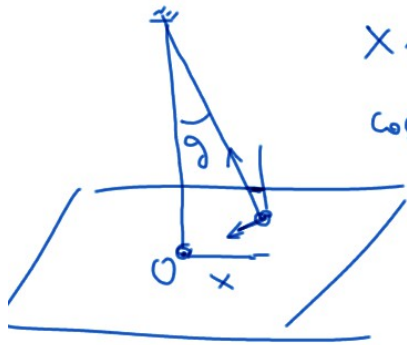
$$\text{Όταν το σώμα πέσει } z=0 \Leftrightarrow t = \sqrt{\frac{2h}{g}}$$

$$\text{max } x = \omega \cos \lambda \frac{g}{3} \left( \frac{2h}{g} \right)^{3/2}$$

$$\text{Αν π.χ. } h = 125 \text{ m, } t = 5 \text{ s, } x = 2.92 \cos \lambda \text{ cm}$$

$$\text{Για Αθήνα } \lambda = 38^\circ \quad x = 2.3 \text{ cm}$$

# Εκκρετής του Φουκώ :



$$x \approx R\theta$$

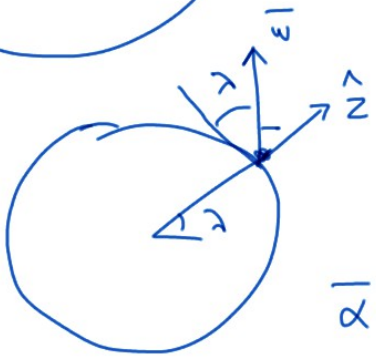
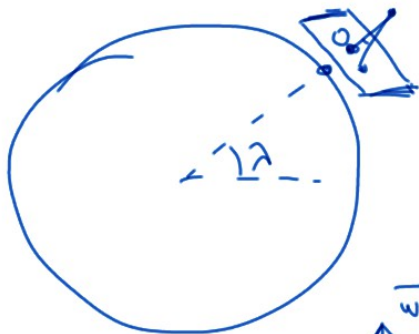
$$\cos\theta \approx 1 - \frac{\theta^2}{2} \approx 1$$

ισοδύναμο με σφίβραση ελατήριου με

Δύναμη ελαστικότητας  $-mg \sin\theta \approx -\frac{mg}{R} x$

$$\vec{F}_{ελ} = -\frac{mg}{R} \vec{r}$$

αποκρίσεων από Θ.Ι.



Δυνάμεις  $m\vec{g}$ ,  $\vec{T}$ ,  $-2m\vec{\omega} \times \vec{v}$ ,  $-\left(\frac{mg}{R}\right)\vec{r} \rightarrow \vec{k}$

Προβολές τους στα xy επίπεδα :

$$m\vec{a} = -k\vec{r} - 2m\vec{\omega} \times \vec{v} \quad \text{με} \quad k = \frac{mg}{R}$$

$$\vec{\omega}_{\perp} = \omega \sin\lambda \hat{z}$$

Σε πολικές  $\vec{r} = r \hat{\theta}$ ,  $\vec{v} = \dot{\theta} \hat{\theta} + \dot{\phi} \hat{\phi}$

$$\vec{a} = (\ddot{\theta} - \dot{\phi}^2) \hat{\theta} + \frac{1}{r} \frac{d}{dt} (\dot{\theta}^2 \hat{\phi}) \hat{\phi}, \quad \vec{\omega}_{\perp} \times \vec{v} = \begin{vmatrix} \hat{\theta} & \hat{\phi} & \hat{z} \\ 0 & 0 & \omega \sin\lambda \\ \dot{\theta} & \dot{\phi} & 0 \end{vmatrix} =$$

$$= -\dot{\phi} \omega \sin\lambda \hat{\theta} + \dot{\theta} \omega \sin\lambda \hat{\phi}$$

$$\hat{\omega}: \ddot{\omega} - \omega \dot{\varphi}^2 = -\frac{g}{R} \omega + 2\omega \sin \lambda \dot{\omega} \dot{\varphi} \quad (1)$$

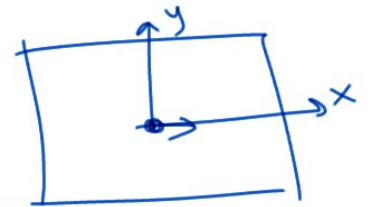
$$\hat{\varphi}: \frac{1}{\omega} \frac{d}{dt} (\omega^2 \dot{\varphi}) = -2\omega \sin \lambda \dot{\omega} \quad (2)$$

$$(2) \rightarrow \frac{d}{dt} (\omega^2 \dot{\varphi}) = -2\omega \sin \lambda \underbrace{\omega \dot{\omega}}_{\frac{d}{dt}(\omega^2/2)} \Leftrightarrow \boxed{\omega^2 (\dot{\varphi} + \omega \sin \lambda) = l = \text{const}} \quad (2')$$

(1)  $\xrightarrow{\text{α γρήγορο } \dot{\varphi}}$   $\ddot{\omega} + \left( \frac{g}{R} + \underbrace{\omega^2 \sin^2 \lambda}_{\text{α γρήγορο}} \right) \omega = \frac{l^2}{\omega^3} \quad (1')$

(ισοδυναμία με διατήρηση ενέργειας  $\frac{m\dot{\omega}^2}{2} + \frac{m\omega^2 \dot{\varphi}^2}{2} + \frac{1}{2}k\omega^2 = \text{const}$ )

Έστω αρχικά  $\omega = 0$ ,  $\dot{\omega} = v_0$  με  $\vec{v} = v_0 \hat{x}$  (δnl.  $\varphi = 0$ )



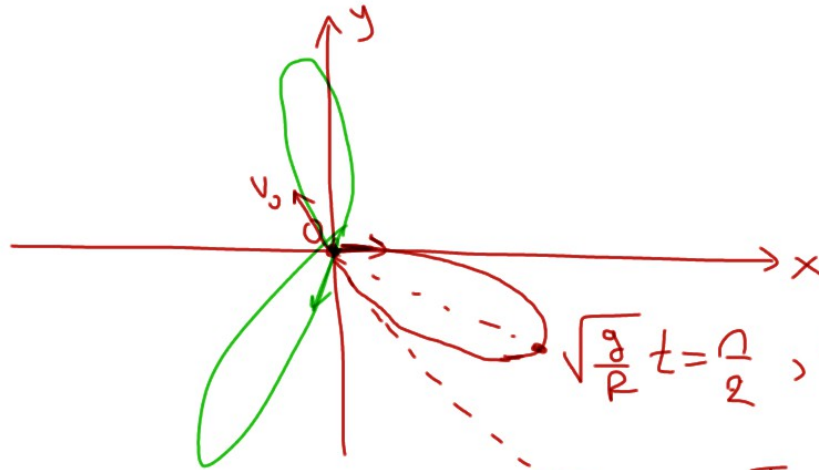
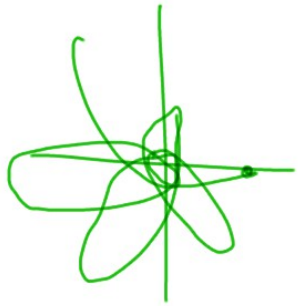
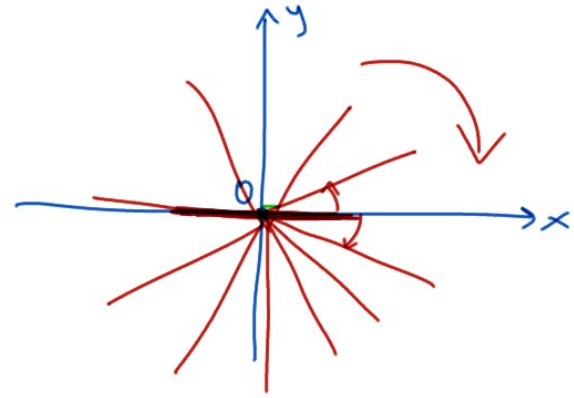
Τότε (2)'  $\rightarrow l = 0$  δnl.  $\dot{\varphi} = -\omega \sin \lambda \Leftrightarrow \boxed{\varphi = -\omega t \sin \lambda}$

και (1)'  $\rightarrow \omega = C_1 \cos\left(\sqrt{\frac{g}{R}} t\right) + C_2 \sin\left(\sqrt{\frac{g}{R}} t\right)$  με  $C_1 = 0, C_2 = v_0 \sqrt{\frac{R}{g}}$   
 δnl.  $\omega = v_0 \sqrt{\frac{R}{g}} \sin\left(\sqrt{\frac{g}{R}} t\right)$



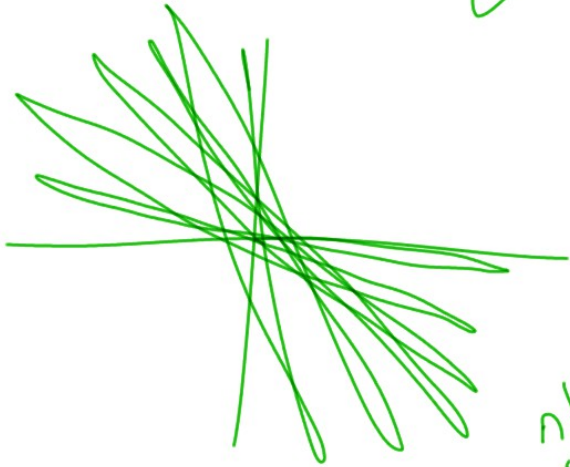
$$\theta = v_0 \sqrt{\frac{R}{g}} \sin\left(\sqrt{\frac{g}{R}} t\right)$$

$$\varphi = -\omega t \sin\lambda$$



$$\sqrt{\frac{g}{R}} t = \frac{\pi}{2} \Rightarrow t = \frac{T}{4} \Rightarrow T = 2\pi \sqrt{R/g}$$

$$\varphi = -\omega \frac{T}{2} \sin\lambda$$



Μια ημίγειρα περιελαφί του κέντρου του ζυγαριου  
 γινεται με χρονο  $\frac{2\pi}{\omega \sin\lambda} = \frac{2\pi}{38h \frac{0.75}{\sin\lambda}}$

$$\etaμιθες \lambdaοβου = \frac{2\pi}{\omega \frac{T}{2} \sin\lambda}$$