

για να είναι $|\vec{a}|^2 = \epsilon \tau a^2 = a^2$.

$$a_1 = \frac{d^2 x}{dt^2} = \underline{\dot{x}_1} \text{ στα δεξιά}$$

$$\delta_1^3 a_1 = a = \epsilon \tau a$$

$$a^r = \begin{pmatrix} \delta_1^4 a_1 v_1 \\ \delta_1^4 a_1 \end{pmatrix}$$

για να είναι στα δεξιά.

πρέπει να προκύπτει

αν $v_1 = 0$ $a_1 = a$, αν $v_1 \neq 0$ $a_1 \neq a$

Οπιοδήποτε 4-ταχυτ.

$$v^\mu = \begin{pmatrix} \text{ch } \phi(\tau) \\ \text{sh } \phi(\tau) \hat{n}(\tau) \end{pmatrix}$$

$$|v|^\mu{}^\mu = -1$$

$$\phi(\tau) = \text{αρχή } \omega \tau$$

$$\tanh \phi(\tau) = v(\tau)$$

↑
ιδιοκρ.
βασισμ.

$$a^\mu = \begin{pmatrix} \dot{\phi} \text{sh } \phi(\tau) \\ \dot{\phi} \text{ch } \phi(\tau) + \text{sh } \phi(\tau) \dot{\hat{n}} \end{pmatrix}$$

$$\cdot = \frac{d}{d\tau}$$

$$|a|^\mu{}^\mu = a_0^2 = c^2 a^2 \quad \hat{n} = c \tau a \Rightarrow \phi(\tau) = \alpha \tau + \beta \Rightarrow x^\mu(\tau)$$

$$a^r = \begin{pmatrix} \gamma^4 \vec{v} \cdot \vec{a} \\ \gamma^4 (\vec{v} \cdot \vec{a}) \vec{v} + \gamma^2 \vec{a} \end{pmatrix}$$

$$\vec{v} = \frac{d\vec{x}}{dt}$$

$$v^r = \begin{pmatrix} \gamma \\ \gamma \vec{v} \end{pmatrix} \quad \frac{dv^r}{d\tau} = \dots \uparrow$$

$$a^r = \frac{dv^r}{dt}$$

ε' Γ ∪ $\vec{v} \parallel \vec{a} \parallel \hat{x} \quad |\vec{a}|^2 = a_0^2 = \epsilon \Gamma a \cup$

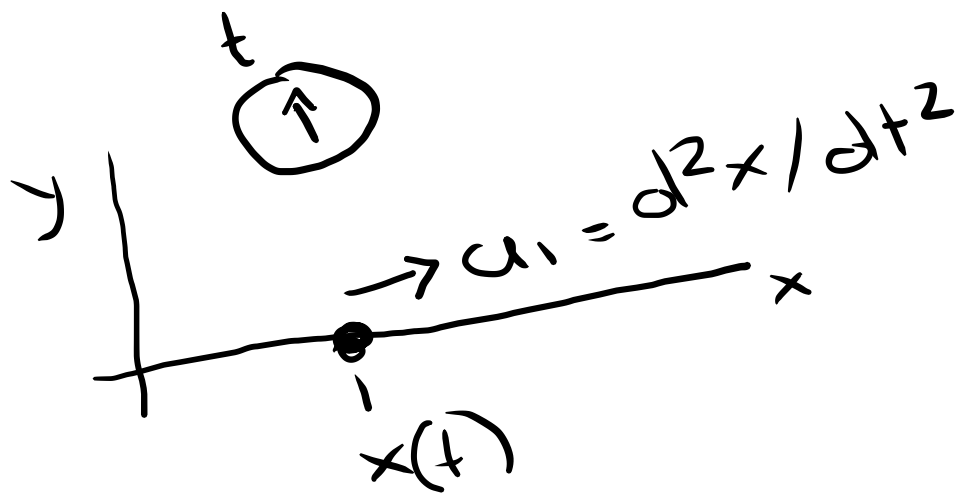
$$a^r = \begin{pmatrix} \gamma^4 v a \\ \gamma^4 a \hat{x} \end{pmatrix}$$

$$|\vec{a}|^2 = (\gamma^4 a)^2 (-v^2 + 1) = a_0^2$$

$$= \gamma^6 a^2 = \epsilon \Gamma a \cup = a_0 = \gamma^3 a$$

$x = \sqrt{t^2 + 1/a_0^2} - 1/a_0$ $\frac{d^2 x}{dt^2} = \epsilon \Gamma a \cup$

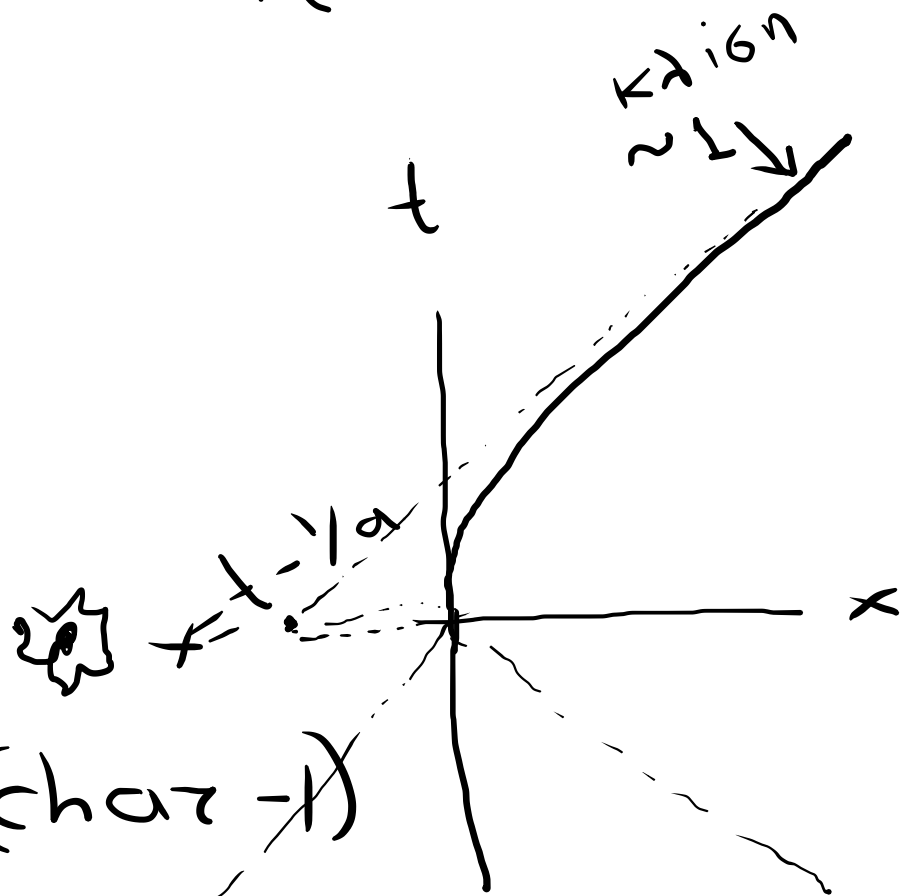
$\frac{dx}{dt} = v \rightarrow \gamma$



$$\partial_1^3 a_1 = a$$

$$a_1 = \frac{a}{\partial_1^3} \xrightarrow{\partial_1 \rightarrow \infty} 0$$

\uparrow
 $v \uparrow$



$$\frac{dx}{dt} \sim 1 \quad (\text{speed} + a \cdot t)$$

$$\frac{d}{dt} \left(\frac{dx}{dt} \right) \rightarrow 0$$

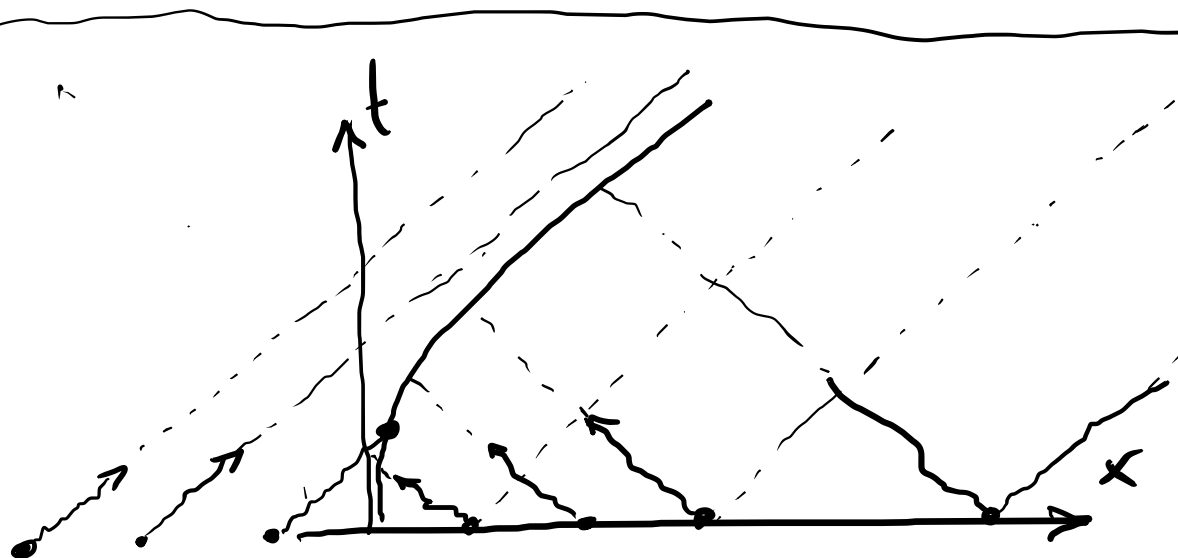
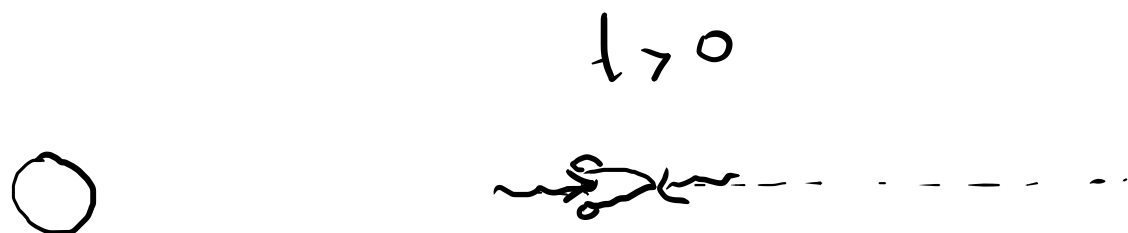
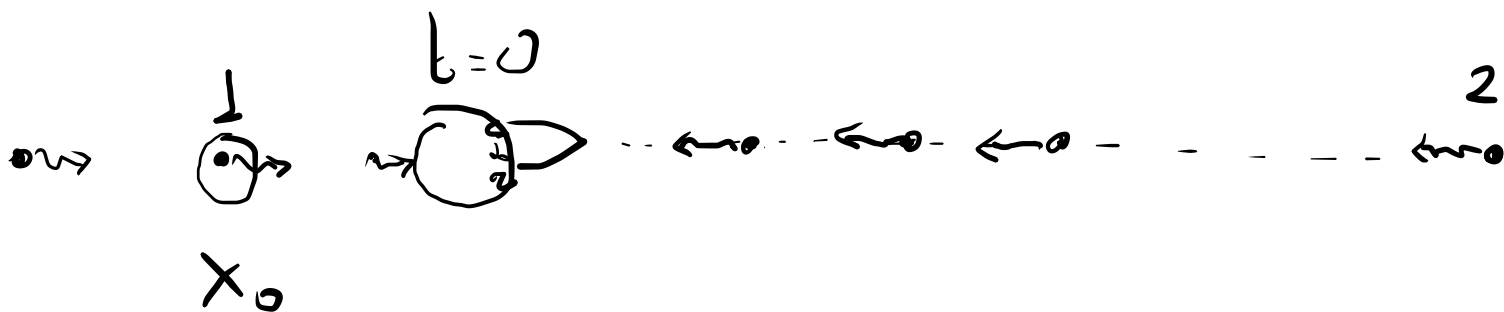
$$x = \frac{1}{a} (\text{ch} a t - t)$$

$$t = \frac{1}{a} \text{sh} a t$$

$$\text{ch} = \sqrt{\text{sh}^2 + 1}$$

$$x = \frac{1}{a} \left((t a)^2 + 1 \right)^{1/2} - 1 = \sqrt{t^2 + 1/a^2} - 1/a$$

$\begin{matrix} \sim \\ t \ll 1/a \end{matrix} \frac{1}{2} a t^2$
 $\begin{matrix} \sim \\ t \gg 1/a \end{matrix} t - 1/a$



$$x_0 < -\frac{1}{a}$$

το φ_{WS} με

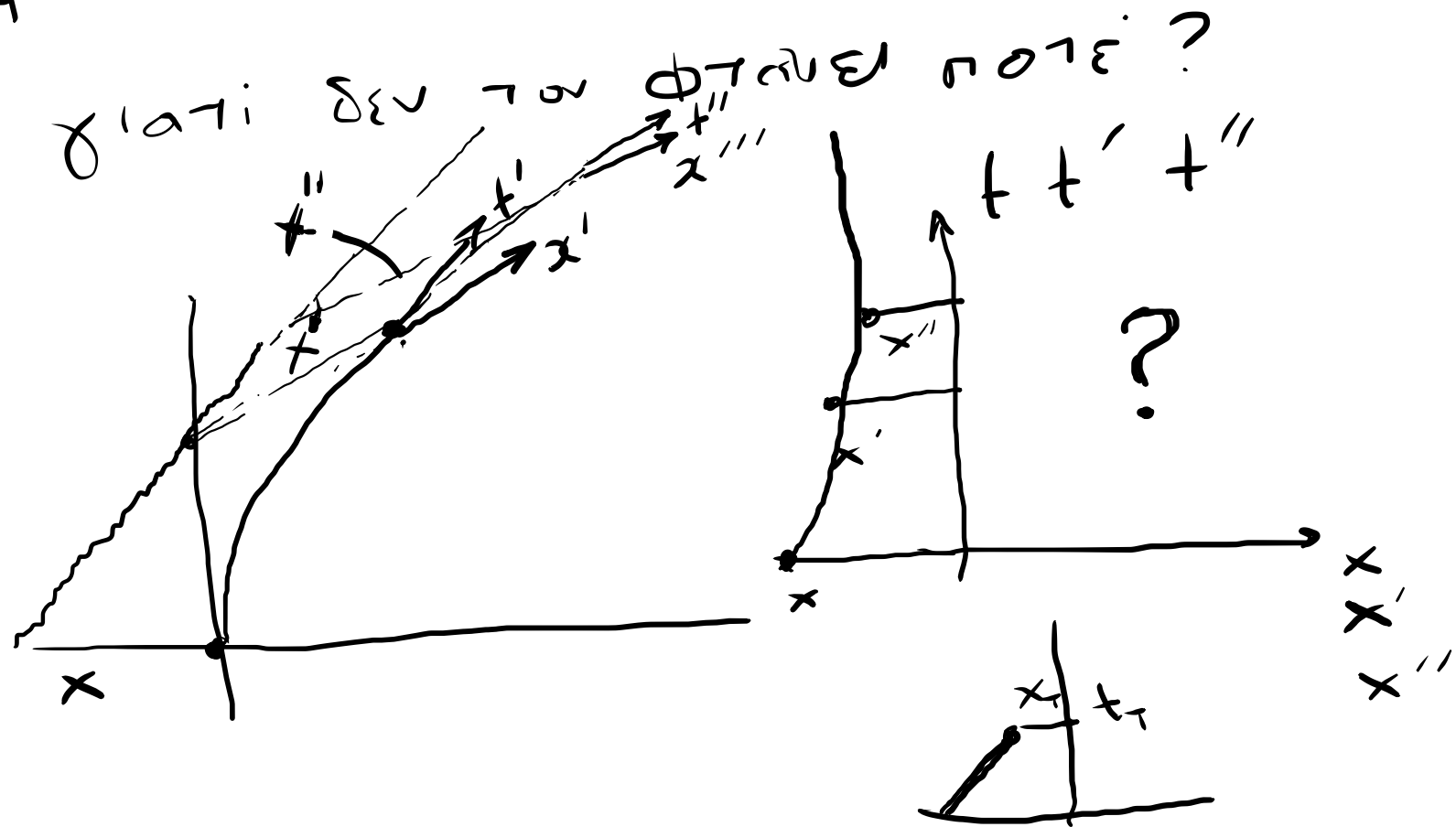
αρχή το $(0, x_0)$

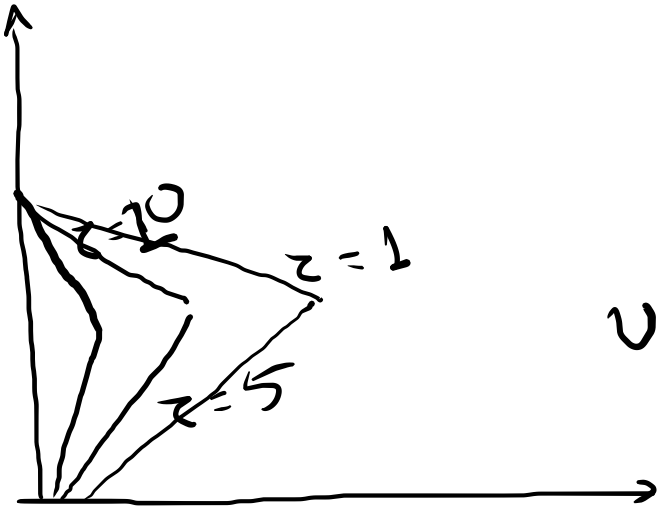
ΔΕΝ θα φτάσει

ποτέ τον αστρον.

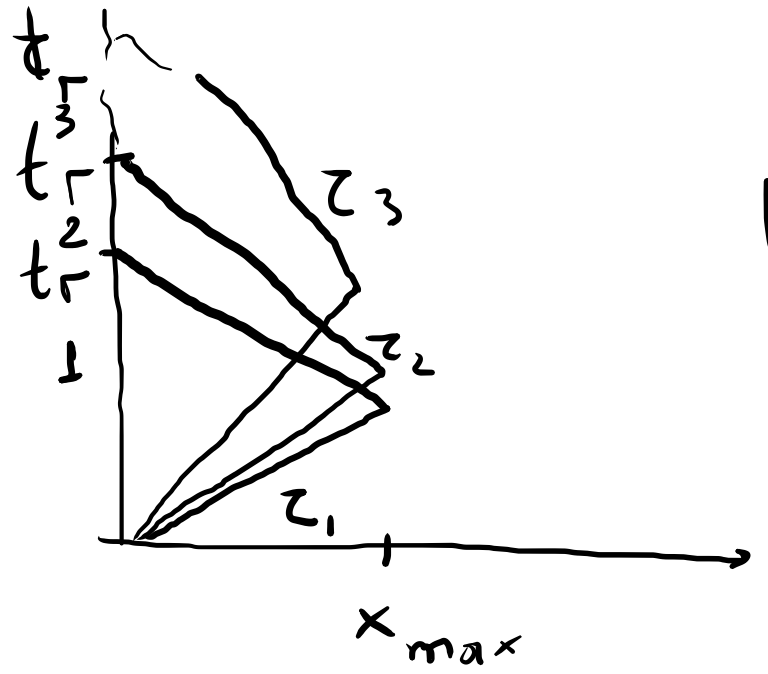
$$v_{a0}'''' = \frac{v_{a0} - 1}{1 - v_{a0}} = -1$$

αφού τον κηλίσια με σταθερή ταχ.τ.





$0 \leftarrow z \rightarrow 1 \rightarrow 0$



$t_1 < z < t_2 \rightarrow 0$
 \downarrow
 $2x_{max}$

$z < t_1$
 \downarrow
 $z \uparrow$

Μηκ 2

$$x \rightarrow x' = x + \varepsilon h(x, t)$$

$$t \rightarrow t' = t + \varepsilon \tau(x, t)$$

οποιοδήποτε
μετασφ.

$$L(x, v, t) \Rightarrow \int_{S'} L' dt = \int_S L dt + \varepsilon \int \frac{d}{dt} (p h + \tau (L - p v)) + \mathcal{O}(\varepsilon^2)$$

$$L' = L(x', v', t') = L(x, v, t) + \varepsilon \dots$$

$$L' \neq L \quad S' \neq S$$

$$S' - S = \mathcal{O}(\varepsilon^2)$$

$$\Rightarrow \varepsilon \int = 0$$

$$p h + \tau (L - p v) = 0$$

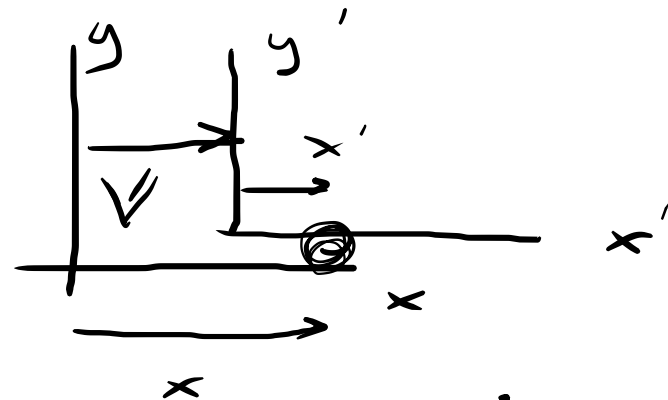
$$L = \frac{v^2}{2} - \frac{x^2}{2}$$

$$L' = \frac{v'^2}{2} - \frac{x'^2}{2}$$

$$L = \frac{1}{2} m \dot{x}^2$$

Για άλλον συστήμα: $x' = x - \int_{t=0}^t v(t) dt$

$v(t)$
 γινόμενο
 σωματιδίου



$$L(x, v, t) = L'(x', v', t') \quad \dot{x}' = \dot{x} - v(t)$$

σφιδψ.

$$L' = \frac{1}{2} m (\dot{x}' + v(t))^2$$

$$X \rightarrow X'$$



$$L = L'$$

αριθμ

από την σωστή.



$$\text{ιδίως } \in L$$

$$L \begin{array}{l} \xrightarrow{x \rightarrow x'} \\ \xrightarrow{t \rightarrow t'} \\ \xrightarrow{v \rightarrow v'} \end{array} L' \neq L$$

αν τύχα 0

ψευδώς. $L' - L \approx O(\epsilon^2)$



συμπέρασμα

↪ διατήρηση

$$L = \frac{1}{2} m \dot{x}^2$$

$$x \rightarrow x' = x + \varepsilon t$$

$$t \rightarrow t' = t$$

για
Gωαρτ.

διαφορ
νοση

$$L' = \frac{1}{2} m \left(\frac{dx'}{dt'} \right)^2$$

$$= \frac{1}{2} m (\dot{x} + \varepsilon)^2$$

$$= \frac{1}{2} m \dot{x}^2 + \dots$$

$$= \frac{1}{2} m \left[\frac{d}{dt} (x' - \varepsilon t) \right]^2$$

$$= \frac{1}{2} m \dot{x}'^2 - m \dot{x}' \varepsilon + \frac{m \varepsilon^2}{2}$$

$$L(x', v', t' = t)$$

για
ναυτηρ

$$L' = L$$

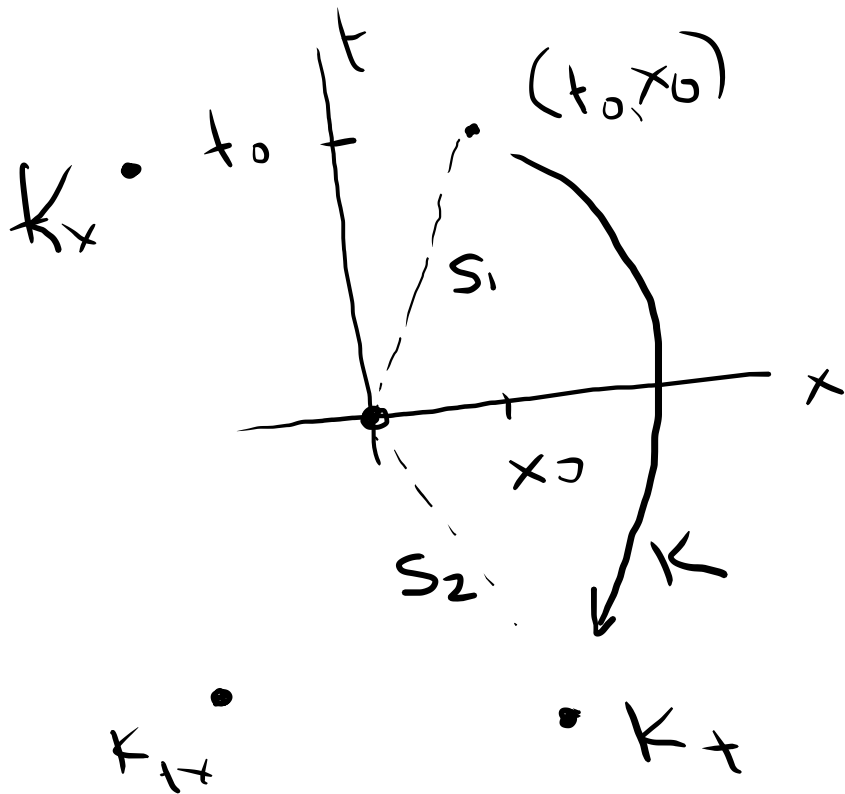
διαφορ

Gωαρτωση

$$\frac{1}{2} m \dot{x}^2 =$$

$$L(x, v, t)$$

$E \rightarrow \Sigma$



$$K_t = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$K_{x_0} = \begin{pmatrix} -t_0 \\ x_0 \end{pmatrix}$$

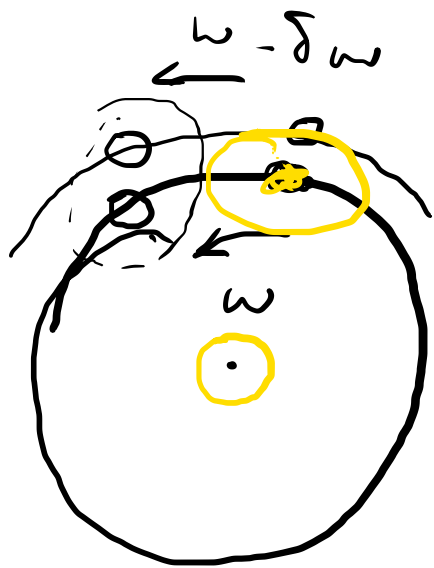
$$K_x = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$K_{xt} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$S_1^2 = -(t_0)^2 + x_0^2$$

$$S_2^2 = -(-t_0)^2 + x_0^2$$





$$\omega^2 r = \frac{GM}{r^2}$$

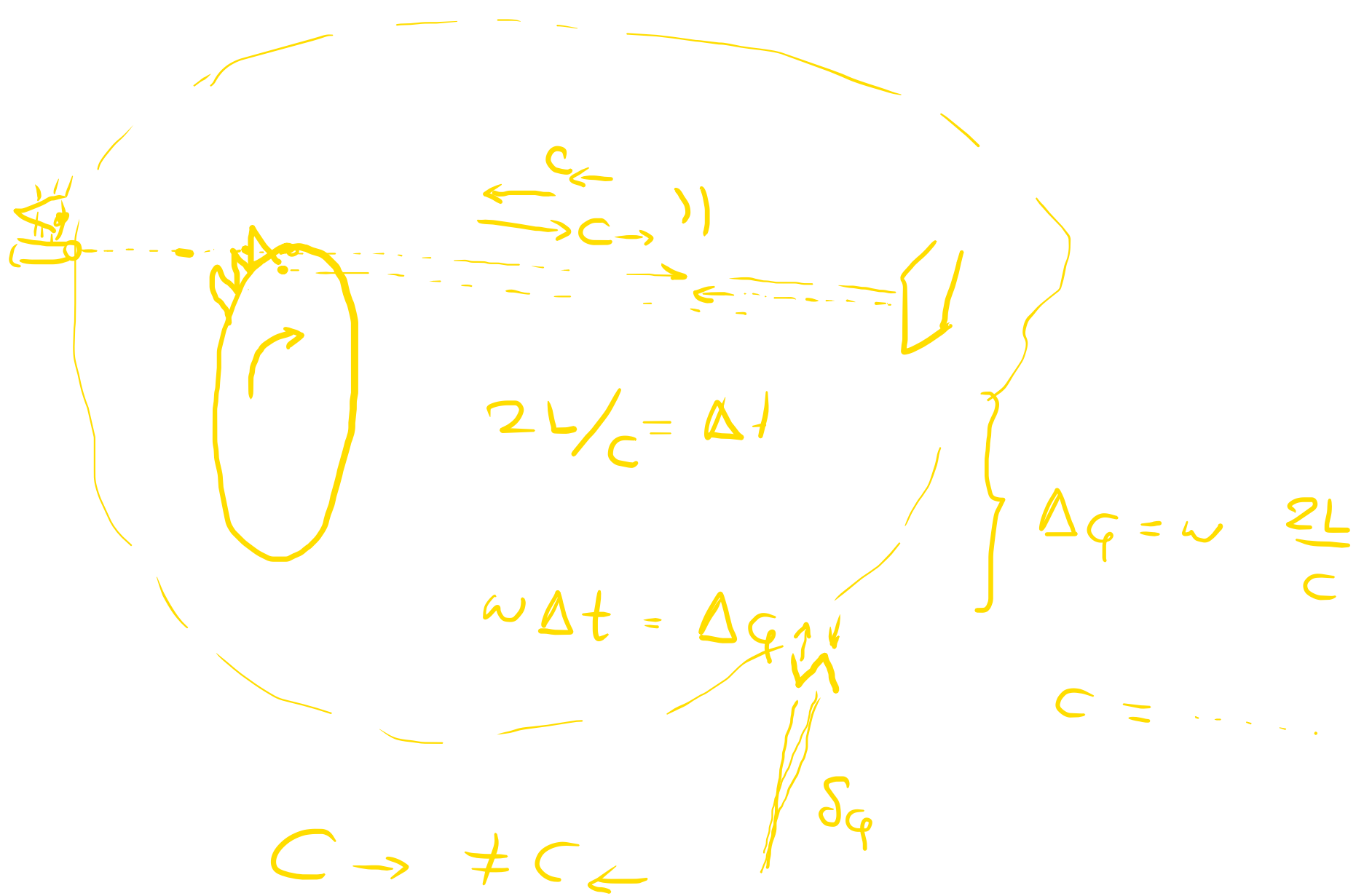
$$\omega^2 \sim 1/r^3$$

$$r + \delta r, \omega - \delta\omega$$

- για την Γη ο αστρον ΔΕΝ είναι αδραν

$\vec{v}_{αστρ.}$ αλλάζει

- για τον αστροναύτη και το "μικρό" περιβάλλον του είναι αδραν. γιατί οι δυνάμεις πεταγεί να κινείται ομαλά



$$c_{\rightarrow} \neq c_{\leftarrow}$$



$$\begin{array}{l}
 c_{\rightarrow} \rightarrow c_{\leftarrow} \\
 c_{\leftarrow} \rightarrow c_{\rightarrow}
 \end{array}$$

$$X^\mu = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad |X|^\mu = -1$$

$$X^\mu = \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad |X^\mu|^2 = 5$$

$$X^\mu(\tau) = \begin{pmatrix} \tau \\ 2\tau \\ 0 \\ 0 \end{pmatrix} \quad |X|^\mu = +3\tau^2$$

$$\gamma = 2/\sqrt{3}$$

$$v = \frac{2-1}{3-1} = \frac{1}{2}$$

$$v^\mu = \begin{pmatrix} \gamma \\ \gamma v \hat{x} \end{pmatrix}$$

$$\gamma = \gamma^0 = \frac{dt}{d\tau}$$



$$dt/d\tau = 2/\sqrt{3}$$

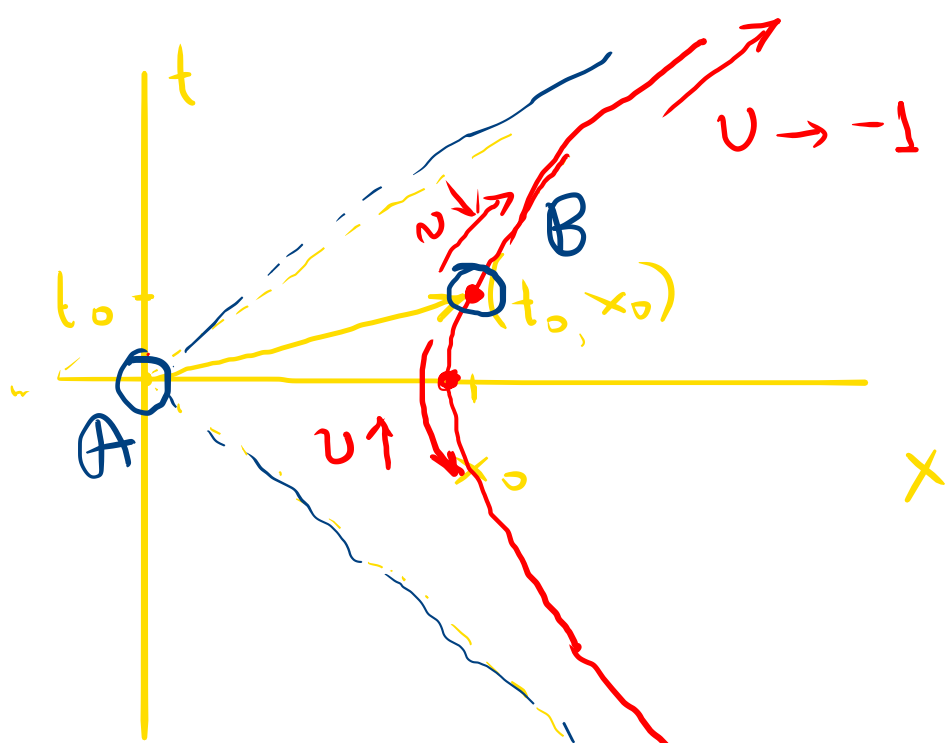
$$x=1 \quad x=3/2 \quad x=2$$

$$t=1 \quad t=2 \quad t=3$$

$$\text{Sim. exp.} \rightarrow \tau=0 \quad \tau=?$$

$$t=2 \quad \Delta t = 1 = 2-1$$

$$\Delta \tau = \frac{1}{2/\sqrt{3}}$$



$$x' = \gamma(x_0 - vt_0)$$

$$t' = \gamma(t_0 - vx_0)$$

$$|x_0| > |t_0|$$

$$x_0 > t_0$$

$$\underline{x'^2 - t'^2 = x_0^2 - t_0^2}$$

~~u_0 < 1~~ $v_0 = t_0/x_0 < 1 \quad \exists \text{ Taylor}$

$$t'(v_0) = 0$$

$$v \rightarrow 1 \quad \gamma \rightarrow +\infty$$

$$v \rightarrow -1 \quad \gamma \rightarrow +\infty$$

$$x' = \gamma(x_0 + t_0) \rightarrow +\infty$$

$$t' = \gamma(t_0 + x_0) \rightarrow +\infty$$

$$\left\{ \begin{array}{l} x' \Rightarrow \gamma(x_0 - t_0) \rightarrow +\infty \\ t' \rightarrow \gamma(t_0 - x_0) \rightarrow -\infty \end{array} \right.$$

Σ | $t_A = 0$ $x_A = 0$ (πυροβολισμός του X)

$t_B = 2$ $x_B = 4$ (θάνατος του X)

ΤΟ Α ΕΙΝΑΙ ΑΙΤΙΟ ΤΟΥ Β?

γιατί αν πάω σε ένα άλλο συστ. αναφοράς Σ_1
του τρέχει ως προς το Σ με $v_1 = 1/2$

και μετά πάλι σε άλλο Σ_2 που τρέχει με $v_2 = 2/3$

t_{A1}	x_{A1}	Σ_1	}	Σ_2	t_{A2}	x_{A2}
t_{B1}	x_{B1}			t_{B2}	x_{B2}	

$t_{A1} = t_{B1}$! οπότε ο πυροβ. \Rightarrow θάνατος

$t_{B2} < t_{A2}$
πρώτη η βολή \Rightarrow θάνατος πριν πυροβολήσει το Α

